Railway Interoperability – The Railways (Interoperability) Regulations 2011

Notice to all:
- Manufacturers and distributors of railway equipment
- Infrastructure managers and railway undertakings
- Railway infrastructure and train: builders, designers, operators, owners and managers
- Certifying authorities, approved bodies and notified bodies, recognised organisations and railway consultants

This Notice should be read with the Railways (Interoperability) Regulations 2011 and other relevant National Technical Specifications Notices (NTSNs). Unless otherwise defined, expressions used in this NTSN have the same meaning as in the Railways (Interoperability) Regulations 2011.

Summary
This Notice has been published by the Secretary of State for Transport pursuant to regulation 3B of the Railways (Interoperability) Regulations 2011 and comes into force on exit day.

The objective of the Railways (Interoperability) Regulations 2011 is to enhance the interoperability of the rail system through the uniform application of technical standards relating to railway equipment to be placed into service in the UK.

This Notice provides technical information on the features that are required to ensure infrastructure subsystems (e.g. stations, platforms, tracks) meet the essential requirements set out in Schedule 2 of the Railways (Interoperability) Regulations 2011.

This Notice replaces and substantially reproduces the provisions of Commission Regulation (EU) No 1299/2014 of 18 November 2014 on the technical specifications for interoperability relating to the ‘infrastructure’ subsystem of the rail system in the European Union (INF TSI), as it had effect immediately before exit day.

The technical requirements set out in this Notice are the same as those in the INF TSI except where indicated otherwise. The specific cases that were included in the INF TSI that are relevant to the UK have been retained as UK specific cases. The specific cases for EU Member States have not been included as they are not relevant to this Notice.
COMMISSION REGULATION (EU) No 1299/2014

of 18 November 2014

on the technical specifications for interoperability relating to the ‘infrastructure’ subsystem of the rail system in the European Union

(Text with EEA relevance)

THE EUROPEAN COMMISSION,

Having regard to the Treaty on the Functioning of the European Union,

Having regard to Directive 2008/57/EC of the European Parliament and of the Council of 17 June 2008 on the interoperability of the rail system within the Community (1), and in particular Article 6(1) thereof,

Whereas:

(1) Article 12 of Regulation (EC) No 881/2004 of the European Parliament and of the Council (2) requires the European Railway Agency (the Agency) to ensure that the technical specifications for interoperability (the TSIs) are adapted to technical progress, market trends and social requirements and to propose to the Commission the amendments to the TSIs which it considers necessary.

(2) By Decision C(2010) 2576 of 29 April 2010, the Commission gave the Agency a mandate to develop and review the TSIs with a view to extending their scope to the whole rail system in the Union. Under the terms of that mandate, the Agency was requested to extend the scope of the TSI relating to the subsystem ‘infrastructure’, to the whole rail system in the Union.

(3) On 21 December 2012, the Agency issued a recommendation on amendments to the TSI relating to the subsystem ‘infrastructure’ (ERA/REC/10-2012/INT).

(4) In order to keep pace with technological progress and encourage modernisation, innovative solutions should be promoted and their implementation should, under certain conditions, be allowed. Where an innovative solution is proposed, the manufacturer or his authorised representative should state how it deviates from or how it complements to the relevant section of the TSI, and the innovative solution should be assessed by the Commission. If this assessment is positive, the Agency should devise the appropriate functional and interface specifications of the innovative solution and develop the relevant assessment methods.

(5) The TSI infrastructure established by this Regulation does not deal with all essential requirements. In accordance with Article 5(6) of Directive 2008/57/EC, technical aspects which are not covered by it should be identified as ‘open points’ governed by national rules applicable in each Member State.

(6) In accordance with Article 17(3) of Directive 2008/57/EC, Member States are to notify to the Commission and other Member States the conformity assessment and verification procedures to be used for the specific cases as well as the bodies
responsible for carrying out these procedures. The same obligation should be provided as regards to open points.

(7) Rail traffic currently operates under existing national, bilateral, multinational or international agreements. It is important that these agreements do not hinder current and future progress towards interoperability. The Member States should therefore notify such agreements to the Commission.

(8) In accordance with Article 11(5) of Directive 2008/57/EC, the TSI on infrastructure should allow, for a limited period of time, for interoperability constituents to be incorporated into subsystems without certification if certain conditions are met.

(9) Commission Decisions 2008/217/EC (3) and 2011/275/EU (4) should therefore be repealed.

(10) In order to prevent unnecessary additional costs and administrative burden, Decisions 2008/217/EC and 2011/275/EU should continue to apply after their repeal to the subsystems and projects referred to in Article 9(1)(a) of Directive 2008/57/EC.

(11) The measures provided for in this Regulation are in conformity with the opinion of the Committee established in accordance with Article 29(1) of Directive 2008/57/EC.

HAS ADOPTED THIS REGULATION:

Infrastructure
National Technical Specification Notice

**Article 1**

**Subject matter**

This technical specification for interoperability (TSI) National Technical Specification Notice (NTSN) concerns relating to the ‘infrastructure’ subsystem of the rail system in the entire European Union, as set out in the Annex, is hereby adopted.

**Article 2**

**Scope**


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2. Without prejudice to Articles 7 and 8 and point 7.2 of the Annex, the TSI NTSN shall apply to new railway lines in the European Union, which are placed in service from 1 January 2015 to 31 October 2019.

3. The TSI NTSN shall not apply to existing infrastructure of the rail system in the European Union, which is already placed in service on all or part of the network of any Member State on 31 October 2019 to 1 January 2015, except when it is subject to renewal or upgrading in accordance with Article 28 of Directive 2016/797 and Regulations 12 and 13 of the Railways (Interoperability) Regulations 2011 and Section 7.3 of the Annex.

4. The TSI NTSN shall apply to the network of the Union rail system as described in Annex I of Directive (EU) 2016/797 and the Railways (Interoperability) Regulations 2011 with the exclusion of cases referred to in regulation 3(2) and 3(5) of the Railways (Interoperability) Regulations 2011; Article 1(3) and (4) of Directive (EU) 2016/797.

5. The TSI NTSN shall apply to networks with the following nominal track gauges: 1435 mm and, 1520 mm, 1524 mm, 1600 mm and 1668 mm.

6. Metric gauge is excluded from the technical scope of this TSI NTSN.

7. The technical and geographical scope of this Regulation NTSN is set out in Sections 1.1 and 1.2 of the Annex.

Article 3

Open points

1. With regard to the aspects listed as “open points” in Appendix R to the Annex to this Regulation NTSN, the conditions to be complied with for verifying the essential requirements set out in Annex III to Directive (EU) 2016/797 and Schedule 2 to the Railways (Interoperability) Regulations 2011 shall be those laid down by national technical rules in force in the Member State which authorises the placing in service of the subsystem covered by this Regulation.

2. Within six months of the entry into force of this Regulation, each Member State shall send to the other Member States and the Commission of the following information, unless such information has already been sent to them under Decisions 2008/217/EC or 2011/275/EU:

(a) the national rules referred to in paragraph 1;
(b) the conformity assessment and verification procedures to be carried out to apply the national rules referred to in paragraph 1;
(c) the bodies designated to carry out the conformity assessment and verification procedures with respect to the open points.

Article 4

UK Specific cases

1. With regard to UK specific cases listed in Section 7.7 of the Annex, the conditions to be met for the verification of the essential requirements set out in Annex III to Directive (EU) 2016/797 and Schedule 2 to the Railways (Interoperability) Regulations 2011 shall be
those laid down in Section 7.7 of the Annex or by national technical rules in force in the Member State which authorises the placing in service of the subsystem covered by this Regulation.

2. Within six months of the entry into force of this Regulation, each Member State shall notify to the other Member States and the Commission the following information:
   (a) the national rules referred to in paragraph 1;
   (b) the conformity assessment and verification procedures to be carried out to apply the national rules referred to in paragraph 1;
   (c) the bodies designated to carry out the conformity assessment and verification procedures for the national rules relating to the specific cases set out in point 7.7 of the Annex.

Article 5

This provision has been left intentionally blank.

Notification of bilateral agreements

1. Member States shall notify the Commission, not later than 1 July 2015, any existing national, bilateral, multilateral or international agreements between Member States and railway undertaking(s), infrastructure managers or non-member countries which are required by the very specific or local nature of the intended rail service or which deliver significant levels of local or regional interoperability.

2. That obligation does not apply to agreements which have already been notified under Decision 2008/217/EC.

3. Member States shall forthwith notify to the Commission of any future agreements or amendments to existing agreements.

Article 6

This provision has been left intentionally blank.

Projects at an advanced stage of development

In accordance with Article 9(3) of Directive 2008/57/EC, each Member State shall communicate to the Commission within one year of the entry into force of this Regulation the list of projects being implemented within its territory and are at an advanced stage of development.
Article 7

‘ECUK’ certificate of verification

1. A ‘n-ECUK’ certificate of verification for a subsystem that contains interoperability constituents which do not have an ‘EC or UK’ declaration of conformity or suitability for use, may be issued during a transitional period ending on 31 May 2021 provided that the requirements laid down in point 6.5 of the Annex are met.

2. The production, upgrade or renewal of the subsystem with use of the non-certified interoperability constituents shall be completed within the transitional period set out in paragraph 1, including its placing in service.

3. During the transitional period set out in paragraph 1:

   (a) the reasons for non-certification of any interoperability constituents shall be properly identified by the notified or approved body before granting the ‘ECUK’ certificate pursuant to Article 15 of Directive (EU) 2016/797 regulations 16 & 17 of and Schedule 4 to the Railways (Interoperability) Regulations 2011;


4. From 31 October 2019 to 1 January 2026, newly produced interoperability constituents shall be covered by the UKEC declaration of conformity or suitability for use, or, in the case of interoperability constituents which fall within regulation 23(2) of the Railways (Interoperability) Regulations 2011, by an EC declaration of conformity or suitability for use.

Article 8

Conformity assessment

1. The procedures for assessment of conformity, suitability for use and ‘ECUK’ verification set out in section 6 of the Annex shall be based on the modules established in Commission Decision 2010/713/EU(6) the NTSN concerning modules for the procedures for assessment of conformity or suitability for use and UK verification (“Modules NTSN”).

2. The UK type or design examination certificate of interoperability constituents shall be valid for a seven year period. During that period, new constituents of the same type are permitted to be placed into service without a new conformity assessment.

3. Subject to the reassessment requirements under the Railways (Interoperability) Regulations 2011, and the procedure set out in the NTSN concerning the further

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assessments of interoperability constituents which hold an EC declaration of conformity or suitability for use, EC certificates referred to in paragraph 2 which have been issued according to the requirements of INF TSI Decision 1299/2014/EU and INF TSI 2011/275/EU or Decision INF TSI 2008/217/EC remain valid, without a need for a new conformity assessment, until the expiry date originally established. In order to renew a certificate the design or type shall be re-assessed only against new or modified requirements set out in the Annex to this Regulation NTSN.

**Article 9**

**Implementation**

1. For the purpose of this NTSN, the implementation plan published in December 2017 continues to apply. Section 7 of the Annex sets out the steps to be followed for the implementation of a fully interoperable infrastructure subsystem. Without prejudice to Article 20 of Directive 2008/57/EC, Member States shall prepare a national implementation plan, describing their actions to comply with this TSI, in accordance with section 7 of the Annex. Member States shall send their national implementation plan to the other Member States and the Commission by 31 December 2015. Member States that have already sent their implementation plan do not have to send it again.

2. **Deleted.**

3. Member States shall send to the Commission a report on the implementation of Article 20 of Directive 2008/57/EC three years after 1 January 2015. This report shall be discussed in the Committee set up by Article 29 of Directive 2008/57/EC and, where appropriate, the TSI in the Annex shall be adapted.

**Article 10**

**Innovative solutions**

1. In order to keep pace with technological progress, innovative solutions may be required, which do not comply with the specifications set out in the Annex or for which the assessment methods set out in the Annex cannot be applied.

2. Innovative solutions may relate to the infrastructure subsystem, its parts and its interoperability constituents.

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3 **Commission Regulation (EU) No 1299/2014 of 18 November 2014 on the technical specifications for interoperability relating to the ‘infrastructure’ subsystem of the rail system in the European Union. This EU legislation is retained EU law under section 3 of the European Union (Withdrawal) Act 2018.**

4 **Commission Decision 2011/275/EU of 26 April 2011 concerning a technical specification for interoperability relating to the ‘infrastructure’ subsystem of the trans-European conventional rail system (OJ L 126, 14.5.2011), and 2008/217/EC: Commission Decision of 20 December 2007 concerning a technical specification for interoperability relating to the infrastructure sub-system of the trans-European high-speed rail system (OJ L 77, 19.3.2008) were repealed on 1 January 2015.**
3. If an innovative solution is proposed, the manufacturer or his authorised representative shall apply for an exemption in accordance with regulations 14 and 14A of the Railways (Interoperability) Regulations 2011, established within the Union shall declare how it deviates from or complements to the relevant provisions of this TSI and submit the deviations to the Commission for analysis. The Commission may request the opinion of the Agency on the proposed innovative solution.

4. The Commission—Competent Authority shall publish an opinion on the proposed innovative solution in accordance with regulation 14A of the Railways (Interoperability) Regulations 2011. If this opinion is positive, an exemption will be granted in accordance with regulations 14 and 14A of the Railways (Interoperability) Regulations 2011, the appropriate functional and interface specifications and the assessment method, which need to be included in the TSI in order to allow the use of this innovative solution, shall be developed and subsequently integrated in the TSI during the revision process pursuant to Article 5 of Directive (EU) 2016/797. If the opinion is negative, the innovative solution proposed cannot be used.

5. Pending the review of the TSI, the positive opinion delivered by the Commission shall be considered as an acceptable means of compliance with the essential requirements of Directive (EU) 2016/797 and may be used for the assessment of the subsystem.

**Article 11**

**Relevant Standards**

This NTSN, published by the Secretary of State on 31 October 2019 in accordance with regulation 3B of the Railways (Interoperability) Regulations 2011, replaces Regulation 1299/2014/EU as the relevant standard to be complied with in relation to the technical specifications for interoperability relating to the infrastructure subsystems of the rail system and substantially reproduces the provisions of that Regulation.

Decisions 2008/217/EC and 2011/275/EU were repealed with effect from 1 January 2015.

The technical requirements in Decisions 2008/217/EC and 2011/275/EU shall continue to apply to:

(a) subsystems authorised in accordance with those Decisions;

(b) projects for new, renewed or upgraded subsystems which, at the date of publication of this Regulation on 12 December 2014, were at an advanced stage of development or the subject of an on-going contract.

**Article 12**

This provision has been left intentionally blank.

**Entry into force**

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This Regulation shall enter into force on the twentieth day following that of its publication in the Official Journal of the European Union.

It shall apply from 1 January 2015. However, an authorisation for placing in service may be granted in accordance with the TSI as set out in the Annex to this Regulation before 1 January 2015.

This Regulation shall be binding in its entirety and directly applicable in all Member States.

Done at Brussels, 18 November 2014.

For the Commission

The President

Jean-Claude JUNCKER

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1.3. This provision has been left intentionally blank

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1. INTRODUCTION

1.1. Technical Scope

This NTSNTSI concerns the infrastructure subsystem and part of the maintenance subsystem of the Union rail system in accordance with Article 1 of Directive (EU) 2016/797.

The infrastructure and the maintenance subsystems are defined respectively in paragraphs 2.1 and 2.8 of Schedule 3 to the Railways (Interoperability) Regulations 2011 and points 2.1 and 2.8 of Annex II to Directive (EU) 2016/797.

The technical scope of this NTSNTSI is further defined in Article 2(1), 2(5) and 2(6) of this Regulation.

1.2. Geographical Scope

The geographical scope of this TSI is defined in Article 2(4) of this Regulation.

1.3. This provision has been left intentionally blank

Content of this TSI

(a) indicates its intended scope (section 2);
(b) lays down essential requirements for the infrastructure and part of the maintenance subsystems (section 3);
(c) establishes the functional and technical specifications to be met by the infrastructure and part of the maintenance subsystems and its interfaces vis-à-vis other subsystems (section 4);
(d) specifies the interoperability constituents and interfaces which must be covered by European specifications, including European standards, which are necessary to achieve interoperability within the Union rail system (section 5);
(e) states, in each case under consideration, which procedures are to be used in order to assess the conformity or the suitability for use of the interoperability constituents, on the one hand, or the EC verification of the subsystems, on the other hand (section 6);
(f) indicates the strategy for implementing this TSI (section 7);
(g) indicates, for the staff concerned, the professional qualifications and health and safety conditions at work required for the operation and maintenance of the infrastructure subsystem, as well as for the implementation of this TSI (section 4).
(h) indicates the provisions applicable to the existing infrastructure subsystem, in particular in the event of upgrading and renewal and, in such cases, the modification work which requires an application for a new authorisation.

(i) indicates the parameters of infrastructure subsystem to be checked by the railway undertaking and the procedures to be applied to check those parameters after the delivery of the vehicle authorisation for placing on the market and before the first use of the vehicle to ensure compatibility between vehicles and the routes on which they are to be operated.

In accordance with Article 4(5) of the Directive (EU) 2016/797, provisions for specific cases are indicated in section 7.

2. DEFINITION AND SCOPE OF SUBSYSTEM

2.1. Definition of the infrastructure subsystem

This **NTSNTSI** covers:

(a) the infrastructure structural subsystem

(b) the part of the maintenance functional subsystem relating to the infrastructure subsystem (that is: washing plants for external cleaning of trains, water restocking, refuelling, fixed installations for toilet discharge and electrical shore supplies).

The elements of the infrastructure subsystem are described in paragraph 2.1 of Schedule 3 to the Railways (Interoperability) Regulations 2011. Annex II to Directive (EU) 2016/797.

The elements of the maintenance subsystem are described in paragraph 2.8 of Schedule 3 to the Railways (Interoperability) Regulations 2011 Annex II to Directive (EU) 2016/797.

The scope of this **NTSNTSI** therefore includes the following aspects of the infrastructure subsystem:

(a) Line layout,

(b) Track parameters,

(c) Switches and crossings,

(d) Track resistance to applied loads,

(e) Structures resistance to traffic loads,

(f) Immediate action limits on track geometry defects,

(g) Platforms,
Further details are set out in point 4.2.2 of this NTSNTSI.

2.2. Interfaces of this TSINTSN with other TSINTSNs

Point 4.3 of this TSINTSN sets out the functional and technical specification of the interfaces with the following subsystems, as defined in the relevant TSINTSNs:

(a) Rolling stock subsystem,
(b) Energy subsystem,
(c) Control command and signalling subsystem,
(d) Traffic operation and management subsystem.

Interfaces with the Persons with Reduced Mobility TSINTSN (PRM TSINTSN) are described in point 2.3 below.

Interfaces with the Safety in Railway Tunnels TSINTSN (SRT TSINTSN) are described in point 2.4 below.

2.3. Interfaces of this TSINTSN with the Persons with Reduced Mobility TSINTSN

All requirements relating to the infrastructure subsystem for the access of persons with reduced mobility to the railway system are set out in the Persons with Reduced Mobility TSINTSN.

2.4. Interfaces of this TSINTSN with the Safety in Railway Tunnels TSINTSN

All requirements relating to the infrastructure subsystem for safety in railway tunnels are set out in the Safety in Railway Tunnels TSINTSN.

2.5. Relation to the safety management system

Necessary processes to manage safety according to the requirements in the scope of this TSINTSN, including interfaces to humans, organisations or other technical systems, shall be designed and implemented in the infrastructure manager’s safety management system as required by Directive 2016/798 on the Railways and Other Guided Transport Systems (Safety) Regulations 2006.
3. ESSENTIAL REQUIREMENTS

The following table indicates basic parameters of this TSI/NTSI and their correspondence to the essential requirements as set out and numbered in Schedule 2 to the Railways (Interoperability) Regulations 2011 Annex III to Directive (EU) 2016/797.

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<td>Use of swing nose crossings</td>
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4. DESCRIPTION OF THE INFRASTRUCTURE SUBSYSTEM

4.1. Introduction

(1) The Union rail system, to which Directive (EU) 2016/797 applies and of which the infrastructure and maintenance subsystems are parts, is an integrated system whose consistency needs to be verified. This consistency must be checked in particular with regard to the specifications of the infrastructure subsystem, its interfaces in relation to the other subsystems of the Union rail system in which it is integrated, as well as the operating and maintenance rules.

(2) The limiting values set out in this TSINTSN are not intended to be imposed as usual design values. However the design values must be within the limits set out in this TSINTSN.

(3) The functional and technical specifications of the infrastructure and part of the maintenance subsystems and their interfaces, as described in points 4.2 and 4.3, do not impose the use of specific technologies or technical solutions, except where this is strictly necessary for the safe and uninterrupted movement of trains which accomplish the required levels of performance for those lines for the interoperability of the Union rail system.

(4) Innovative solutions for interoperability which do not fulfil the requirements specified in this TSINTSN and/or which are not assessable as stated in this TSINTSN require new specifications and/or new assessment methods. In order to allow technological innovation, these specifications and assessment methods shall be developed by the process for obtaining an exemption for innovative solutions is described in Article 10.

(5) Where reference is made to EN standards, any variations called ‘national deviations’ in the EN do not apply, unless otherwise specified in this TSINTSN.

(6) Where line speeds are stated in [km/h] as a category or performance parameter in this TSINTSN, it shall be allowed to translate the speed to equivalent [mph] as in Appendix G, for Ireland and for the United Kingdom of Great Britain and Northern Ireland networks.

4.2. Functional and technical specifications of the infrastructure subsystem

4.2.1. TSINTSN Categories of Line

(1) This provision has been left intentionally blank. The elements of the Union’s rail network are set out in point 1 of Annex I to Directive (EU) 2016/797. In order to deliver interoperability cost-effectively, each element of the Union’s rail network shall be assigned a “TSI category of line”.

The Union rail system, to which Directive (EU) 2016/797 applies and of which the infrastructure and maintenance subsystems are parts, is an integrated system whose consistency needs to be verified. This consistency must be checked in particular with regard to the specifications of the infrastructure subsystem, its interfaces in relation to the other subsystems of the Union rail system in which it is integrated, as well as the operating and maintenance rules.

The limiting values set out in this TSINTSN are not intended to be imposed as usual design values. However the design values must be within the limits set out in this TSINTSN.

The functional and technical specifications of the infrastructure and part of the maintenance subsystems and their interfaces, as described in points 4.2 and 4.3, do not impose the use of specific technologies or technical solutions, except where this is strictly necessary for the safe and uninterrupted movement of trains which accomplish the required levels of performance for those lines for the interoperability of the Union rail system.

Innovative solutions for interoperability which do not fulfil the requirements specified in this TSINTSN and/or which are not assessable as stated in this TSINTSN require new specifications and/or new assessment methods. In order to allow technological innovation, these specifications and assessment methods shall be developed by the process for obtaining an exemption for innovative solutions is described in Article 10.

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Where reference is made to EN standards, any variations called ‘national deviations’ in the EN do not apply, unless otherwise specified in this TSINTSN.

Where line speeds are stated in [km/h] as a category or performance parameter in this TSINTSN, it shall be allowed to translate the speed to equivalent [mph] as in Appendix G, for Ireland and for the United Kingdom of Great Britain and Northern Ireland networks.
(2) The NTSNTSI category of line shall be a combination of traffic codes. For lines where only one type of traffic is carried (for example, a freight only line), a single code may be used to describe the performances; where mixed traffic runs the category will be described by one or more codes for passenger and freight. The combined traffic codes describe the envelope within which the desired mix of traffic can be accommodated.

(3) These NTSNTSI categories of line shall be used for the classification of existing lines to define a target system so that the relevant performance parameters will be met.

(4) For the purpose of TSINTSN categorisation, lines are classified generically based on the type of traffic (traffic code) characterised by the following performance parameters:
- gauge,
- axle load,
- line speed,
- train length
- usable length of platform.

The columns for ‘gauge’ and ‘axle load’ shall be treated as minimum requirements as they directly control the trains that may run. The columns for ‘line speed’, ‘usable length of platform’ and ‘train length’ are indicative of the range of values that are typically applied for different traffic types and they do not directly impose restrictions on the traffic that may run over the line.

(5) The performance parameters listed in Table 2 and Table 3 are not intended to be used to directly ascertain the compatibility between rolling stock and infrastructure.

(6) Information defining the relation between maximum axle load and maximum speed according to type of vehicle is given in Appendix E and Appendix F.

(7) The performance levels for types of traffic are set out in Table 2 and Table 3 here-under.

<table>
<thead>
<tr>
<th>Traffic code</th>
<th>Gauge</th>
<th>Axle load [t]</th>
<th>Line speed [km/h]</th>
<th>Usable length of platform [m]</th>
</tr>
</thead>
<tbody>
<tr>
<td>P1</td>
<td>GC</td>
<td>17 (Δ)</td>
<td>250-350</td>
<td>400</td>
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<tr>
<td>P2</td>
<td>GB</td>
<td>20 (Δ)</td>
<td>200-250</td>
<td>200-400</td>
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</table>

Table 2
Performance parameters for passenger traffic
<table>
<thead>
<tr>
<th>Traffic code</th>
<th>Gauge</th>
<th>Axle load [t]</th>
<th>Line speed [km/h]</th>
<th>Train length [m]</th>
</tr>
</thead>
<tbody>
<tr>
<td>F1</td>
<td>GC</td>
<td>22,5 (-)</td>
<td>100-120</td>
<td>740-1050</td>
</tr>
<tr>
<td>F2</td>
<td>GB</td>
<td>22,5 (-)</td>
<td>100-120</td>
<td>600-1050</td>
</tr>
<tr>
<td>F3</td>
<td>GA</td>
<td>20 (-)</td>
<td>80-120</td>
<td>500-1050</td>
</tr>
<tr>
<td>F4</td>
<td>G1</td>
<td>18 (-)</td>
<td>n.a.</td>
<td>n.a.</td>
</tr>
<tr>
<td>F1520</td>
<td>S</td>
<td>22,5 (-)</td>
<td>80-160</td>
<td>35-400</td>
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<tr>
<td>F1600</td>
<td>IRL1</td>
<td>22,5 (-)</td>
<td>80-160</td>
<td>75-240</td>
</tr>
</tbody>
</table>

(*) Axle load is based on design mass in working order for power heads and locomotives as defined in point 2.1 of EN 15663:2009+AC:2010 and design mass under normal payload for other vehicles in accordance with point 6.3 of EN15663:2009+AC:2010.

(**) Axle load is based on design mass in working order for power heads and locomotives as defined in point 2.1 of EN 15663:2009+AC:2010 and design mass under exceptional payload for other vehicles as defined in Appendix K to this **TSINTSN**.

For structures, axle load by itself is not sufficient to define the requirements for infrastructure. Requirements are specified for new structures in point 4.2.7.1.1 and for existing structures in point 4.2.7.4.

Passenger hubs, freight hubs and connecting lines are included in the above traffic codes, as appropriate.

This provision has been left intentionally blank in accordance with Article 4(7) of Directive (EU) 2016/797 which provides that TSIs shall not prevent the
Member States from deciding on the use of infrastructures for the movement of vehicles not covered by the TSIs, it is allowed to design new and upgraded lines able to accommodate:

- gauges larger,
- axle loads higher,
- speeds greater,
- usable length of platform greater,
- trains longer than those specified in Table 2 and Table 3.

(11) Without prejudice to Section 7.6 and point 4.2.7.1.2(3), when categorising a new line as P1, it shall be ensured that ‘Class I’ trains, according to the HS RST TSI (Commission Decision 2008/232/EC), for a speed greater than 250 km/h, can run on that line up to the maximum speed.

(12) It is permissible for specific locations on the line to be designed for any or all of the performance parameters line speed, usable length of platform and train length less than those set out in Table 2 and Table 3, where duly justified to meet geographical, urban or environmental constraints.

4.2.2. Basic parameters characterising the infrastructure subsystem

4.2.2.1. List of Basic Parameters

The Basic Parameters characterising the infrastructure subsystem, grouped according to the aspects listed in point 2.1, are:

A. Line layout:
   (a) Structure gauge (4.2.3.1),
   (b) Distance between track centres (4.2.3.2),
   (c) Maximum gradients (4.2.3.3),
   (d) Minimum radius of horizontal curve (4.2.3.4),
   (e) Minimum radius of vertical curve (4.2.3.5),

B. Track parameters:
   (a) Nominal track gauge (4.2.4.1),
   (b) Cant (4.2.4.2),
   (c) Cant deficiency (4.2.4.3),
   (d) Abrupt change of cant deficiency (4.2.4.4),
(e) Equivalent conicity (4.2.4.5),
(f) Railhead profile for plain line (4.2.4.6),
(g) Rail inclination (4.2.4.7),

C. Switches and crossings
(a) Design geometry of switches and crossings (4.2.5.1),
(b) Use of swing nose crossings (4.2.5.2),
(c) Maximum unguided length of fixed obtuse crossings (4.2.5.3),

D. Track resistance to applied loads
(a) Track resistance to vertical loads (4.2.6.1),
(b) Longitudinal track resistance (4.2.6.2),
(c) Lateral track resistance (4.2.6.3),

E. Structures resistance to traffic loads
(a) Resistance of new bridges to traffic loads (4.2.7.1),
(b) Equivalent vertical loading for new earthworks and earth pressure effects imposed on new structures (4.2.7.2),
(c) Resistance of new structures over or adjacent to tracks (4.2.7.3),
(d) Resistance of existing bridges and earthworks to traffic loads (4.2.7.4),

F. Immediate action limits on track geometry defects
(a) The immediate action limit for alignment (4.2.8.1),
(b) The immediate action limit for longitudinal level (4.2.8.2),
(c) The immediate action limit for track twist (4.2.8.3),
(d) The immediate action limit of track gauge as isolated defect (4.2.8.4),
(e) The immediate action limit for cant (4.2.8.5),
(f) The immediate action limits for switches and crossings (4.2.8.6),

G. Platforms
(a) Usable length of platforms (4.2.9.1),
(b) Platform height (4.2.9.2),
(c) Platform offset (4.2.9.3),
(d) Track layout alongside platforms (4.2.9.4),

H. Health, safety and environment
(a) Maximum pressure variation in tunnels (4.2.10.1),
(b) Effect of crosswinds (4.2.10.2),

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I. Provision for operation

(a) Location markers (4.2.11.1),
(b) Equivalent conicity in service (4.2.11.2)

J. Fixed installations for servicing trains

(a) General (4.2.12.1),
(b) Toilet discharge (4.2.12.2),
(c) Train external cleaning facilities (4.2.12.3),
(d) Water restocking (4.2.12.4),
(e) Refuelling (4.2.12.5),
(f) Electric shore supply (4.2.12.6),

K. Maintenance rules

(a) Maintenance plan (4.5.2).

4.2.2.2. Requirements for Basic Parameters

(1) These requirements are described in the following paragraphs, together with any particular conditions that may be allowed in each case for the basic parameters and interfaces concerned.

(2) The values of basic parameters specified are only valid up to a maximum line speed of 350 km/h.

(3) For Ireland and for the United Kingdom in respect of the Northern Ireland network the values of basic parameters specified are only valid up to a maximum line speed of 165 km/h.

(4) In case of multi-rail track, requirements of this are to be applied separately to each pair of rails designed to be operated as separate track.

(5) Requirements for lines representing specific cases are described under point 7.7.

(6) A short section of track with devices to allow transition between different nominal track gauges is allowed.

(7) Requirements are described for the subsystem under normal service conditions. Consequences, if any, of the execution of works, which may require temporary exceptions as far as the subsystem performance is concerned, are dealt with in point 4.4.

(8) The performance levels of trains can be enhanced by adopting specific systems, such as vehicle body tilting. Special conditions are allowed for running such trains, provided they do not entail restrictions for other trains not equipped with such systems.
4.2.3. **Line layout**

4.2.3.1. **Structure gauge**

(1) The upper part of the structure gauge shall be set on the basis of the gauges selected according to point 4.2.1. Those gauges are defined in Annex C and in Annex D, point D.4.8 of EN 15273-3:2013.

(2) The lower part of the structure gauge shall be GI2 as defined in Annex C of EN 15273-3:2013. Where tracks are equipped with rail brakes, structure gauge GI1 as defined in Annex C of EN 15273-3:2013 shall apply for the lower part of the gauge.

(3) Calculations of the structure gauge shall be done using the kinematic method in accordance with the requirements of sections 5, 7, 10 and the Annex C and Annex D, point D.4.8 of EN 15273-3:2013.

(4) This provision has been left intentionally blank. Instead of points (1) to (3), for the 1 520 mm track gauge system, all traffic codes selected according to point 4.2.1 are applied with the uniform structure gauge ‘S’ as defined in Appendix H to this TSI.

(5) Instead of points (1) to (3), for the 1 600 mm track gauge system, all traffic codes selected according to point 4.2.1 are applied with the uniform structure gauge IRL1 as defined in Appendix O to this TSI.

4.2.3.2. **Distance between track centres**

(1) The distance between track centres shall be set on the basis of the gauges selected according to point 4.2.1.

(2) The nominal horizontal distance between track centres for new lines shall be specified for the design and shall not be smaller than the values from the Table 4; it considers margins for aerodynamic effects.

*Table 4*

<table>
<thead>
<tr>
<th>Maximum allowed speed [km/h]</th>
<th>Minimum nominal horizontal distance between track centres [m]</th>
</tr>
</thead>
<tbody>
<tr>
<td>160 &lt; v ≤ 200</td>
<td>3,80</td>
</tr>
<tr>
<td>200 &lt; v ≤ 250</td>
<td>4,00</td>
</tr>
<tr>
<td>250 &lt; v ≤ 300</td>
<td>4,20</td>
</tr>
<tr>
<td>v &gt; 300</td>
<td>4,50</td>
</tr>
</tbody>
</table>

(3) The distance between track centres shall at least satisfy the requirements for the limit installation distance between track centres, defined according section 9 of EN 15273-3:2013.
(4) *This provision has been left intentionally blank* Instead of points (1) to (3), for the 1,520 mm track gauge system, the nominal horizontal distance between track centres shall be specified for the design and shall not be smaller than the values from the Table 5; it considers margins for aerodynamic effects.

**Table 5**

<table>
<thead>
<tr>
<th>Maximum allowed speed [km/h]</th>
<th>Minimum nominal horizontal distance between track centres [m]</th>
</tr>
</thead>
<tbody>
<tr>
<td>$v \leq 160$</td>
<td>4,10</td>
</tr>
<tr>
<td>$160 &lt; v \leq 200$</td>
<td>4,30</td>
</tr>
<tr>
<td>$200 &lt; v \leq 250$</td>
<td>4,50</td>
</tr>
<tr>
<td>$v &gt; 250$</td>
<td>4,70</td>
</tr>
</tbody>
</table>

(5) *This provision has been left intentionally blank* Instead of point (2), for the 1,668 mm track gauge system, the nominal horizontal distance between track centres for new lines shall be specified for the design and shall not be smaller than the values from the Table 6, it considers margins for aerodynamic effects.

**Table 6**

<table>
<thead>
<tr>
<th>Maximum allowed speed [km/h]</th>
<th>Minimum nominal horizontal distance between track centres [m]</th>
</tr>
</thead>
<tbody>
<tr>
<td>$160 &lt; v \leq 200$</td>
<td>3,92</td>
</tr>
<tr>
<td>$200 &lt; v &lt; 250$</td>
<td>4,00</td>
</tr>
<tr>
<td>$250 \leq v \leq 300$</td>
<td>4,30</td>
</tr>
<tr>
<td>$300 &lt; v \leq 350$</td>
<td>4,50</td>
</tr>
</tbody>
</table>

(6) Instead of points (1) to (3), for the 1,600 mm track gauge system, the distance between track centres shall be set on the basis of the gauges selected according to point 4.2.1. The nominal horizontal distance between track centres shall be specified for the design and shall not be less than 3,57 m for gauge IRL1; it considers margins for aerodynamic effects.

**4.2.3.3. Maximum gradients**
(1) Gradients of tracks through passenger platforms of new lines shall not be more than 2.5 mm/m, where vehicles are intended to be regularly attached or detached.

(2) Gradients of new stabling tracks intended for parking rolling stock shall not be more than 2.5 mm/m unless specific provision is made to prevent the rolling stock from running away.

(3) Gradients as steep as 35 mm/m are allowed for main tracks on new P1 lines dedicated to passenger traffic at the design phase provided the following 'envelope' requirements are observed:
   (a) the slope of the moving average profile over 10 km is less than or equal to 25 mm/m.
   (b) the maximum length of continuous 35 mm/m gradient does not exceed 6 km.

4.2.3.4. Minimum radius of horizontal curve

The minimum design radius of horizontal curve shall be selected with regard to the local design speed of the curve.

(1) The minimum horizontal design curve radius for new lines shall not be less than 150 m.

(2) Reverse curves (other those in marshalling yards where wagons are shunted individually) with radii in the range from 150 m up to 300 m for new lines shall be designed to prevent buffer locking. For straight intermediate track elements between the curves, Table 43 and Table 44 of Appendix I shall apply. For non-straight intermediate track elements, a detailed calculation shall be made in order to check the magnitude of the end throw differences.

(3) Instead of point (2), for the 1 520 mm track gauge system, reverse curves with radii in the range from 150 m up to 250 m shall be designed with a section of straight track of at least 15 m between the curves.

4.2.3.5. Minimum radius of vertical curve

(1) The radius of vertical curves (except for humps in marshalling yards) shall be at least 500 m on a crest or 900 m in a hollow.

(2) For humps in marshalling yards the radius of vertical curves shall be at least 250 m on a crest or 300 m in a hollow.

(3) Instead of point (1), for the 1 520 mm track gauge system the radius of vertical curves (except the marshalling yards) shall be at least 5 000 m both on a crest and in a hollow.

(4) Instead of point (2), for the 1 520 mm track gauge system and for humps in marshalling yards the radius of vertical curves shall be at least 350 m on a crest and 250 m in a hollow.

4.2.4. Track parameters
4.2.4.1. Nominal track gauge

(1) The UK track gauge shall be the European standard nominal track gauge shall be 1 435 mm.

(2) Instead of point (1), for the 1 520 mm track gauge system the nominal track gauge shall be 1 520 mm.

(3) Instead of point (1), for the 1 668 mm track gauge system, the nominal track gauge shall be 1 668 mm.

(4) Instead of point (1), for the 1 600 mm track gauge system the nominal track gauge shall be 1 600 mm.

4.2.4.2. Cant

(1) The design cant for lines shall be limited as defined in Table 7.

<table>
<thead>
<tr>
<th>Design cant [mm]</th>
<th>Freight and mixed traffic</th>
<th>Passenger traffic</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ballasted track</td>
<td>160</td>
<td>180</td>
</tr>
<tr>
<td>Non ballasted track</td>
<td>170</td>
<td>180</td>
</tr>
</tbody>
</table>

(2) The design cant on tracks adjacent to station platforms where trains are intended to stop in normal service shall not exceed 110 mm.

(3) New lines with mixed or freight traffic on curves with a radius less than 305 m and a cant transition steeper than 1 mm/m, the cant shall be restricted to the limit given by the following formula:

\[ D \leq \frac{(R - 50)}{1.5} \]

where D is the cant in mm and R is the radius in m.

(4) This provision has been left intentionally blank instead of points (1) to (3), for the 1 520 mm track gauge system the design cant shall not exceed 150 mm.

(5) This provision has been left intentionally blank instead of point (1), for the 1 668 mm track gauge system, the design cant shall not exceed 185 mm.

(6) This provision has been left intentionally blank instead of point (2), for the 1 668 mm track gauge system, the design cant on tracks adjacent to station platforms where trains are intended to stop in normal service shall not exceed 125 mm.

(7) This provision has been left intentionally blank instead of point (3), for the 1 668 mm track gauge system, for new lines with mixed or freight traffic on curves with a radius less than 250 m, the cant shall be restricted to the limit given by the following formula:

\[ D \leq 0.9 \times (R - 50) \]
where $D$ is the cant in mm and $R$ is the radius in m.

(8) Instead of point (1), for the 1 600 mm track gauge system the design cant shall not exceed 185 mm.

4.2.4.3. Cant deficiency

(1) The maximum values for cant deficiency are set out in Table 8.

<table>
<thead>
<tr>
<th>Design speed [km/h]</th>
<th>$v \leq 160$</th>
<th>$160 &lt; v \leq 300$</th>
<th>$v &gt; 300$</th>
</tr>
</thead>
<tbody>
<tr>
<td>For operation of rolling stock conforming to the Locomotives and Passenger TSI or NTSN that replaces and/or substantially reproduces it</td>
<td>153</td>
<td>100</td>
<td></td>
</tr>
<tr>
<td>For operation of rolling stock conforming to the Freight Wagons TSI or NTSN that replaces and/or substantially reproduces it</td>
<td>130</td>
<td>—</td>
<td>—</td>
</tr>
</tbody>
</table>

(2) It is permissible for trains specifically designed to travel with higher cant deficiency (for example multiple units with axle loads lower than set out in table 2; vehicles with special equipment for the negotiation of curves) to run with higher cant deficiency values, subject to a demonstration that this can be achieved safely.

(3) Instead of point (1), for all types of rolling stock of the 1 520 mm track gauge system the cant deficiency shall not exceed 115 mm. This is valid for speeds up to 200 km/h.

(4) Instead of point (1), for the 1 668 mm track gauge system, the maximum values for cant deficiency are set out in Table 9.

<table>
<thead>
<tr>
<th>Design speed [km/h]</th>
<th>$v \leq 160$</th>
<th>$160 &lt; v \leq 300$</th>
<th>$v &gt; 300$</th>
</tr>
</thead>
<tbody>
<tr>
<td>For operation of rolling stock conforming to the Locomotives and Passenger TSI</td>
<td>175</td>
<td>115</td>
<td></td>
</tr>
<tr>
<td>For operation of rolling stock conforming to the Freight Wagons TSI</td>
<td>150</td>
<td>—</td>
<td>—</td>
</tr>
</tbody>
</table>

4.2.4.4. Abrupt change of cant deficiency

(1) The maximum values of abrupt change of cant deficiency shall be:
(a) 130 mm for \( v \leq 60 \text{ km/h} \),
(b) 125 mm for \( 60 \text{ km/h} < v \leq 200 \text{ km/h} \),
(c) 85 mm for \( 200 \text{ km/h} < v \leq 230 \text{ km/h} \)
(d) 25 mm for \( v > 230 \text{ km/h} \).

(2) Where \( v \leq 40 \text{ km/h} \) and cant deficiency \( \leq 75 \text{ mm} \) both before and after an abrupt change of curvature, the value of abrupt change of cant deficiency may be raised to 150 mm.

(3) Instead of points (1) and (2), for the 1 520 mm track gauge system the maximum values of abrupt change of cant deficiency shall be:
   (a) 115 mm for \( v \leq 200 \text{ km/h} \),
   (b) 85 mm for \( 200 \text{ km/h} < v \leq 230 \text{ km/h} \),
   (c) 25 mm for \( v > 230 \text{ km/h} \).

(4) Instead of point (1), for the 1 668 mm track gauge system, the maximum design values of abrupt change of cant deficiency shall be:
   (a) 150 mm for \( V \leq 45 \text{ km/h} \)
   (b) 115 mm for \( 45 \text{ km/h} < V \leq 100 \text{ km/h} \),
   (c) \( \frac{399 - V}{2.6} \text{ [mm]} \) for \( 100 \text{ km/h} < V \leq 220 \text{ km/h} \),
   (d) 70 mm for \( 220 \text{ km/h} < V \leq 230 \text{ km/h} \).
    
   Abrupt change of cant deficiency is not allowed for speeds of more than 230 km/h.

4.2.4.5. Equivalent conicity

(1) The limiting values for equivalent conicity quoted in Table 10 shall be calculated for the amplitude \( (y) \) of the wheelset’s lateral displacement:

<table>
<thead>
<tr>
<th>Condition</th>
<th>Limiting Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>( (TG - SR) \geq 7\text{mm} )</td>
<td>( y = 3 \text{mm} )</td>
</tr>
<tr>
<td>( 5\text{mm} \leq (TG - SR) &lt; 7\text{mm} )</td>
<td>( y = \frac{(TG - SR) - 1}{2} )</td>
</tr>
<tr>
<td>( (TG - SR) &lt; 5\text{mm} )</td>
<td>( y = 2 \text{mm} )</td>
</tr>
</tbody>
</table>

where \( TG \) is the track gauge and \( SR \) is the distance between the flange contact faces of the wheelset.
(2) No assessment of equivalent conicity is required for switches and crossings.

(3) Design track gauge, rail head profile and rail inclination for plain line shall be selected to ensure that the equivalent conicity limits set out in Table 10 are not exceeded.

Table 10

Equivalent conicity design limit values

<table>
<thead>
<tr>
<th>Speed range [km/h]</th>
<th>Wheel profile</th>
</tr>
</thead>
<tbody>
<tr>
<td>v ≤ 60</td>
<td>Assessment not required</td>
</tr>
<tr>
<td>60 &lt; v ≤ 200</td>
<td>0.25</td>
</tr>
<tr>
<td>200 &lt; v ≤ 280</td>
<td>0.20</td>
</tr>
<tr>
<td>v &gt; 280</td>
<td>0.10</td>
</tr>
</tbody>
</table>

(4) The following wheelsets shall be modelled passing over the designed track conditions (simulated by calculation according to EN 15302:2008+A1:2010):


For SR1 and SR2 the following values apply:

(a) For the 1435 mm track gauge system SR1 = 1420 mm and SR2 = 1426 mm.
(b) This provision has been left intentionally blank for the 1524 mm track gauge system SR1 = 1505 mm and SR2 = 1511 mm.
(c) For the 1600 mm track gauge system SR1 = 1585 mm and SR2 = 1 591 mm.
(d) For the 1668 mm track gauge system SR1 = 1653 mm and SR2 = 1 659 mm.

(5) Instead of points (1) to (4), for the 1520 mm track gauge system, no assessment of equivalent conicity is required.

4.2.4.6. Railhead profile for plain line

(1) The railhead profile shall be selected from the range set out in Annex A of EN 13674-1:2011, Annex A of EN13674-4:2006+A1:2009 or shall be in accordance with as defined in point (2).

(2) The design of railhead profiles for plain line shall comprise:

(a) a lateral slope on the side of the railhead angled to between vertical and 1/16 with reference to the vertical axis of the railhead;
(b) the vertical distance between the top of this lateral slope and the top of the rail shall be less than 20 mm;
(c) a radius of at least 12 mm at the gauge corner;
(d) the horizontal distance between the crown of the rail and the tangent point shall be between 31 and 37.5 mm.

**Figure 1**

**Railhead profile**

1. Crown of rail
2. Tangent point
3. Lateral slope
4. Vertical axis of rail head
5. Gauge corner

(3) These requirements are not applicable to expansion devices.

**4.2.4.7. Rail inclination**

**4.2.4.7.1. Plain line**

(1) The rail shall be inclined towards the centre of the track.

(2) For tracks intended to be operated at speeds greater than 60 km/h, the rail inclination for a given route shall be selected from the range 1/20 to 1/40.

(3) For sections of not more than 100 m between switches and crossings without inclination where the running speed is no more than 200 km/h, the laying of rails without inclination is allowed.

**4.2.4.7.2. Requirements for switches and crossings**

(1) The rail shall be designed to be either vertical or inclined.
(2) If the rail is inclined, the designed inclination shall be selected from the range 1/20 to 1/40.

(3) The inclination can be given by the shape of the active part of the rail head profile.

(4) Within switches and crossings where the running speed is more than 200 km/h and no more than 250 km/h, the laying of rails without inclination is allowed provided that it is limited to sections not exceeding 50 m.

(5) For speeds of more than 250 km/h the rails shall be inclined.

4.2.5. **Switches and crossings**

4.2.5.1. **Design geometry of switches and crossings**

Point 4.2.8.6 of this TSINTSN defines immediate action limits for switches and crossings that are compatible with geometrical characteristics of wheelsets as defined in the rolling stock TSINTSNs. It will be the task of the infrastructure manager to decide geometrical design values appropriate to its maintenance plan.

4.2.5.2. **Use of swing nose crossing**

For speeds higher than 250 km/h switches and crossings shall be equipped with swing-nose crossings.

4.2.5.3. **Maximum unguided length of fixed obtuse crossings**

The design value of the maximum unguided length of fixed obtuse crossings shall be in accordance with the requirements set out in Appendix J to this TSINTSN.

4.2.6. **Track resistance to applied loads**

4.2.6.1. **Track resistance to vertical loads**

The track design, including switches and crossings, shall take into account at least the following forces:

(a) the axle load selected according to point 4.2.1;

(b) maximum vertical wheel forces. Maximum wheel forces for defined test conditions are defined in EN 14363:2005 point 5.3.2.3.

(c) vertical quasi-static wheel forces. Maximum quasi-static wheel forces for defined test conditions are defined in EN 14363:2005 points 5.3.2.3.

4.2.6.2. **Longitudinal track resistance**

4.2.6.2.1. **Design forces**

The track, including switches and crossings, shall be designed to withstand longitudinal forces equivalent to the force arising from braking of 2,5 m/s² for the performance parameters chosen in accordance with point 4.2.1.
4.2.6.2.2. Compatibility with braking systems

(1) The track, including switches and crossings, shall be designed to be compatible with the use of magnetic braking systems for emergency braking.

(2) Provisions for the use of eddy current braking systems on track shall be defined at operational level by the infrastructure manager on the basis of the specific characteristics of the track, including switches and crossings. The conditions of use of this braking system are registered in accordance with Commission Implementing Regulation (EU) 2019/7775 (RINF).

(3) For the 1 600 mm track gauge system it shall be allowed not to apply point (1).

4.2.6.3. Lateral track resistance

The track design, including switches and crossings, shall take into account at least the following forces:

(a) lateral forces; Maximum lateral forces exerted by a wheel set on the track for defined test conditions are defined in EN 14363:2005 point 5.3.2.2.

(b) quasi-static guiding forces; Maximum quasi-static guiding forces $Y_{qst}$ for defined radii and test conditions are defined in EN 14363:2005 point 5.3.2.3.

4.2.7. Structures resistance to traffic loads

The requirements of EN 1991-2:2003/AC:2010 and Annex A2 to EN 1990:2002 issued as EN 1990:2002/A1:2005 specified in this section of the TSINTSN are to be applied in accordance with the corresponding points in the national annexes to these standards if they exist.

4.2.7.1. Resistance of new bridges to traffic loads

4.2.7.1.1. Vertical loads

(1) Structures shall be designed to support vertical loads in accordance with the following load models, defined in EN 1991-2:2003/AC:2010:

(a) Load Model 71, as set out in EN 1991-2:2003/AC:2010 point 6.3.2 (2)P

(b) In addition, for continuous bridges, Load Model SW/0, as set out in EN 1991-2:2003/AC:2010 point 6.3.3 (3)P

(2) The load models shall be multiplied by the factor alpha (a) as set out in EN 1991-2:2003/AC:2010 points 6.3.2 (3)P and 6.3.3 (5)P.

(3) The value of factor alpha (a) shall be equal to or greater than the values set out in Table 11.

Table 11
Factor alpha (α) for the design of new structures

<table>
<thead>
<tr>
<th>Type of traffic</th>
<th>Minimum factor alpha (α)</th>
</tr>
</thead>
<tbody>
<tr>
<td>P1, P2, P3, P4</td>
<td>1.0</td>
</tr>
<tr>
<td>P5</td>
<td>0.91</td>
</tr>
<tr>
<td>P6</td>
<td>0.83</td>
</tr>
<tr>
<td>P1520</td>
<td>1</td>
</tr>
<tr>
<td>P1600</td>
<td>1.1</td>
</tr>
<tr>
<td>F1, F2, F3</td>
<td>1.0</td>
</tr>
<tr>
<td>F4</td>
<td>0.91</td>
</tr>
<tr>
<td>F1520</td>
<td>1.46</td>
</tr>
<tr>
<td>F1600</td>
<td>1.1’</td>
</tr>
</tbody>
</table>

4.2.7.1.2. Allowance for dynamic effects of vertical loads

(1) The load effects from the Load Model 71 and Load Model SW/0 shall be enhanced by the dynamic factor phi (Φ) as set out in EN 1991-2:2003/AC:2010 points 6.4.3 (1)P and 6.4.5.2 (2).

(2) For bridges for speeds over 200 km/h where EN 1991-2:2003/AC:2010 paragraph 6.4.4 requires a dynamic analysis to be carried out the structure shall additionally be designed for HSLM defined in EN 1991-2:2003/AC:2010 paragraphs 6.4.6.1.1 (3) to (6) inclusive.

(3) It is permissible to design new bridges such that they will also accommodate an individual passenger train with higher axle loads than covered by HSLM. The dynamic analysis shall be undertaken using the characteristic value of the loading from the individual train taken as the design mass under normal payload in accordance with Appendix K with an allowance for passengers in standing areas in accordance with Note 1 of Appendix K.

4.2.7.1.3. Centrifugal forces

Where the track on a bridge is curved over the whole or part of the length of the bridge, the centrifugal force shall be taken into account in the design of structures as set out in EN 1991-2:2003/AC:2010 paragraphs 6.5.1 (2), (4)P and (7).

4.2.7.1.4. Nosing forces

The nosing force shall be taken into account in the design of structures as set out in EN 1991-2:2003/AC:2010 point 6.5.2.
4.2.7.1.5. Actions due to traction and braking (longitudinal loads)

Traction and braking forces shall be taken into account in the design of structures as set out in EN 1991-2:2003/AC:2010 paragraphs 6.5.3 (2)P, (4), (5), (6) and (7)P.

4.2.7.1.6. Design track twist due to rail traffic actions

The maximum total design track twist due to rail traffic actions shall not exceed the values set out in paragraph A2.4.4.2.2(3)P in Annex A2 to EN 1990:2002 issued as EN 1990:2002/A1:2005.

4.2.7.2. Equivalent vertical loading for new earthworks and earth pressure effects

(1) Earthworks shall be designed and earth pressure effects shall be specified taking into account the vertical loads produced by the Load Model 71, as set out in EN 1991-2:2003/AC:2010 paragraph 6.3.2(2).

(2) The equivalent vertical loading shall be multiplied by the factor alpha (a) as set out in EN 1991-2:2003/AC:2010 paragraph 6.3.2 (3)P. The value of a shall be equal to or greater than the values set out in Table 11.

4.2.7.3. Resistance of new structures over or adjacent to tracks


4.2.7.4. Resistance of existing bridges and earthworks to traffic loads

(1) Bridges and earthworks shall be brought to a specified level of interoperability according to the TSINTSN category of line as defined in point 4.2.1.

(2) The minimum capability requirements for structures for each traffic code are given in Appendix E. The values represent the minimum target level that structures must be capable of for the line to be declared interoperable.

(3) The following cases are relevant:

(a) Where an existing structure is replaced by a new structure then the new structure shall be in accordance with the requirements of point 4.2.7.1 or point 4.2.7.2.

(b) If the minimum capability of the existing structures expressed by the published EN line category in combination with the allowed speed satisfies the requirements in Appendix E then the existing structures satisfy the relevant interoperability requirements.

(c) Where the capability of an existing structure does not satisfy the requirements in Appendix E and works (e.g. strengthening) are being carried out to raise the capability of the structure to meet the requirements of this TSINTSN (and the structure is not to be replaced by a new structure) then the
structure shall be brought into conformity with the requirements in Appendix E.

(4) For the United Kingdom of Great Britain and Northern Ireland networks, in paragraphs (2) and (3) above the EN line category may be replaced by Route Availability (RA) number (delivered in accordance with the national technical rule notified for this purpose) and consequently reference to Appendix E are replaced by reference to Appendix F.

4.2.8. **Immediate action limits on track geometry defects**

4.2.8.1. **The immediate action limit for alignment**

(1) The immediate action limits for isolated defects in alignment are set out in point 8.5 of EN 13848-5:2008+A1:2010. Isolated defects shall not exceed the limits of wavelength range D1 as set out in Table 6 of the EN Standard.

(2) The immediate action limits for isolated defects in alignment for speeds of more than 300 km/h are an open point.

4.2.8.2. **The immediate action limit for longitudinal level**

(1) The immediate action limits for isolated defects in longitudinal level are set out in point 8.3 of EN 13848-5:2008+A1:2010. Isolated defects shall not exceed the limits of wavelength range D1 as set out in Table 5 of the EN Standard.

(2) The immediate action limits for isolated defects in longitudinal level for speeds of more than 300 km/h are an open point.

4.2.8.3. **The immediate action limit for track twist**

(1) The immediate action limit for track twist as an isolated defect is given as a zero to peak value. Track twist is defined in EN 13848-1:2003+A1:2008 point 4.6.

(2) The track twist limit is a function of the measurement base applied according to EN 13848-5:2008+A1:2010 point 8.6.

(3) The infrastructure manager shall set out in the maintenance plan the base-length on which it will measure the track in order to check compliance with this requirement. The base-length of measurement shall include at least one base between 2 and 5 m.

(4) Instead of points (1) and (2), for the 1520 mm track gauge system the track twist, for a base length of 10 m, shall be not more than:

(a) 16 mm for passenger lines with \( v > 120 \) km/h or freight lines with \( v > 80 \) km/h

(b) 20 mm for passenger lines with \( v \leq 120 \) km/h or freight lines with \( v \leq 80 \) km/h

(5) Instead of point (3), for the 1520 mm track gauge system the Infrastructure Manager shall set out in the maintenance plan the base-length on which it will
measure the track in order to check compliance with this requirement. The base-
length of measurement shall include at least one base of 10 m.

(6) Instead of point (2), for the 1 668 mm track gauge system, the track twist limit is
a function of the measurement base applied according to one of the following
equations depending on the cant:

(a) Twist limit = \((20/l + 3)\) for \(u \leq 0.67 \times (r – 100)\) with a maximum value of:
  - 7 mm/m for speeds \(v \leq 200\) km/h
  - 5 mm/m for speeds \(v > 200\) km/h

(b) Twist limit = \((20/l + 1,5)\) for \(0.67 \times (r – 100) < u < 0.9 \times (r – 50)\) with a
  maximum value of:
  - 6 mm/m for \(l \leq 5\) m
  - 3 mm/m for \(l > 13\) m

\(u = \) cant (mm), \(l = \) twist base length (m), \(r = \) horizontal curve radius (m)

4.2.8.4. The immediate action limit of track gauge as an isolated defect

(1) The immediate action limits of track gauge as an isolated defect are set out in
Table 12.

<table>
<thead>
<tr>
<th>Speed [km/h]</th>
<th>Dimensions [mm]</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Minimum track gauge</td>
</tr>
<tr>
<td>(v \leq 120)</td>
<td>1 426</td>
</tr>
<tr>
<td>(120 &lt; v \leq 160)</td>
<td>1 427</td>
</tr>
<tr>
<td>(160 &lt; v \leq 230)</td>
<td>1 428</td>
</tr>
<tr>
<td>(v &gt; 230)</td>
<td>1 430</td>
</tr>
</tbody>
</table>

(2) This provision has been left intentionally blank

Instead of point (1), for the 1 520 mm track gauge system, the immediate action limits of track gauge as an isolated defect are set out in Table 13.

<table>
<thead>
<tr>
<th>Speed [km/h]</th>
<th>Dimensions [mm]</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Minimum track gauge</td>
</tr>
<tr>
<td>(v \leq 140)</td>
<td>1 512</td>
</tr>
<tr>
<td>(v &gt; 140)</td>
<td>1 512</td>
</tr>
</tbody>
</table>
(3) Instead of point (1), for the 1 600 track gauge system the immediate action limits of track gauge as an isolated defect are:
   (a) minimum track gauge: 1 591 mm
   (b) maximum track gauge: 1 635 mm.

4.2.8.5. The immediate action limit for cant

(1) The maximum cant allowed in service is 180 mm.
(2) The maximum cant allowed in service is 190 mm for dedicated passenger traffic lines.
(3) **This provision has been left intentionally blank** Instead of points (1) and (2), for the 1 520 mm track gauge system, the maximum cant allowed in service is 150 mm.
(4) Instead of points (1) and (2), for the 1 600 mm track gauge system, the maximum cant allowed in service is 185 mm.
(5) Instead of points (1) and (2), for the 1 668 mm track gauge system, the maximum cant allowed in service is 200 mm.

4.2.8.6. The immediate action limits for switches and crossings

*Figure 2*

Point retraction in fixed common crossings

(1) The technical characteristics of switches and crossings shall comply with the following in-service values:
   (a) Maximum value of free wheel passage in switches: 1 380 mm.
       This value can be increased if the infrastructure manager demonstrates that the actuation and locking system of the switch is able to resist the lateral impact forces of a wheelset.
   (b) Minimum value of fixed nose protection for common crossings: 1 392 mm.
This value is measured 14 mm below the running surface, and on the theoretical reference line, at an appropriate distance back from the actual point (RP) of the nose as indicated in Figure 2.

For crossings with point retraction, this value can be reduced. In this case the infrastructure manager shall demonstrate that the point retraction is sufficient to guarantee that the wheel will not hit the nose at the actual point (RP).

(c) Maximum value of free wheel passage at crossing nose: 1 356 mm.
(d) Maximum value of free wheel passage at check rail/wing rail entry: 1 380 mm.
(e) Minimum flangeway width: 38 mm.
(f) Minimum flangeway depth: 40 mm.
(g) Maximum height of check rail: 70 mm.

(2) All relevant requirements for switches and crossings are also applicable to other technical solutions using switch rails, for example side modifiers used in multi-rail track.

(3) This provision has been left intentionally blank Instead of point (1), for the 1 520 mm track gauge system the technical characteristics of switches and crossings shall comply with the following in-service values:
(a) Minimum value of bypass at the narrowest location between open switch rail and stock rail is 65 mm.
(b) Minimum value of fixed nose protection for common crossings is 1 472 mm.
(c) This value is measured 13 mm below the running surface, and on the theoretical reference line, at an appropriate distance back from the actual point (RP) of the nose as indicated in Figure 2. For crossings with point retraction, this value can be reduced. In this case the Infrastructure Manager shall demonstrate that the point retraction is sufficient to guarantee that the wheel will not hit the nose at the actual point (RP).
(d) Maximum value of free wheel passage at crossing nose is 1 435 mm.
(e) Minimum flangeway width is 42 mm.
(f) Minimum flangeway depth is 40 mm.
(g) Maximum height of check rail is 50 mm.

(4) Instead of point (1), for the 1 600 mm track gauge system the technical characteristics of switches and crossings shall comply with the following in-service values:
(a) Maximum value of free wheel passage in switches: 1 546 mm.

This value can be increased if the infrastructure manager demonstrates that the actuation and locking system of the switch is able to resist the lateral impact forces of a wheelset.
(b) Minimum value of fixed nose protection for common crossings: 1 556 mm.

This value is measured 14 mm below the running surface, and on the theoretical reference line, at an appropriate distance back from the actual point (RP) of the nose as indicated in Figure 2.

For crossings with point retraction, this value can be reduced. In this case the infrastructure manager shall demonstrate that the point retraction is sufficient to guarantee that the wheel will not hit the nose at the actual point (RP).

(c) Maximum value of free wheel passage at crossing nose: 1 520 mm.

(d) Maximum value of free wheel passage at check rail/wing rail entry: 1 546 mm.

(e) Minimum flangeway width: 38 mm.

(f) Minimum flangeway depth: 40 mm.

(g) Maximum height of check rail above head of running rail: 25 mm.

4.2.9. Platforms

(1) The requirements of this point are only applicable to passenger platforms where trains are intended to stop in normal service.

(2) For the requirements of this point it is permissible to design platforms required for the current service requirement provided provision is made for the reasonably foreseeable future service requirements. When specifying the interfaces with trains intended to stop at the platform, consideration shall be given to both the current service requirements and the reasonably foreseeable service requirements at least 10 years following the bringing into service of the platform.

4.2.9.1. Usable length of platforms

The usable length of a platform shall be defined according to point 4.2.1.

4.2.9.2. Platform height

(1) The nominal platform height shall be 550 mm or 760 mm above the running surface for radii of 300 m or more.

(2) For smaller radii the nominal platform height may be adjusted depending on the platform offset to minimise the stepping distance between the train and the platform.

(3) For platforms where trains, which are outside the scope of the LOC&PAS TSN, are intended to stop, different provisions for the nominal platform height might apply.
Instead of points (1) and (2), for the 1 520 mm track gauge system the nominal platform height shall be 200 mm or 550 mm above the running surface.

Instead of points (1) and (2), for the 1 600 mm track gauge system the nominal platform height shall be 915 mm above the running surface.

4.2.9.3. Platform offset

(1) The distance between the track centre and the platform edge parallel to the running plane \( (b_q) \), as defined in chapter 13 of EN 15273-3:2013, shall be set on the basis of the installation limit gauge \( (b_{qlim}) \). The installation limit gauge shall be calculated on the basis of the gauge G1.

(2) The platform shall be built close to the gauge within a maximum tolerance of 50 mm. The value for \( b_q \) shall therefore respond to:

\[ b_{qlim} \leq b_q \leq b_{qlim} + 50 \text{ mm}. \]

Instead of points (1) and (2), for the 1 520 mm track gauge system the platform offset shall be:

(a) 1 920 mm for platforms with heights of 550 mm and
(b) 1 745 mm for platforms with height of 200 mm.

Instead of points (1) and (2), for the 1 600 mm track gauge system the platform offset shall be 1 560 mm.

4.2.9.4. Track layout alongside platforms

(1) Track adjacent to the platforms for new lines shall preferably be straight, but shall nowhere have a radius of less than 300 m.

(2) No values are specified for an existing track alongside new, renewed or upgraded platforms.

4.2.10. Health, safety and environment

4.2.10.1. Maximum pressure variations in tunnels

(1) Any tunnel or underground structure intended to be operated at speeds greater than or equal to 200 km/h has to provide that maximum pressure variation, caused by the passage of a train running at the maximum allowed speed in the tunnel, do not exceed 10 kPa during the time taken for the train to pass through the tunnel.

(2) Above requirement has to be fulfilled along the outside of any train complying with the Locomotives and Passenger TSINTSN.

4.2.10.2. Effect of crosswinds
A line is interoperable from the cross wind point of view if safety is ensured for a reference train running along that line under the most critical operational conditions.

The rules for proving conformity shall take into account the characteristic wind curves of the reference trains defined in the LOC&PAS TSIINTSN.

If safety cannot be achieved without mitigating measures, either due to the geographic situation or to other specific features of the line, the infrastructure manager shall take the necessary measures to maintain the safety, for example by:

- locally reducing train speeds, possibly temporarily during periods at risk of storms,
- installing equipment to protect the track section concerned from cross winds,
- other appropriate means.

It shall be demonstrated that safety is achieved after measures taken.

### 4.2.10.3 Aerodynamic effect on ballasted track

The aerodynamic interaction between rolling stock and infrastructure may cause the lifting and further blowing away of ballast stones from the track bed in plain line and switches and crossings (Ballast pick up). This risk shall be mitigated.

The requirements for the infrastructure subsystem aimed at mitigating the risk for “ballast pick up“ apply only to lines intended to be operated at speed greater than 250 km/h.

The requirements of point (2) above are an open point.

### 4.2.11. Provision for operation

#### 4.2.11.1. Location markers

Location markers shall be provided at nominal intervals along the track of not more than 1 000 m.

#### 4.2.11.2. Equivalent conicity in service

If ride instability is reported, the railway undertaking and the infrastructure manager shall localise the section of the line in a joint investigation according paragraphs (2) and (3) hereafter.

*Note:* This joint investigation is also specified in point 4.2.3.4.3.2 of TSIINTSN LOC & PAS for action on rolling stock.
The infrastructure manager shall measure the track gauge and the railhead profiles at the site in question at a distance of approximate 10 m. The mean equivalent conicity over 100 m shall be calculated by modelling with the wheelsets (a) – (d) mentioned in paragraph 4.2.4.5.(4) of this TSINTSN in order to check for compliance, for the purpose of the joint investigation, with the limit equivalent conicity for the track specified in Table 14.

Table 14
Equivalent conicity in service limit values for the track (for the purpose of joint investigation)

<table>
<thead>
<tr>
<th>Speed range [km/h]</th>
<th>Maximum value of mean equivalent conicity over 100 m</th>
</tr>
</thead>
<tbody>
<tr>
<td>$v \leq 60$</td>
<td>assessment not required</td>
</tr>
<tr>
<td>$60 &lt; v \leq 120$</td>
<td>0.40</td>
</tr>
<tr>
<td>$120 &lt; v \leq 160$</td>
<td>0.35</td>
</tr>
<tr>
<td>$160 &lt; v \leq 230$</td>
<td>0.30</td>
</tr>
<tr>
<td>$v &gt; 230$</td>
<td>0.25</td>
</tr>
</tbody>
</table>

If the mean equivalent conicity over 100 m complies with the limit values in Table 14, a joint investigation by the railway undertaking and the infrastructure manager shall be undertaken to specify the reason for the instability.

4.2.12. Fixed installations for servicing trains

4.2.12.1. General

This point 4.2.12 sets out the infrastructure elements of the maintenance subsystem required for servicing trains.

4.2.12.2. Toilet discharge

Fixed installations for toilet discharge shall be compatible with the characteristics of the retention toilet system specified in the LOC & PAS NTSONNTSI.

4.2.12.3. Train external cleaning facilities

(1) Where a washing plant is provided it shall be able to clean the outer sides of single or double-deck trains between a height of:

(a) 500 to 3 500 mm for a single-deck train,
(b) 500 to 4 300 mm for double-deck trains.

(2) The washing plant shall be designed so that trains can be driven through it at any speed between 2 km/h and 5 km/h.

4.2.12.4. Water restocking
(1) Fixed equipment for water restocking shall be compatible with the characteristics of the water system specified in the LOC & PAS NTSNTSI.

(2) Fixed equipment for drinking water supply on the interoperable network shall be supplied with drinking water meeting the requirements of Council Directive 98/83/EC.

4.2.12.5. Refuelling

Refuelling equipment shall be compatible with the characteristics of the fuel system specified in the LOC & PAS NTSNTSI.

4.2.12.6. Electrical shore supply

Where provided, electrical shore supply shall be by means of one or more of the power supply systems specified in the LOC & PAS NTSNTSI.

4.3. Functional and technical specification of the interfaces

From the standpoint of technical compatibility, the interfaces of the infrastructure subsystem with the other subsystems are like described in the following points.

4.3.1. Interfaces with the rolling stock subsystem

Table 15

Interfaces with the rolling stock subsystem, 'Locomotives and Passenger Rolling Stock TSI/TSN'

<table>
<thead>
<tr>
<th>Interface</th>
<th>Reference Infrastructure NTSNTSI</th>
<th>Reference Locomotives and Passenger Rolling Stock NTSNTSI</th>
</tr>
</thead>
<tbody>
<tr>
<td>Track gauge</td>
<td>4.2.4.1 Nominal track gauge</td>
<td>4.2.3.5.2.1 Mechanical and geometrical characteristics of wheelset</td>
</tr>
<tr>
<td></td>
<td>4.2.5.1 Design geometry of switches and crossings</td>
<td>4.2.3.5.2.3 Variable gauge wheelsets</td>
</tr>
<tr>
<td></td>
<td>4.2.8.6 The immediate action limits for switches and crossings</td>
<td></td>
</tr>
<tr>
<td>Gauge</td>
<td>4.2.3.1 Structure gauge</td>
<td>4.2.3.1 Gauging</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Category</th>
<th>Subcategories</th>
</tr>
</thead>
<tbody>
<tr>
<td>Axle load and axle spacing</td>
<td>4.2.6.1 Track resistance to vertical loads</td>
</tr>
<tr>
<td></td>
<td>4.2.6.3 Lateral track resistance</td>
</tr>
<tr>
<td></td>
<td>4.2.7.1 Resistance of new bridges to traffic loads</td>
</tr>
<tr>
<td></td>
<td>4.2.7.2 Equivalent vertical loading for new earthworks and earth pressure effects imposed on new structures</td>
</tr>
<tr>
<td></td>
<td>4.2.7.4 Resistance of existing bridges and earthworks to traffic loads</td>
</tr>
<tr>
<td>Running characteristics</td>
<td>4.2.6.1 Track resistance to vertical loads</td>
</tr>
<tr>
<td></td>
<td>4.2.6.3 Lateral track resistance</td>
</tr>
<tr>
<td></td>
<td>4.2.7.1 Resistance of new bridges to traffic loads</td>
</tr>
<tr>
<td></td>
<td>4.2.7.4 Equivalent conicity in service</td>
</tr>
<tr>
<td>Ride stability</td>
<td>4.2.4.4 Equivalent conicity</td>
</tr>
<tr>
<td></td>
<td>4.2.4.6 Railhead profile for plain line</td>
</tr>
<tr>
<td></td>
<td>4.2.11.2 Equivalent conicity in service</td>
</tr>
<tr>
<td>Longitudinal actions</td>
<td>4.2.6.2 Longitudinal track resistance</td>
</tr>
<tr>
<td></td>
<td>4.2.7.1.5 Actions due to traction and braking (longitudinal loads)</td>
</tr>
<tr>
<td>Minimum horizontal curve radius</td>
<td>4.2.3.4 Minimum radius of horizontal curve</td>
</tr>
<tr>
<td></td>
<td>4.2.3.6 Minimum curve radius</td>
</tr>
<tr>
<td></td>
<td>Annex A, A.1 Buffers</td>
</tr>
<tr>
<td></td>
<td>4.2.2.10 Load conditions and weighed mass</td>
</tr>
<tr>
<td></td>
<td>4.2.3.2.1 Axle load parameter</td>
</tr>
<tr>
<td></td>
<td>4.2.3.4.2.1 Limit values for running safely</td>
</tr>
<tr>
<td></td>
<td>4.2.3.4.2.2 Track loading limit values</td>
</tr>
<tr>
<td></td>
<td>4.2.3.4.3 Equivalent conicity</td>
</tr>
<tr>
<td></td>
<td>4.2.3.5.2.2 Mechanical and geometrical characteristics of wheels</td>
</tr>
<tr>
<td></td>
<td>4.2.4.5 Braking performance</td>
</tr>
<tr>
<td></td>
<td>4.2.5.2.1 Braking performance</td>
</tr>
</tbody>
</table>

Annex A, A.1 Buffers
<table>
<thead>
<tr>
<th>Running dynamic behaviour</th>
<th>4.2.4.3 Cant deficiency</th>
<th>4.2.3.4.2 Running dynamic behaviour</th>
</tr>
</thead>
<tbody>
<tr>
<td>Maximum deceleration</td>
<td>4.2.6.2 Longitudinal track resistance</td>
<td>4.2.4.5 Braking performance</td>
</tr>
<tr>
<td></td>
<td>4.2.7.1.5 Actions due to traction and braking</td>
<td></td>
</tr>
<tr>
<td>Aerodynamic effect</td>
<td>4.2.3.2 Distance between track centres</td>
<td>4.2.6.2.1 Slipstream effects on passengers on platforms and on trackside workers</td>
</tr>
<tr>
<td></td>
<td>4.2.7.3 Resistance of new structures over or adjacent to tracks</td>
<td>4.2.6.2.2 Head pressure pulse</td>
</tr>
<tr>
<td></td>
<td>4.2.10.1 Maximum pressure variations in tunnels</td>
<td>4.2.6.2.3 Maximum pressure variations in tunnels</td>
</tr>
<tr>
<td></td>
<td>4.2.10.3 Aerodynamic effect on ballasted track</td>
<td>4.2.6.2.5 Aerodynamic effect on ballasted tracks</td>
</tr>
<tr>
<td>Crosswind</td>
<td>4.2.10.2 Effect of crosswinds</td>
<td>4.2.6.2.4 Crosswind</td>
</tr>
<tr>
<td>Installations for servicing trains</td>
<td>4.2.12.2 Toilet discharge</td>
<td>4.2.11.3 Toilet discharge system</td>
</tr>
<tr>
<td></td>
<td>4.2.12.3 Train external cleaning facilities</td>
<td>4.2.11.2.2 Exterior cleaning through a washing plant</td>
</tr>
<tr>
<td></td>
<td>4.2.12.4 Water restocking</td>
<td>4.2.11.4 Water refilling equipment</td>
</tr>
<tr>
<td></td>
<td>4.2.12.5 Refuelling</td>
<td>4.2.11.5 Interface for water refilling</td>
</tr>
<tr>
<td></td>
<td>4.2.12.6 Electric shore supply</td>
<td>4.2.11.7 Refuelling equipment</td>
</tr>
<tr>
<td></td>
<td></td>
<td>4.2.11.6 Special requirements for stabling of trains</td>
</tr>
</tbody>
</table>

**Table 16**

**Interfaces with the rolling stock subsystem, ‘Freight Wagons TSI**

<table>
<thead>
<tr>
<th>Interface</th>
<th>Reference Infrastructure</th>
<th>Reference Freight wagons</th>
</tr>
</thead>
<tbody>
<tr>
<td>Track gauge</td>
<td>4.2.4.1 Nominal track gauge</td>
<td>4.2.3.6.2 Characteristics of wheelsets</td>
</tr>
<tr>
<td></td>
<td>4.2.4.6 Railhead profile for plain line</td>
<td></td>
</tr>
</tbody>
</table>


### 4.3.2. Interfaces with the energy subsystem

*Table 17*

<table>
<thead>
<tr>
<th>Interface</th>
<th>Reference Infrastructure</th>
<th>Reference Energy</th>
</tr>
</thead>
<tbody>
<tr>
<td>Gauge</td>
<td>4.2.3.1 Structure gauge</td>
<td>4.2.10 Pantographs gauge</td>
</tr>
<tr>
<td></td>
<td>4.2.10 Pantographs gauge</td>
<td></td>
</tr>
</tbody>
</table>

**Gauge**

- 4.2.3.1 Structure gauge
- 4.2.3.2 Distance between track centres
- 4.2.3.5 Minimum radius of vertical curve
- 4.2.9.3 Platform offset

### Interfaces with the energy subsystem

#### Table 17

**Interfaces with the energy subsystem**

<table>
<thead>
<tr>
<th>Interface</th>
<th>Reference Infrastructure</th>
<th>Reference Energy</th>
</tr>
</thead>
<tbody>
<tr>
<td>Gauge</td>
<td>4.2.3.1 Structure gauge</td>
<td>4.2.10 Pantographs gauge</td>
</tr>
</tbody>
</table>
### 4.3.3. Interfaces with the control command and signalling subsystem

#### Table 18

<table>
<thead>
<tr>
<th>Interface</th>
<th>Reference Infrastructure TSINTSN</th>
<th>Reference Control Command and Signalling TSINTSN</th>
</tr>
</thead>
<tbody>
<tr>
<td>Structure gauge set for CCS installations. Visibility of track-side CCS objects.</td>
<td>4.2.3.1 Structure gauge</td>
<td>4.2.5.2 Eurobalise communication (space for installation)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>4.2.5.3 Euroloop communication (space for installation)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>4.2.10 Train detection systems (space for installation)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>4.2.15 Visibility of track-side control-command and signalling objects</td>
</tr>
</tbody>
</table>

### 4.3.4. Interfaces with the operation and traffic management subsystem

#### Table 19

<table>
<thead>
<tr>
<th>Interface</th>
<th>Reference Infrastructure NTSNTSI</th>
<th>Reference Operation and Traffic Management NTSNTSI</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ride stability</td>
<td>4.2.11.2 Equivalent conicity in service</td>
<td>4.2.3.4.4 Operational quality</td>
</tr>
<tr>
<td>Use of eddy current brakes</td>
<td>4.2.6.2 Longitudinal track resistance</td>
<td>4.2.2.6.2 Braking performance</td>
</tr>
<tr>
<td>Crosswinds</td>
<td>4.2.10.2 Effect of crosswinds</td>
<td>4.2.3.6.3 Contingency arrangements</td>
</tr>
<tr>
<td>Operating rules</td>
<td>4.4 Operating rules</td>
<td>4.2.1.2.2.2 Modifications to information contained in the route book</td>
</tr>
<tr>
<td></td>
<td></td>
<td>4.2.3.6 Degraded operation</td>
</tr>
<tr>
<td>Staff competences</td>
<td>4.6 Professional competences</td>
<td>2.2.1 Staff and trains’</td>
</tr>
</tbody>
</table>
4.4. Operating rules

(1) Operating rules are developed within the procedures described in the infrastructure manager’s safety management system. These rules take into account the documentation related to operation which forms a part of the technical file as required in regulation 17(2)(a) of and Schedule 4 to the Railways (Interoperability) Regulations 2011, Article 15(4) and set out in Annex IV (point 2.4) of Directive (EU) 2016/797.

(2) In certain situations involving pre-planned works, it may be necessary to temporarily suspend the specifications of the infrastructure subsystem and its interoperability constituents defined in sections 4 and 5 of this TSINTSN.

4.5. Maintenance rules

(1) Maintenance rules are developed within the procedures described in the infrastructure manager’s safety management system.

(2) The maintenance file shall be prepared before placing a line into service as the part of the technical file accompanying the declaration of verification.

(3) The maintenance plan shall be drawn up for the subsystem to ensure that the requirements set out in this TSINTSN are maintained during its lifetime.

4.5.1. Maintenance file

A maintenance file shall contain at least:

(a) a set of values for immediate action limits,
(b) the measures taken (for example speed restriction, repair time) when prescribed limits are not met,
related to track geometric quality and limits on isolated defects.

4.5.2. Maintenance plan

The infrastructure manager shall have a maintenance plan containing the items listed in point 4.5.1 together with at least the following:

(a) a set of values for intervention limits and alert limits,
(b) a statement about the methods, professional competences of staff and personal protective safety equipment necessary to be used,
(c) the rules to be applied for the protection of people working on or near the track,
(d) the means used to check that in-service values are respected,
(e) the measures taken, for speed greater than 250 km/h, to mitigate the risk of ballast pick up.

4.6. Professional qualifications
The professional qualifications of staff required for operation and maintenance of the infrastructure subsystem are not set out in this TSINTSN but are described in the infrastructure manager's safety management system.

4.7. Health and safety conditions

(1) The health and safety conditions of staff required for the operation and maintenance of the infrastructure subsystem shall be compliant with the relevant European and national legislation.

(2) The issue is covered by the procedures described in the infrastructure manager's safety management system.

5. INTEROPERABILITY CONSTITUENTS

5.1. Basis on which interoperability constituents have been selected

(1) The requirements of point 5.3 are based on a traditional design of ballasted track with Vignole (flat-bottom) rail on concrete or wooden sleepers and fastening providing resistance to longitudinal slip by bearing on the rail foot.

(2) Components and subassemblies used for the construction of other designs of track are not considered to be interoperability constituents.

5.2. List of constituents

(1) For the purposes of this technical specification for interoperability, only the following elements, whether individual components or subassemblies of the track are declared to be ‘interoperability constituents’:

(a) the rail (5.3.1),
(b) the rail fastening systems (5.3.2),
(c) track sleepers (5.3.3).

(2) The following points describe the specifications applicable to each of these constituents.

(3) Rails, fastenings and sleepers used for short length of track for specific purposes, for example in switches and crossings, at expansion devices, transition slabs and special structures, are not considered to be interoperability constituents.

5.3. Constituents performances and specifications

5.3.1. The rail

The specifications of the ‘rail’ interoperability constituent concern the following parameters:

(a) railhead profile,
(b) rail steel.
5.3.1.1. Railhead profile

The rail head profile shall fulfil the requirements of point 4.2.4.6 ‘Railhead profile for plain line’.

5.3.1.2. Rail steel

(1) The rail steel is relevant to the requirements of point 4.2.6 ‘Track resistance to applied loads’.

(2) The rail steel shall meet the following requirements:

(a) The rail hardness shall be at least 200 HBW.

(b) The tensile strength shall be at least 680 MPa.

(c) Minimum number of cycles at fatigue test without failure shall be at least \(5 \times 10^6\).

5.3.2. The rail fastening systems

(1) The rail fastening system is relevant to the requirements of point 4.2.6.1 for ‘Track resistance to vertical loads’, point 4.2.6.2 for ‘Longitudinal track resistance’ and point 4.2.6.3 for ‘Lateral track resistance’.

(2) The rail fastening system shall comply in laboratory test conditions with the following requirements:

(a) The longitudinal force required to cause the rail to begin to slip (i.e. move in an inelastic way) through a single rail fastening assembly shall be at least 7 kN and for speeds of more than 250 km/h shall be at least 9 kN,

(b) The rail fastening shall resist application of 3,000,000 cycles of the typical load applied in a sharp curve, such that the performance of the fastening in terms of clamping force and longitudinal restraint is not degraded by more than 20% and vertical stiffness is not degraded by more than 25%. The typical load shall be appropriate to:

— the maximum axle load the rail fastening system is designed to accommodate,
— the combination of rail, rail inclination, rail pad and type of sleepers with which the fastening system may be used, the rail fastening shall resist application of 3,000,000 cycles of the typical load applied in a sharp curve, such that the change in performance of the fastening system shall not exceed:
— 20% in terms of clamping force,
— 25% in terms of vertical stiffness,
— a reduction of more than 20% in terms of longitudinal restraint.

The typical load shall be appropriate to:
— the maximum axle load the rail fastening system is designed to accommodate,
— the combination of rail, rail inclination, rail pad and type of sleepers with which the fastening system may be used.

5.3.3. Track sleepers

(1) Track sleepers shall be designed such that when they are used with a specified rail and rail fastening system they will have properties that are consistent with the requirements of point 4.2.4.1 for ‘Nominal track gauge’, point 4.2.4.7 for ‘Rail inclination’ and point 4.2.6 for ‘Track resistance to applied loads’.

(2) For the nominal track gauge system of 1 435 mm, the design track gauge for track sleepers shall be 1 437 mm.

6. ASSESSMENT OF CONFORMITY OF INTEROPERABILITY CONSTITUENTS AND ECUK VERIFICATION OF THE SUBSYSTEMS

Modules for the procedures for assessment of conformity and suitability for use and ECUK verification are defined in Article 8 of this Regulation NTSN.

6.1. Interoperability Constituents

6.1.1. Conformity assessment procedures

(1) The conformity assessment procedure of interoperability constituents as defined in section 5 of this TSI NTSN shall be carried out by application of the relevant modules.

(2) Serviceable interoperability constituents that are suitable for reuse are not subject to the conformity assessment procedures.

6.1.2. Application of modules as set out in the Modules NTSN

(1) The following modules for conformity assessment of interoperability constituents are used:

(a) CA ‘Internal production control’
(b) CB ‘ECUK type examination’
(c) CC ‘Conformity to type based on internal production control’
(d) CD ‘Conformity to type based on quality management system of the production process’
(e) CF ‘Conformity to type based on product verification’
(f) CH ‘Conformity based on full quality management system’
(2) The modules for conformity assessment of interoperability constituents shall be chosen from those shown in Table 20.

Table 20

 Modules for conformity assessment to be applied for interoperability constituents

<table>
<thead>
<tr>
<th>Procedures</th>
<th>Rail</th>
<th>Rail fastening system</th>
<th>Track sleepers</th>
</tr>
</thead>
<tbody>
<tr>
<td>Placed on the EU market before entry into force of relevant TSIs</td>
<td>CA or CH</td>
<td>CA or CH</td>
<td></td>
</tr>
<tr>
<td>Placed on the UK market after entry into force of relevant TSIs</td>
<td>CB + CC or CH or CB + CD or CB + CF or CH</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(3) In the case of products placed on the UK market before the 12 December 2014 publication of relevant TSIs, the type is considered to have been approved and therefore UKEC type examination (module CB) is not necessary, provided that the manufacturer demonstrates that tests and verification of interoperability constituents have been considered successful for previous applications under comparable conditions and are in conformity with the requirements of the INF TSI 1299/2014/EU. In this case these assessments shall remain valid in the new application. If it is not possible to demonstrate that the solution is positively proven in the past, the procedure for interoperability constituents placed on the UK market after publication of this NTSNTSI applies.

(4) The conformity assessment of interoperability constituents shall cover the phases and characteristics as indicated in Table 36 of Appendix A to this TSINTSN.

6.1.3. Innovative solutions for interoperability constituents

If an innovative solution is proposed for an interoperability constituent, the procedure described in Article 10 shall apply.

6.1.4. **ECUK declaration of conformity for interoperability constituents**

6.1.4.1. Interoperability constituents subject to other requirements European Union Directives

(1) Regulation 25(4) of the Railways (Interoperability) Regulations 2011 states that if an interoperability constituent is subject to other requirements in any
enactment or rule of law, a person may only draw up a UK declaration of conformity or suitability for use if satisfied that the interoperability constituent meets those other requirements and the person must state in the declaration that the interoperability constituent meets those other requirements in accordance with Article 10(3) of Directive (EU) 2016/797, for interoperability constituents that are the subject of other legal acts of the Union covering other matters, the EC declaration of conformity or suitability for use shall state that the interoperability constituents also meet the requirements of those other legal acts.

(2) in accordance with point 3(e) of Schedule 8 to the Railways (Interoperability) Regulations 2011, Annex I to Commission Implementing Regulation (EU) 2019/250, the UK EC declaration of conformity or suitability for use shall include a list of restrictions or conditions of use.

6.1.4.2. **ECUK declaration of conformity for rails**
No statement setting out the conditions of use is required.

6.1.4.3. **ECUK declaration of conformity for rail fastening systems**
The ECUK declaration of conformity shall be accompanied by statement setting out:
(a) the combination of rail, rail inclination, rail pad and type of sleepers with which the fastening system may be used
(b) the maximum axle load the rail fastening system is designed to accommodate.

6.1.4.4. **ECUK declaration of conformity for track sleepers**
The ECUK declaration of conformity shall be accompanied by statement setting out:
(a) the combination of rail, rail inclination and type of rail fastening system with which the sleeper may be used,
(b) the nominal and design track gauge,
(c) the combinations of axle load and train speed the track sleeper is designed to accommodate.

6.1.5. **Particular assessment procedures for interoperability constituents**

6.1.5.1. **Assessment of rails**
Assessment of rail steel shall be done according to the following requirements:

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(a) Rail hardness shall be tested for position RS according to EN 13674-1:2011 paragraph 9.1.8, measured using one specimen (control sample out of production).

(b) Tensile strength shall be tested according to EN 13674-1:2011 paragraph 9.1.9, measured using one specimen (control sample out of production).

(c) Fatigue test shall be done according to EN 13674-1:2011 paragraph 8.1 and paragraph 8.4.

6.1.5.2. Assessment of sleepers

(1) Until 31 May 2021 a design track gauge for track sleepers below 1 437 mm shall be allowed.

(2) For polyvalent gauge and multiple gauge track sleepers it is allowed not to assess the design track gauge for the nominal track gauge of 1 435 mm.

6.2. Infrastructure subsystem

6.2.1. General provisions

(1) At the request of the applicant, the notified approved body carries out the ECUK verification of the infrastructure subsystem in accordance with Schedule 4 to the Railways (Interoperability) Regulations 2011 Article 15 of Directive (EU) 2016/797 and in accordance with the provisions of the relevant modules.

(2) If the applicant demonstrates that tests or assessments of an infrastructure subsystem or parts of the subsystem are the same as have been successful for previous applications of a design, the notified approved body shall consider the results of these tests and assessments for the ECUK verification.

(3) The ECUK verification of the infrastructure subsystem shall cover the phases and characteristics indicated in Table 37 in Appendix B to this TSINTSN.

(4) Performance parameters as set out in point 4.2.1 of this TSINTSN are not subject to the ECUK verification of the subsystem.

(5) Particular assessment procedures for specific basic parameters of infrastructure subsystem are set out in point 6.2.4.

(6) The applicant shall draw up the ECUK declaration of verification for the infrastructure subsystem in accordance with Article 18 and Annex V of Directive 2008/57/EC regulations 16 and 17 and Schedule 5 to the Railways (Interoperability) Regulations 2011.

6.2.2. Application of modules

For the ECUK verification procedure of the infrastructure subsystem, the applicant may choose either:

(a) Module SG: ECUK verification based on unit verification, or
6.2.2.1. Application of module SG

In the case where ECUK verification is most effectively undertaken by using information collected by the infrastructure manager, contracting entity or the main contractors involved (for example data obtained using track recording vehicle or other measuring devices), the notified approved body shall take this information into account to assess conformity.

6.2.2.2. Application of module SH1

The SH1 module may be chosen only where the activities contributing to the proposed subsystem to be verified (design, manufacturing, assembling, installation) are subject to a quality management system for design, production, final product inspection and testing, approved and surveyed by a notified approved body.

6.2.3. Innovative solutions

If an innovative solution is proposed for the infrastructure subsystem, the procedure described in Article 10 shall apply.

6.2.4. Particular assessment procedures for infrastructure subsystem

6.2.4.1. Assessment of Structure gauge

(1) Assessment of structure gauge as a design review shall be done against characteristic cross sections using the results of calculations made by infrastructure manager or the contracting entity on the basis of sections 5, 7, 10, Annex C and point D.4.8 of Annex D of EN 15273-3:2013.

(2) Characteristic cross sections are:

(a) track without cant,
(b) track with maximum cant,
(c) track with a civil engineering structure over the line
(d) any other location where the designed installation limit gauge is approached by less than 100 mm or the installation nominal gauge or uniform gauge is approached by less than 50 mm.

(3) After assembly before putting into service clearances shall be verified at locations where the designed installation limit gauge is approached by less than 100 mm or the installation nominal gauge or uniform gauge is approached by less than 50 mm.

(4) This provision has been left intentionally blank.

Instead of point (1), for the 1520 mm track gauge system assessment of structure gauge as a design review is to
be made against characteristic cross sections using the uniform structure gauge 'S' as defined in Appendix H to this TSI.

(5) Instead of point (1), for the 1 600 mm track gauge system assessment of structure gauge as a design review is to be made against characteristic cross sections using the structure gauge 'IRL1' as defined in Appendix O to this TSI.

6.2.4.2. Assessment of distance between track centres

(1) A design review for assessment of the distance between track centres shall be done using the results of calculations made by the Infrastructure Manager or the contracting entity on the basis of chapter 9 of EN 15273-3:2013. The nominal distance between track centres shall be checked at the line layout where distances are given in parallel to the horizontal plane. The limit installation distance between track centres shall be checked with the radius and relevant cant.

(2) After assembly before putting into service, distance between track centres shall be verified at critical locations where the limit installation distance between track centres as defined according chapter 9 of EN 15273-3:2013 is approached by less than 50 mm.

(3) Instead of point (1), for the 1 520 mm track gauge system a design review for assessment of the distance between track centres is to be made using the results of calculations made by the infrastructure manager or the contracting entity. The nominal distance between track centres shall be checked at the line layout where distances are given in parallel to the horizontal plane. The limit installation distance between track centres shall be checked with the radius and relevant cant.

(4) Instead of point (2), for the 1 520 mm track gauge system after assembly before putting into service, distance between track centres shall be verified at critical locations where the limit installation distance between track centres is approached by less than 50 mm.

6.2.4.3. Assessment of nominal track gauge

(1) Assessment of the nominal track gauge at design review shall be done by checking the self-declaration of the applicant.

(2) Assessment of the nominal track gauge at assembly before putting into service shall be done by checking the interoperability constituent sleeper’s certificate. For non-certified interoperability constituents assessment of the nominal track gauge shall be done by checking the self-declaration of the applicant.

6.2.4.4. Assessment of track layout

(1) At design review the curvature, cant, cant deficiency and abrupt change of cant deficiency shall be assessed against the local design speed.
Assessment of switches and crossings layout is not required.

### 6.2.4.5. Assessment of cant deficiency for trains designed to travel with higher cant deficiency

Point 4.2.4.3(2) states that ‘It is permissible for trains specifically designed to travel with higher cant deficiency (for example multiple units with lower axle loads; vehicles with special equipment for the negotiation of curves) to run with higher cant deficiency values, subject to a demonstration that this can be achieved safely’. This demonstration is outside the scope of this TSI/NTSN and thus not subject to an notified/approved body verification of the infrastructure subsystem. The demonstration shall be undertaken by the RU, if necessary in cooperation with the IM.

### 6.2.4.6. Assessment of design values for equivalent conicity

Assessment of design values for equivalent conicity shall be done using the results of calculations made by the infrastructure manager or the contracting entity on the basis of EN 15302:2008+A1:2010.

### 6.2.4.7. Assessment of railhead profile

(1) The design profile of new rails shall be checked against point 4.2.4.6.

(2) Reused serviceable rails shall not be subject to the requirements for railhead profile as set out in point 4.2.4.6.

### 6.2.4.8. Assessment of switches and crossings

Assessment of switches and crossings related to points 4.2.5.1 to 4.2.5.3 shall be done by checking that a self-declaration of the infrastructure manager or contracting entity exists.

### 6.2.4.9. Assessment of new structures, earthworks and earth pressure effects

(1) Assessment of new structures shall be done by checking the traffic loads and the track twist limit used for design against the minimum requirements of points 4.2.7.1 and 4.2.7.3. The notified/approved body is not required to review the design nor carry out any calculations. When reviewing the value of factor alpha used in the design according to point 4.2.7.1 it is only necessary to check that the value of factor alpha satisfies Table 11.

(2) Assessment of new earthworks and earth pressure effects shall be done by checking the vertical loads used for design according to requirements of point 4.2.7.2. When reviewing the value of factor alpha used in the design according to point 4.2.7.2 it is only necessary to check that the value of factor alpha satisfies Table 11. The notified/approved body is not required to review the design nor carry out any calculations.

### 6.2.4.10. Assessment of existing structures
(1) Assessment of existing structures against the requirements of point 4.2.7.4(3) (b) and (c) shall be done by one of the following methods:

(a) check that the values of EN line categories, in combination with the allowed speed published or intended to be published for the lines containing the structures, is in line with the requirements of Appendix E of this TSINTSN,

(b) check that the values of EN line categories, in combination with the allowed speed specified for the structures or for the design, is in line with the requirements of Appendix E of this TSINTSN,

(c) check the traffic loads specified for the structures or for the design against the minimum requirements of points 4.2.7.1.1 and 4.2.7.1.2. When reviewing the value of factor alpha according to point 4.2.7.1.1 it is only necessary to check that the value of factor alpha is in line with the value of factor alpha mentioned in Table 11.

(2) It is not required to review the design nor carry out any calculations.

(3) For existing structures assessment point 4.2.7.4(4) applies respectively.

6.2.4.11. Assessment of platform offset

(1) Assessment of the distance between the track centre and the platform edge as a design review shall be done using the results of calculations made by the Infrastructure Manager or the contracting entity on the basis of chapter 13 of EN 15273-3:2013.

(2) After assembly before putting into service clearances shall be verified. The offset is checked at the ends of the platform and every 30 m in straight track and every 10 m in curved track.

(3) This provision has been left intentionally blank Instead of point (1), for the 1 520 mm track gauge system assessment of the distance between the track centre and the platform edge as a design review shall be done against requirements of point 4.2.9.3. Point (2) applies accordingly.

(4) Instead of point (1), for the 1 600 mm track gauge system assessment of the distance between the track centre and the platform edge as a design review shall be done against requirements of point 4.2.9.3(4). Point (2) applies accordingly.

6.2.4.12. Assessment of maximum pressure variations in tunnels

(1) Assessment of maximum pressure variation in the tunnel (10 kPa criterion) shall be done using the results of numerical simulations according to chapters 4 and 6 of EN 14067-5:2006+A1:2010 made by the infrastructure manager or the contracting entity on the basis of all expected operational conditions with the trains complying with the Locomotives and Passengers TSINTSN and intended to run at speeds greater than or equal to 200 km/h in the specific tunnel to be assessed.
(2) The input parameters to be used are to be such that the reference characteristic pressure signature of the trains set out in the locomotives and passenger rolling stock TSI NTSN is fulfilled.

(3) The reference cross section areas of the interoperable trains (constant along a train) to be considered is to be, independently to each motor or trailer vehicle:
   (a) 12 m² for vehicles designed for GC and DE3 reference kinematic profile,
   (b) 11 m² for vehicles designed for GA and GB reference kinematic profile,
   (c) 10 m² for vehicles designed for G1 reference kinematic profiles.

   The vehicle gauge to be considered shall be set on the basis of the gauges selected according to point 4.2.1.

(4) The assessment may take into account construction features which reduce the pressure variation if any, as well as the tunnel length.

(5) The pressure variations due to atmospheric or geographical conditions can be neglected.

6.2.4.13. **Assessment of effect of crosswinds**

This demonstration of the safety is outside the scope of this TSI NTSN and thus not subject to an notified-approved body verification. The demonstration shall be undertaken by the infrastructure manager, if necessary in cooperation with the railway undertaking.

6.2.4.14. **Assessment of fixed installations for servicing trains**

Assessment of fixed installations for servicing trains is in the responsibility of the Member State concerned. This NTSN does not cover assessment of fixed installations for servicing trains. Those responsible for such installations should have regard to any requirements contained in any other enactment or rule of law in relation to such assessments.

6.2.4.15. **Assessment of compatibility with braking systems**

The assessment of the requirements laid down in point 4.2.6.2.2(2) is not required.

6.2.5. **Technical solutions giving presumption of conformity at design stage**

Presumption of conformity at design stage for technical solutions may be assessed prior and independent from a specific project.

6.2.5.1. **Assessment of track resistance for plain line**

(1) The demonstration of conformity of the track to the requirements of point 4.2.6 may be done by reference to an existing track design which meets the operating conditions intended for the subsystem concerned.
(2) A track design shall be defined by the technical characteristics as set out in Appendix C.1 to this TSINTSN and by its operating conditions as set out in Appendix D.1 to this TSINTSN.

(3) A track design is considered to be existing, if both of the following conditions are met:
   (a) the track design has been in normal operation for at least one year and
   (b) the total tonnage over the track was at least 20 million gross tons for the period of normal operation.

(4) The operating conditions for an existing track design refer to conditions which have been applied in normal operation.

(5) The assessment to confirm an existing track design shall be performed by checking that the technical characteristics as set out in Appendix C.1 to this TSINTSN and conditions of use as set out in Appendix D.1 to this TSINTSN are specified and that the reference to the previous use of the track design is available.

(6) When a previously assessed existing track design is used in a project, the notified approved body shall only assess that the conditions of use are respected.

(7) For new track designs that are based on existing track designs, a new assessment can be performed by verifying the differences and evaluating their impact on the track resistance. This assessment may be supported for example by computer simulation or by laboratory or in situ testing.

(8) A track design is considered to be new, if at least one of the technical characteristics set out in Appendix C to this TSINTSN or one of conditions of use set out in Appendix D to this TSINTSN is changed.

6.2.5.2. Assessment for switches and crossing

(1) The provisions as set out in point 6.2.5.1 are applicable for the assessment of track resistance for switches and crossings. Appendix C.2 sets out the technical characteristics of switches and crossings design and Appendix D.2 sets out the conditions of use of switches and crossings design.

(2) Assessment of design geometry of switches and crossings shall be done according to point 6.2.4.8 of this TSINTSN.

(3) Assessment of maximum unguided length of fixed obtuse crossings shall be done according to point 6.2.4.8 of this TSINTSN.

6.3. ECUK Verification when speed is used as a migration criterion

(1) Point 7.5 allows a line to be put into service at a lower speed than the ultimate intended speed. This point sets out requirements for ECUK verification in this case.
Some limiting values set out in section 4 depend on the intended speed of the route. Conformity should be assessed at the intended ultimate speed; however it is permissible to assess speed dependant characteristics at the lower speed at the time of placing in service.

The conformity of the other characteristics for the intended speed of the route remains valid.

To declare the interoperability at this intended speed, it is only necessary to assess the conformity of the characteristics temporarily not respected, when they are brought up to the required level.

6.4. Assessment of maintenance file

Point 4.5 requires the infrastructure manager to have for each interoperable line a maintenance file for the infrastructure subsystem.

The body shall confirm that the maintenance file exists and contains the items listed in point 4.5.1. The body is not responsible for assessing the suitability of the detailed requirements set out in the maintenance file.

The body shall include a reference to the maintenance file required by point 4.5.1 of this NTSN in the technical file referred to in regulation 17(2) of the Railways (Interoperability) Regulations 2011 Article 15(4) of Directive (EU) 2016/797.

6.5. Subsystems containing Interoperability constituents not holding an ECUK declaration

The circumstances in which it is permissible to rely on an EC declaration of conformity rather than a UK declaration of conformity to place an interoperability constituent on the UK market and any relevant additional assessment requirements are set out in Part 3 and regulation 47A of the Railways (Interoperability) Regulations 2011 and in the NTSN concerning the further assessment of interoperability constituents which hold an EC declaration of conformity or suitability for use.

6.5.1. Conditions

Subject to 6.5 above, until 31 May 2021, a notified-approved body is allowed to issue an ECUK certificate of verification for a subsystem even if some of the interoperability constituents incorporated within the subsystem are not covered by the relevant EC or UK declarations of conformity and/or suitability for use according to this TSINTSN (or relevant TSIs), if the following criteria are complied with:

(a) the conformity of the subsystem has been checked against the requirements of section 4 and in relation to sections 6.2 to 7 (except point 7.7 'Specific
(b) the interoperability constituents, which are not covered by the relevant EC or UK declaration of conformity and/or suitability for use, have been used in a subsystem already approved and put in service in at least one of the Member States of the EU or the UK before the entry in force of this TSI January 2015.

(2) ECUK declarations of conformity and/or suitability for use shall not be drawn up for the interoperability constituents assessed in this manner.

6.5.2. Documentation

(1) The ECUK certificate of verification of the subsystem shall indicate clearly which interoperability constituents have been assessed by the notified body as part of the subsystem verification.

(2) The ECUK declaration of verification of the subsystem shall indicate clearly:

(a) Which interoperability constituents have been assessed as part of the subsystem;

(b) Confirmation that the subsystem contains the interoperability constituents identical to those verified as part of the subsystem;

(c) For those interoperability constituents, the reason(s) why the manufacturer did not provide an EC or UK Declaration of conformity and/or suitability for use before its incorporation into the subsystem, including the application of national technical rules or national rules notified under Article 14 of Directive (EU) 2016/797.

6.5.3. Maintenance of the subsystems certified according to 6.5.1.

(1) During and after the transition period and until the subsystem is upgraded or renewed (taking into account the decision of Member State/the Competent Authority on application of TSI/the NTSNs), the interoperability constituents which do not hold an EC or UK Declaration of conformity and/or suitability for use and are of the same type are allowed to be used as maintenance related replacements (spare parts) for the subsystem, under the responsibility of the body responsible for maintenance.

(2) In any case the body responsible for maintenance must ensure that the components for maintenance related replacements are suitable for their

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8 Directive 2016/797/EU of the European Parliament and of the Council of 11th May 2016 on the interoperability of the rail system within the Community, implemented by the Railways (Interoperability) Regulations 2011. The EU legislation is EU derived domestic legislation under section 2 of the European Union (Withdrawal) Act 2018, and it has been amended under that Act by the Railways (Interoperability) (Amendment) (EU Exit) Regulations 2019 SI (2019/345) to make amendments to EU legislation as a result of the UK’s exit from the EU.
applications, are used within their area of use and enable interoperability to be achieved within the rail system while at the same time meeting the essential requirements. Such components must be traceable and certified in accordance with any national or international rule or any code of practice widely acknowledged in the railway domain.

6.6. **Subsystem containing serviceable interoperability constituents that are suitable for reuse**

6.6.1. **Conditions**

(1) An **notified approved** body is allowed to issue an **ECUK** certificate of verification for a subsystem even if some of the interoperability constituents incorporated within the subsystem are serviceable interoperability constituents that are suitable for reuse, if the following criteria are complied with:

   (a) the conformity of the subsystem has been checked against the requirements of section 4 and in relation to sections 6.2 to 7 (except point 7.7 ‘Specific Cases’) of this **TSINTSN** by the **notified approved** body. Furthermore the conformity of the ICs to 6.1 does not apply, and

   (b) the interoperability constituents are not covered by the relevant **EC** or **UK** declaration of conformity and/or suitability for use.

(2) **ECUK** declarations of conformity and/or suitability for use shall not be drawn up for the interoperability constituents assessed in this manner.

6.6.2. **Documentation**

(1) The **ECUK** certificate of verification of the subsystem shall indicate clearly which interoperability constituents have been assessed by the **notified approved** body as part of the subsystem verification.

(2) The **ECUK** declaration of verification of the subsystem shall indicate clearly:

   (a) Which interoperability constituents are serviceable interoperability constituents that are suitable for reuse;

   (b) Confirmation that the subsystem contains the interoperability constituents identical to those verified as part of the subsystem.

6.6.3. **Use of serviceable interoperability constituents in maintenance**

(1) Serviceable interoperability constituents that are suitable for reuse are allowed to be used as maintenance related replacements (spare parts) for the subsystem, under the responsibility of the body responsible for maintenance.

(2) In any case the body responsible for maintenance must ensure that the components for maintenance related replacements are suitable for their applications, are used within their area of use, and enable interoperability to be achieved within the rail system while at the same time meeting the essential
requirements. Such components must be traceable and certified in accordance with any national or international rule, or any code of practice widely acknowledged in the railway domain.

7. IMPLEMENTATION OF THE INFRASTRUCTURE NTSNTSI

Member States shall develop a national plan for the implementation of this TSI considering the coherence of the entire rail system of the European Union. This plan shall include all projects regarding new, renewal and upgrading of infrastructure subsystem, in line with the details mentioned in points 7.1 to 7.7 here below. As referred to in Article 9, the UK has published an implementation plan.

7.1. Application of this TSI NTSN to railway lines

Sections 4 to 6 and any specific provisions in points 7.2 to 7.6 here below apply in full to the lines within the geographical scope of this TSI NTSN, which will be placed in service as interoperable lines after this NTSN is published this TSI enters into force.

7.2. Application of this TSI NTSN to new railway lines

(1) For the purpose of this TSI NTSN a ‘new line’ means a line that creates a route where none currently exists.

(2) The following situations, for example to increase speed or capacity, may be considered as an upgraded line rather than a new line:

(a) the realignment of part of an existing route,

(b) the creation of a bypass,

(c) the addition of one or more tracks on an existing route, regardless of the distance between the original tracks and the additional tracks.

7.3. Application of this TSI NTSN to existing railway lines

7.3.1. Upgrading of a line

(1) In accordance with regulation 2 of the Railways (Interoperability) Regulations 2011 Article 2(14) of Directive (EU) 2016/797, “upgrading” means any major modification work on a subsystem or part of it which results in a change in the technical file accompanying the “EC” or “UK” declaration of verification, if that technical file exists, and which improves the overall performance of the subsystem.

(2) The infrastructure subsystem of a line is considered to be upgraded in the context of this NTSN when at least the performance parameters axle load or gauge, as defined in point 4.2.1 are improved in order to meet the requirements of another traffic code.
In accordance with regulation 2 of the Railways (Interoperability) Regulations 2011, Article 2(15) of Directive (EU) 2016/797, “renewal” means any major substitution work on a subsystem or part of it which does not change the overall performance of the subsystem.

For this purpose, major substitution should be interpreted as a project undertaken to systematically replace elements of a line or a section of a line. Renewal differs from a substitution in the framework of maintenance, referred to in point 7.3.3 below, since it gives the opportunity to achieve an NTSNa TSI compliant line. A renewal is the same case as upgrading, but without a change in performance parameters.

The scope of the upgrading or renewal of the infrastructure subsystem may cover the entire subsystem on a given line or only certain parts of the subsystem. According to regulation 13 of the Railways (Interoperability) Regulations 2011, Article 18(6) of Directive (EU) 2016/797, at the request of the applicant, the Competent Authority shall examine the project and decide whether a new authorisation for placing in service is needed.

Where a new authorisation is required, parts of the infrastructure subsystem falling under the scope of the upgrading or renewal shall comply with this NTSNTSI and shall be subject to the procedure established in Article 15 of Directive (EU) 2016/797, regulation 17 of and Schedule 4 to the Railways (Interoperability) Regulations 2011, unless a permission for non-application of NTSNTSI is granted according to regulation 14 of the Railways (Interoperability) Regulations 2011, Article 7 of Directive (EU) 2016/797.

Where a new authorisation for placing in service is not required, compliance with this NTSNTSI is recommended. Where compliance is not possible, the contracting entity shall inform the Member State of the reasons thereof.

7.3.2. This provision has been left intentionally blank

7.3.3. Substitution in the framework of maintenance

Where the parts of a subsystem on a line are maintained, the formal verification and authorisation for placing into service is not required in accordance with this TSI. However, maintenance replacements should be, as far as it is reasonably practicable, undertaken in accordance with the requirements of this TSI.

The objective should be that maintenance replacements progressively contribute the development of an interoperable line.

In order to bring progressively an important part of the infrastructure subsystem in a process towards interoperability, the following group of basic parameters should be adapted together:
(a) Line layout,
(b) Track parameters,
(c) Switches and crossings,
(d) Track resistance to applied loads,
(e) Structures resistance to traffic loads,
(f) Platforms.

(4) In such cases, it is noted that each of the above elements taken separately cannot ensure compliance of the whole subsystem. The conformity of a subsystem can only be stated when all the elements are compliant with the NTSNTS.$^9$

### 7.3.4. Existing lines that are not subject to a renewal or upgrading project

The demonstration of the level of compliance of existing lines with the basic parameters of the TSINTSN is voluntary. The procedure for this demonstration shall be: It is recommended that this voluntary procedure is carried out according with Commission Recommendation 2014/881/EU of 18 November 2014.

### 7.4. Application of this TSINTSN to existing platforms

In case of upgrade or renewal of the infrastructure subsystem, the following conditions related to platform height governed by point 4.2.9.2 of this TSINTSN, shall apply:

(a) It shall be allowed to apply other nominal platform heights for consistency with a particular upgrade or renewal programme of a line or a section of a line.

(b) It shall be allowed to apply other nominal platform heights, if the work requires structural alterations to any load bearing element.

### 7.5. Speed as an implementation criterion

(1) It is permissible to bring a line into service as an interoperable line at a lower speed than its intended ultimate line speed. However, when it is the case the line should not be constructed in a way that inhibits future adoption of the intended ultimate line speed.

(2) For example the distance between track centres shall be suitable for the intended ultimate line speed but the cant will need to be appropriate to the speed at the time the line is brought into service.

(3) Requirements for assessment of conformity in this case are set out in section 6.3.

---

### 7.6. Route compatibility checks before the use of authorised vehicles

The procedure to be applied and the parameters of the infrastructure subsystem to be used by the railway undertaking, for the purpose of route compatibility check are described in point 4.2.2.5. and appendix D1 of the Annex to Commission Implementing Regulation (EU) 2019/773.

### 7.7. UK Specific cases

The following UK specific cases may be applied on particular networks. The UK specific cases are classified as:

(a) **‘P’ cases**: permanent cases;

(b) **‘T’ cases**: temporary cases (note that there are no T cases for the UK). Where it is recommended that the target system is reached by 2020 (an objective set out in Decision No 1692/96/EC of the European Parliament and Council).

All specific cases and their relevant dates shall be re-examined in the course of future revisions of the NTSNTSI with a view to limiting their technical and geographical scope based on an assessment of their impact on safety, interoperability, cross border services, TEN-T corridors, and the practical and economic impacts of retaining or eliminating them. Special account shall be given to availability of EU funding.

Specific cases shall be limited to the route or network where they are strictly necessary and taken account of through route compatibility procedures.

### 7.7.1. Platform height (4.2.9.2)

**P cases**

For other parts of the Union rail network as set out in Article 2(4) of this Regulation, for renewal and upgrading, the nominal platform height of 380 mm above the running surface shall be allowed.

### 7.7.2. Platform offset (4.2.9.3)

The provision has been left intentionally blank.

---

P cases

For platform heights of 550 mm and 760 mm, the conventional value $b_{0}$ of platform offset shall be calculated according to the following formulas:

$$b_{0} = 1650 + \frac{5000}{R} \quad \text{In curve with a radius } 1000 \leq R \leq \infty \text{ (m)}$$

$$b_{0} = 1650 + \frac{26470}{R} - 21,5 \quad \text{In curve with a radius } R < 1000 \text{ (m)}$$

7.7.3. This provision has been left intentionally blank

Particular features on the Bulgarian network

7.7.3.1. Platform height (4.2.9.2)

P cases

For upgraded or renewed platforms, the nominal platform height of 300 mm and 1 100 mm above the running surface shall be allowed.

7.7.3.2. Platform offset (4.2.9.3)

P cases

Instead of points 4.2.9.3(1) and 4.2.9.3(2), the platform offset shall be:

(a) 1 650 mm for platforms with heights of 300 mm and
(b) 1 750 mm for platforms with height of 1 100 mm.

7.7.4. This provision has been left intentionally blank

Particular features on the Danish network

7.7.4.1. Platform height (4.2.9.2)

P cases

For S-Tog services the nominal platform height of 920 mm above the running surface shall be allowed.

7.7.5. This provision has been left intentionally blank

Particular features on the Estonian network

7.7.5.1. Nominal track gauge (4.2.4.1)

P cases

Instead of point 4.2.4.1(2), for the 1 520 mm track gauge system the nominal track gauge shall be either 1 520 mm or 1 524 mm.

7.7.5.2. Resistance of new bridges to traffic loads (4.2.7.1)
**P-cases**

For the 1 520 mm track gauge system, for lines with an axle load of 30 t, it shall be allowed to design structures to support vertical loads in accordance with the load model set out in Appendix M to this TSI.

**7.7.5.3. The immediate action limit for switches and crossing (4.2.8.6)**

**P-cases**

Instead of sub-point 4.2.8.6(3)(a), for the 1 520 mm track gauge system, the minimum value of bypass at the narrowest location between open switch rail and stock rail is 54 mm.

**7.7.6. This provision has been left intentionally blank**

**Particular features on the Finnish network**

**7.7.6.1. TSI Categories of line (4.2.1)**

**P-cases**

Instead of gauges specified in the columns ‘Gauge’ in Table 2 and Table 3 of point 4.2.1(6), for the nominal track gauge of 1 524 mm, it shall be allowed to use gauge FIN1.

**7.7.6.2. Structure gauge (4.2.3.1)**

**P-cases**

(1) Instead of points 4.2.3.1(1) and 4.2.3.1(2), for the nominal track gauge of 1 524 mm, both the upper and lower part of the structure gauge shall be set on the basis of the gauge FIN1. Those gauges are defined in Annex D, section D.4.4 of EN 15273-3:2013.

(2) Instead of point 4.2.3.1(3), for the nominal track gauge of 1 524 mm, calculations of the structure gauge shall be done using the static method in accordance with the requirements of sections 5, 6, 10 and Annex D Section D.4.4 of EN 15273-3:2013.

**7.7.6.3. Distance between track centres (4.2.3.2)**

**P-cases**

(1) Instead of point 4.2.3.2(1), for the nominal track gauge of 1 524 mm, the distance between track centres shall be set on the basis of the gauge FIN1.

(2) Instead of point 4.2.3.2(2), for the nominal track gauge of 1 524 mm, the nominal horizontal distance between track centres for new lines shall be specified for the design and shall not be smaller than the values mentioned in Table 21; it considers margins for aerodynamic effects.

**Table 21**
### Minimum nominal horizontal distance between track centres

<table>
<thead>
<tr>
<th>Maximum allowed speed [km/h]</th>
<th>Minimum nominal horizontal distance between track centres [m]</th>
</tr>
</thead>
<tbody>
<tr>
<td>$v \leq 120$</td>
<td>4,10</td>
</tr>
<tr>
<td>$120 &lt; v \leq 160$</td>
<td>4,30</td>
</tr>
<tr>
<td>$160 &lt; v \leq 200$</td>
<td>4,50</td>
</tr>
<tr>
<td>$200 &lt; v \leq 250$</td>
<td>4,70</td>
</tr>
<tr>
<td>$v &gt; 250$</td>
<td>5,00</td>
</tr>
</tbody>
</table>

(3) Instead of point 4.2.3.2(3), for the nominal track gauge of 1 524 mm, the distance between track centres shall at least satisfy the requirements for the limit installation distance between track centres, defined according Annex D, Section D4.4.5 of EN 15273-3:2013.

#### 7.7.6.4. Minimum radius of horizontal curve (4.2.3.4)

**P cases**

Instead of point 4.2.3.4(3), for the nominal track gauge of 1 524 mm, reverse curves (other than reverse curves in marshalling yards where wagons are shunted individually) with radii in the range from 150 m up to 275 m for new lines shall be designed in accordance with Table 22 to prevent buffer locking.

**Table 22**

<table>
<thead>
<tr>
<th>Limits for the length of a straight intermediate element between two long circular curves in the opposite directions [m] (9)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Alignment chain (9)</td>
</tr>
<tr>
<td>$R = 150$ m — straight — $R = 150$ m</td>
</tr>
<tr>
<td>$R = 160$ m — straight — $R = 160$ m</td>
</tr>
<tr>
<td>$R = 170$ m — straight — $R = 170$ m</td>
</tr>
<tr>
<td>$R = 180$ m — straight — $R = 180$ m</td>
</tr>
<tr>
<td>$R = 190$ m — straight — $R = 190$ m</td>
</tr>
<tr>
<td>$R = 200$ m — straight — $R = 200$ m</td>
</tr>
<tr>
<td>$R = 210$ m — straight — $R = 210$ m</td>
</tr>
<tr>
<td>$R = 220$ m — straight — $R = 220$ m</td>
</tr>
<tr>
<td>$R = 230$ m — straight — $R = 230$ m</td>
</tr>
<tr>
<td>$R = 240$ m — straight — $R = 240$ m</td>
</tr>
<tr>
<td>$R = 250$ m — straight — $R = 250$ m</td>
</tr>
</tbody>
</table>
7.7.6.5. Nominal track gauge (4.2.4.1)

P cases
Instead of point 4.2.4.1(1), the nominal track gauge shall be 1 524 mm.

7.7.6.6. Cant (4.2.4.2)

P cases

(1) Instead of point 4.2.4.2(1), for the nominal track gauge of 1 524 mm, the design cant shall not exceed 180 mm for ballasted or non-ballasted track.

(2) Instead of point 4.2.4.2(3), for the nominal track gauge of 1 524 mm, new lines with mixed or freight traffic on curves with a radius less than 320 m and a cant transition steeper than 1 mm/m, the cant shall be restricted to the limit given by the following formula

\[ D \leq (R - 50) \times 0.7 \]

where \( D \) is the cant in mm and \( R \) is the radius in m.

7.7.6.7. Maximum unguided length of fixed obtuse crossings (4.2.5.3) P cases

In paragraph (1) of Appendix J, for the nominal track gauge of 1 524 mm:

(a) Instead of subparagraph (J.1)(b), the minimum radius through obtuse crossing shall be 200 m; for radius between 200-220 m small radius shall be compensated with track gauge widening

(b) Instead of subparagraph (J.1)(c), the minimum check rail height shall be 39 mm

7.7.6.8. The immediate action limit of track gauge as an isolated defect (4.2.8.4)

P cases

Instead of point 4.2.8.4(1), for the nominal track gauge of 1 524 mm, the immediate action limits of track gauge as an isolated defect are set out in Table 23.

<table>
<thead>
<tr>
<th>Speed [km/h]</th>
<th>Minimum track gauge</th>
<th>Maximum track gauge</th>
</tr>
</thead>
</table>
7.7.6.9. The immediate action limit of cant (4.2.8.5)

P cases

Instead of point 4.2.8.5(1), for the nominal track gauge of 1 524 mm, the maximum cant allowed in service is 190 mm.

7.7.6.10. The immediate action limits for switches and crossings (4.2.8.6)

P cases

Instead of point 4.2.8.6(1), for the nominal track gauge of 1 524 mm, the technical characteristics of switches and crossings shall comply with the following in-service values:

(a) Maximum value of free wheel passage in switches: 1 469 mm.
   This value can be increased if the Infrastructure Manager demonstrates that the actuation and locking system of the switch is able to resist the lateral impact forces of a wheel set.

(b) Minimum value of fixed nose protection for common crossings: 1 476 mm.
   This value is measured 14 mm below the running surface, and on the theoretical reference line, at an appropriate distance back from the actual point (RP) of the nose as indicated in Figure 2.
   For crossings with point retraction, this value can be reduced. In this case the Infrastructure Manager shall demonstrate that the point retraction is sufficient to guarantee that the wheel will not hit the nose at the actual point (RP).

(c) Maximum value of free wheel passage at crossing nose: 1 440 mm.

(d) Maximum value of free wheel passage at check rail/wing rail entry: 1 469 mm.

(e) Minimum flangeway width: 42 mm.

(f) Minimum flangeway depth: 40 mm.

(g) Maximum excess height of check rail: 55 mm.

7.7.6.11. Platform offset (4.2.9.3)

P cases

| v ≤ 60  | 1 515 | 1 554 |
| 60 < v ≤ 120 | 1 516 | 1 552 |
| 120 < v ≤ 160 | 1 517 | 1 547 |
| 160 < v ≤ 200 | 1 518 | 1 543 |
| 200 < v ≤ 250 | 1 519 | 1 539 |
| v > 250 | 1 520 | 1 539 |
Instead of point 4.2.9.3(1), for the nominal track gauge of 1 524 mm, the distance between the track centre and the platform edge, parallel to the running plane, shall be set on the basis of the installation limit gauge and is defined in chapter 13 of EN 15273-3:2013. The installation limit gauge shall be set on the basis of the gauge FIN1. The minimum distance of \( b_{qlim} \), calculated as in chapter 13 of EN15273-3:2013 is hereafter referred to as \( b_{qlim} \).

7.7.6.12. Train external cleaning facilities (4.2.12.3)

\textbf{P cases}

Instead of point 4.2.12.3(1), for the nominal track gauge of 1 524 mm, where a washing plant is provided it shall be able to clean the outer sides of single or double-deck trains between a height of:

(a) 330 to 4 367 mm for a single-deck train,
(b) 330 to 5 300 mm for double-deck trains.

7.7.6.13. Assessment of structure gauge (6.2.4.1)

\textbf{P cases}

Instead of point 6.2.4.1(1), for the nominal track gauge of 1 524 mm, assessment of structure gauge as a design review shall be done against characteristic cross sections using the results of calculations made by the Infrastructure Manager or the contracting entity on the basis of sections 5, 6, 10 and Annex D, Section D.4.4 of EN 15273-3:2013.

7.7.7. \textit{This provision has been left intentionally blank}

\textbf{Particular features on the French network}

7.7.7.1. Platform height (4.2.9.2)

\textbf{P cases}

For the rail network of Ile-de-France the nominal platform height of 920 mm above the running surface shall be allowed.

7.7.8. \textit{This provision has been left intentionally blank}

\textbf{Particular features on the German network}

7.7.8.1. Platform height (4.2.9.2)

\textbf{P cases}

For S-Bahn services the nominal platform height of 960 mm above the running surface shall be allowed.
7.7.9. *This provision has been left intentionally blank*

**Particular features on the Hellenic network**

7.7.9.1. Platform height (4.2.9.2)

P cases

The nominal platform height shall be allowed to be 300 mm above the running surface.

7.7.10. *This provision has been left intentionally blank*  

**Particular features on the Italian network**

7.7.10.1. Platform offset (4.2.9.3)

P cases

Instead of point 4.2.9.3(1), for the platforms with the height of 550 mm, the distance $b_{qlim}$ [mm], between the the track centre and the platform edge, parallel to the running plane, shall be calculated from the formula:

(a) on straight track and inside the curves:

$$b_{qlim} = 1650 + 3750/R + (g - 1435)/2 + 11.5$$

(b) outside the curves:

$$b_{qlim} = 1650 + 3750/R + (g - 1435)/2 + 11.5 + 220 \times \tan \delta$$

where $R$ is the radius of the track, in metres, $g$ is the track gauge, $\delta$ is the angle of the cant with the horizontal line.

7.7.10.2. Equivalent conicity (4.2.4.5)

P cases

(1) Instead of point 4.2.4.5(3) design values of track gauge, rail head profile and rail inclination for plain line shall be selected to ensure that the equivalent conicity limits set out in Table 24 are not exceeded.

<table>
<thead>
<tr>
<th>Wheel profile</th>
<th>$S1002$, GV1/40</th>
<th>EPS</th>
</tr>
</thead>
<tbody>
<tr>
<td>Speed range [km/h]</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$v \leq 60$</td>
<td>Assessment not required</td>
<td></td>
</tr>
<tr>
<td>$60 &lt; v \leq 200$</td>
<td>0.25</td>
<td>0.30</td>
</tr>
<tr>
<td>$200 &lt; v \leq 280$</td>
<td>0.20</td>
<td>N.A.</td>
</tr>
</tbody>
</table>
Instead of point 4.2.4.5. (4) the following wheelsets shall be modelled passing over the designed track conditions (simulated by calculation according to EN 15302:2008+A1:2010):


For SR1 and SR2 the following values apply:

(f) For the 1 435 mm track gauge system SR1 = 1 420 mm and SR2 = 1 426 mm.

7.7.10.3. Equivalent conicity in service (4.2.11.2)

P cases

Instead of point 4.2.11.2.(2) the infrastructure manager shall measure the track gauge and the railhead profiles at the site in question at a distance of approximate 10 m. The mean equivalent conicity over 100 m shall be calculated by modelling with the wheelsets (a) — (e) mentioned in paragraph 7.7.10.2 (2) of this TSI in order to check for compliance, for the purpose of the joint investigation, with the limit equivalent conicity for the track specified in Table 14.

7.7.11. This provision has been left intentionally blank Particular features on the Latvian network

7.7.11.1. Resistance of new bridges to traffic loads — vertical loads (4.2.7.1.1)

P cases

(1) For sub-point 4.2.7.1.1(1)(a), for the 1 520 mm track gauge system, load model 71 shall be applied with a distributed load qvk of 100 kN/m.

(2) Instead of point 4.2.7.1.1(3), for the 1 520 mm track gauge system, the value of factor alpha (α) shall in all cases be equal to 1.46.

7.7.12. This provision has been left intentionally blank Particular features on the Polish network

7.7.12.1. TSI Categories of line (4.2.1)

P cases
In point 4.2.1(7), Table 2 line P3, instead of gauge DE3, on upgraded or renewed railway lines in Poland gauge G2 is allowed.

7.7.12.2—Distance between track centres (4.2.3.2)

P cases
Instead of point 4.2.3.2(4), for 1 520 mm track gauge, for station tracks for direct reloading of goods from wagon to wagon the nominal horizontal minimum distance of 3,60 m shall be allowed.

7.7.12.3—Minimum radius of horizontal curve (4.2.3.4)

P cases
Instead of point 4.2.3.4(3), for the 1 520 mm track gauge, on tracks other than main tracks, reverse curves with radii in the range from 150 m up to 250 m shall be designed with a section of straight track of at least 10 m between the curves.

7.7.12.4—Minimum radius of vertical curve (4.2.3.5)

P cases
Instead of point 4.2.3.5(3), for the 1 520 mm track gauge, the radius of vertical curves (except the marshalling yards) shall be at least 2 000 m both on a crest and in a hollow.

7.7.12.5—Cant deficiency (4.2.4.3)

P cases
Instead of point 4.2.4.3(3), for all types of rolling stock of the 1 520 mm track gauge the cant deficiency shall not exceed 130 mm.

7.7.12.6—Abrupt change of cant deficiency (4.2.4.4)

P cases
Instead of point 4.2.4.4(3), for 1 520 mm track gauge, requirements of points 4.2.4.4(1) and 4.2.4.4(2) shall be applied.

7.7.12.7—The immediate action limit for track twist (4.2.8.3)

P cases
Instead of point 4.2.8.3(4) and 4.2.8.3(5), for 1 520 mm track gauge points from 4.2.8.3(1) to 4.2.8.3(3) shall be applied.

7.7.12.8—The immediate action limit of track gauge as an isolated defect (4.2.8.4)

P cases
Instead of requirements of Table 13 in point 4.2.8.4(2) the limit values for 1 520 mm track gauge in Poland are given in following table:

**Table 25**

Immediate action limits of track gauge for 1 520 mm track gauge in Poland

<table>
<thead>
<tr>
<th>Speed [km/h]</th>
<th>Minimum track gauge [mm]</th>
<th>Maximum track gauge [mm]</th>
</tr>
</thead>
<tbody>
<tr>
<td>&lt; 50</td>
<td>1 511</td>
<td>1 548</td>
</tr>
<tr>
<td>50 ≤ v ≤ 140</td>
<td>1 512</td>
<td>1 548</td>
</tr>
<tr>
<td>v &gt; 140</td>
<td>1 512</td>
<td>1 536</td>
</tr>
</tbody>
</table>

7.7.12.9. The immediate action limits for switches and crossings (4.2.8.6)

**P cases**

(1) Instead of sub-point 4.2.8.6(1)(d), for certain types of switches of R = 190 m and crossings with slants of 1:9 and 1:4, the maximum value of free wheel passage at check rail/wing rail entry of 1 385 mm shall be allowed.

(2) Instead of point 4.2.8.6(3), for the 1 520 mm track gauge the technical characteristics of switches and crossings shall comply with the following in-service values:

(a) Maximum value of free wheel passage in switches: 1 460 mm.

This value can be increased if the Infrastructure Manager demonstrates that the actuation and locking system of the switch is able to resist the lateral impact forces of a wheelset.

(b) Minimum value of fixed nose protection for common crossings: 1 472 mm.

This value is measured 14 mm below the running surface, and on the theoretical reference line, at an appropriate distance back from the actual point (RP) of the nose as indicated in Figure 2.

For crossings with point retraction, this value can be reduced. In this case the Infrastructure Manager shall demonstrate that the point retraction is sufficient to guarantee that the wheel will not hit the nose at the actual point (RP).

(c) Maximum value of free wheel passage at crossing nose: 1 436 mm.

(d) Minimum flangeway width: 38 mm.

(e) Minimum flangeway depth: 40 mm.

(f) Maximum excess height of check rail: 55 mm.

7.7.12.10. Platform height (4.2.9.2)
**P-cases**

(1) For platforms used for urban or suburban railway services the nominal platform height of 960 mm above running surface shall be allowed.

(2) For upgraded or renewed lines with maximum speed of no more than 160 km/h the nominal platform height from 220 mm to 380 mm above running surface shall be allowed.

**7.7.12.11. Equivalent conicity in service (4.2.11.2)**

**T-cases**

Until introduction of equipment for measurement of elements required for calculation of equivalent conicity in service, it is allowed in Poland not to assess this parameter.

**7.7.12.12. Track sleepers (5.3.3)**

**P-cases**

The requirement of point 5.3.3(2) shall be applied for speeds above 250 km/h.

**7.7.13. This provision has been left intentionally blank Particular features on the Portuguese network**

**7.7.13.1. Structure gauge (4.2.3.1)**

**P-cases**

(1) Instead of point 4.2.3.1(1), for the nominal track gauge of 1668 mm, the upper part of the structure gauge shall be set on the basis of the gauges set out in Table 26 and Table 27, which are defined in Annex D Section D.4.3 of EN 15273-3:2013.

**Table 26**

<table>
<thead>
<tr>
<th>Traffic code</th>
<th>Gauge</th>
</tr>
</thead>
<tbody>
<tr>
<td>P1</td>
<td>PTc</td>
</tr>
<tr>
<td>P2</td>
<td>PTb+</td>
</tr>
<tr>
<td>P3</td>
<td>PTc</td>
</tr>
<tr>
<td>P4</td>
<td>PTb+</td>
</tr>
<tr>
<td>P5</td>
<td>PTb</td>
</tr>
<tr>
<td>P6</td>
<td>PTb</td>
</tr>
</tbody>
</table>
(2) Instead of point 4.2.3.1(2), for the nominal track gauge of 1,668 mm the lower part of the structure gauge shall be in accordance with Annex D Section D.4.3.4 of EN 15273-3:2013.

(3) Instead of point 4.2.3.1(3), for the nominal track gauge of 1,668 mm, calculations of the structure gauge shall be done using the kinematic method in accordance with the requirements of Annex D Section D.4.3 of EN 15273-3:2013.

### 7.7.13.2. Distance between track centres (4.2.3.2)

**P cases**

Instead of point 4.2.3.2(1), for the nominal track gauge of 1,668 mm, the distance between track centres shall be set on the basis of the reference contours PTb, PTb+ or PTc, which are defined in Annex D Section D.4.3 of EN 15273-3:2013.

### 7.7.13.3. The immediate action limit of track gauge as an isolated defect (4.2.8.4)

**P cases**

Instead of point 4.2.8.4(1), for the nominal track gauge of 1,668 mm, the immediate action limits of track gauge as an isolated defect are set out in Table 28.

#### Table 28

<table>
<thead>
<tr>
<th>Speed [km/h]</th>
<th>Minimum track gauge</th>
<th>Maximum track gauge</th>
</tr>
</thead>
<tbody>
<tr>
<td>( v \leq 120 )</td>
<td>1,657</td>
<td>1,703</td>
</tr>
<tr>
<td>( 120 &lt; v \leq 160 )</td>
<td>1,658</td>
<td>1,703</td>
</tr>
<tr>
<td>( 160 &lt; v \leq 230 )</td>
<td>1,661</td>
<td>1,696</td>
</tr>
</tbody>
</table>
7.7.13.4. The immediate action limit for switches and crossings (4.2.8.6)

P cases

Instead of point 4.2.8.6(1), for the nominal track gauge of 1 668 mm, the technical characteristics of switches and crossings shall comply with the following in-service values:

(a) Maximum value of free wheel passage in switches: 1 618 mm. This value can be increased if the Infrastructure Manager demonstrates that the actuation and locking system of the switch is able to resist the lateral impact forces of a wheelset.

(b) Minimum value of fixed nose protection for common crossings: 1 625 mm. This value is measured 14 mm below the running surface, and on the theoretical reference line, at an appropriate distance back from the actual point (RP) of the nose as indicated in Figure 2.

For crossings with point retraction, this value can be reduced. In this case the Infrastructure Manager shall demonstrate that the point retraction is sufficient to guarantee that the wheel will not hit the nose at the actual point (RP).

(c) Maximum value of free wheel passage at crossing nose: 1 590 mm.

(d) Maximum value of free wheel passage at check rail/wing rail entry: 1 618 mm.

(e) Minimum flangeway width: 38 mm.

(f) Minimum flangeway depth: 40 mm.

(g) Maximum excess height of check rail: 70 mm.

7.7.13.5. Platform height (4.2.9.2)

P cases

For the nominal track gauge of 1 668 mm, for upgraded or renewed platforms the nominal platform height of 685 mm (general use) or 900 mm (urban and suburban traffic) above the running surface for radii of more than 300 m or 350 m respectively shall be allowed.

7.7.13.6. Platform offset (4.2.9.3)

P cases

(1) Instead of point 4.2.9.3(1), for the nominal track gauge of 1 668 mm, the distance between the track centre and the platform edge parallel to the running plane (bₚq), as defined in chapter 13 of EN 15273-3:2013, shall be set on the basis of the installation limit gauge (bₚlim). The installation limit gauge shall be calculated on
the basis of the gauge PTb+ defined in Annex D, Section D.4.3 of EN 15273-3:2013.

(2) For a three-rail track, the installation limit gauge shall be the outside envelope resultant from the overlaying of the installation gauge centred on the track gauge 1 668 mm, and the installation gauge set in 4.2.9.3(1) centred on the track gauge 1 435 mm.

7.7.13.7. Assessment of structure gauge (6.2.4.1)

**P cases**

Instead of point 6.2.4.1(1), for the nominal track gauge of 1 668 mm, assessment of structure gauge as a design review shall be done against characteristic cross sections using the results of calculations made by the Infrastructure Manager or the contracting entity on the basis of chapters 5, 7, 10 and section D.4.3 of EN 15273-3:2013.

7.7.13.8. Assessment of maximum pressure variations in tunnels (6.2.4.12)

**P cases**

Instead of point 6.2.4.12(3), for the nominal track gauge of 1 668 mm, the reference cross section area (constant along a train) to be considered is to be, independently to each motor or trailer vehicle:

(a) 12 m² for vehicles designed for PTc reference kinematic profile,
(b) 11 m² for vehicles designed for PTb and PTb+ reference kinematic profile.

The vehicle gauge to be considered shall be set on the basis of the gauge selected according to point 7.7.13.1.

7.7.14. **This provision has been left intentionally blank**

**Particular features on the Ireland network**

7.7.14.1. Structure gauge (4.2.3.1)

**P cases**

Instead of point 4.2.3.1(5), for the nominal track gauge of 1 600 mm, it shall be allowed to apply the uniform structure gauge IRL2 as set out in Appendix O to this TSI.

7.7.14.2. Distance between track centres (4.2.3.2)

**P cases**

Instead of point 4.2.3.2(6), for the 1 600 mm track gauge, the distance between track centres shall be set on the basis of the gauges selected according to point 7.7.14.1. The nominal horizontal distance between track centres shall be specified for the
design and shall not be less than 3.47 m for gauge IRL2; it considers margins for aerodynamic effects.

7.7.14.3. Assessment of structure gauge (6.2.4.1)

P cases

Instead of point 6.2.4.1(5), for the 1600 mm track gauge, assessment of structure gauge as a design review is to be made against characteristic cross-sections using the structure gauge ‘IRL2’ as defined in Appendix O to this TSI.

7.7.15. This provision has been left intentionally blank

Particular features on the Spanish network

7.7.15.1. Structure gauge (4.2.3.1)

P cases

(1) Instead of point 4.2.3.1(1), for the nominal track gauge of 1668 mm, the upper part of the structure gauge for new lines shall be set on the basis of the gauges set out in Table 29 and Table 30 which are defined in Annex D, Section D.4.11 of EN 15273-3:2013.

### Table 29

Gauges for passenger traffic on the Spanish network

<table>
<thead>
<tr>
<th>Traffic code</th>
<th>Gauge of upper parts</th>
</tr>
</thead>
<tbody>
<tr>
<td>P1</td>
<td>GEC16</td>
</tr>
<tr>
<td>P2</td>
<td>GEB16</td>
</tr>
<tr>
<td>P3</td>
<td>GEC16</td>
</tr>
<tr>
<td>P4</td>
<td>GEB16</td>
</tr>
<tr>
<td>P5</td>
<td>GEB16</td>
</tr>
<tr>
<td>P6</td>
<td>GHE16</td>
</tr>
</tbody>
</table>

### Table 30

Gauges for freight traffic on the Spanish network

<table>
<thead>
<tr>
<th>Traffic code</th>
<th>Gauge of upper parts</th>
</tr>
</thead>
<tbody>
<tr>
<td>F1</td>
<td>GEC16</td>
</tr>
<tr>
<td>F2</td>
<td>GEB16</td>
</tr>
</tbody>
</table>
For renewed or upgraded lines the upper part of the structure gauge shall be set on the basis of the gauge GHE16 which is defined in Annex D, Section D.4.11 of EN 15273-3:2013.

(2) Instead of point 4.2.3.1(2), for the nominal track gauge of 1,668 mm the lower part of the structure gauge shall be GE12 as set out in Appendix P to this TSI. Where tracks are equipped with rail brakes, structure gauge GE11 shall be applied for the lower part of the gauge, as set out in Appendix P to this TSI.

(3) Instead of point 4.2.3.1(3), for the nominal track gauge of 1,668 mm calculations of the structure gauge shall be done using the kinematic method in accordance with the requirements of Annex D, Section D.4.11 of EN 15273-3:2013 for the upper parts and Appendix P to this TSI for the lower parts.

7.7.15.2. Distance between track centres (4.2.3.2)

P cases

Instead of point 4.2.3.2(1), for the nominal track gauge of 1,668 mm, the distance between track centres shall be set on the basis of gauges of upper parts GHE16, GEB16 or GEC16, which are defined in Annex D, Section D.4.11 of EN 15273-3:2013.

7.7.15.3. Design track twist due to rail traffic actions (4.2.7.1.6)

P cases

Instead of point 4.2.7.1.6, for the nominal track gauge of 1,668 mm, the maximum total design track twist due to rail traffic actions shall not exceed 8 mm/3 m.

7.7.15.4. The immediate action limit of track gauge as an isolated defect (4.2.8.4)

P cases

Instead of point 4.2.8.4(1), for the nominal track gauge of 1,668 mm, the immediate action limits of track gauge as an isolated defect are set out in Table 31.

<table>
<thead>
<tr>
<th>Table 31</th>
</tr>
</thead>
<tbody>
<tr>
<td>Immediate action limits of 1,668 mm track gauge</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Speed [km/h]</th>
<th>Minimum track gauge</th>
<th>Maximum track gauge</th>
</tr>
</thead>
<tbody>
<tr>
<td>v ≤ 80</td>
<td>1,659</td>
<td>1,698</td>
</tr>
<tr>
<td>80 &lt; v ≤ 120</td>
<td>1,659</td>
<td>1,691</td>
</tr>
<tr>
<td>120 &lt; v ≤ 160</td>
<td>1,660</td>
<td>1,698</td>
</tr>
</tbody>
</table>
7.7.15.5. The immediate action limits for switches and crossings (4.2.8.6)

P cases

Instead of point 4.2.8.6(1), for the nominal track gauge of 1 668 mm, the technical characteristics of switches and crossings shall comply with the following in-service values:

(a) Maximum value of free wheel passage in switches: 1 618 mm.

This value can be increased if the Infrastructure Manager demonstrates that the actuation and locking system of the switch is able to resist the lateral impact forces of a wheelset.

(b) Minimum value of fixed nose protection for common crossings: 1 626 mm.

This value is measured 14 mm below the running surface, and on the theoretical reference line, at an appropriate distance back from the actual point (RP) of the nose as indicated in Figure 2.

For crossings with point retraction, this value can be reduced. In this case the Infrastructure Manager shall demonstrate that the point retraction is sufficient to guarantee that the wheel will not hit the nose at the actual point (RP).

(c) Maximum value of free wheel passage at crossing nose: 1 590 mm.

(d) Maximum value of free wheel passage at check rail/wing rail entry: 1 620 mm.

(e) Minimum flangeway width: 38 mm.

(f) Minimum flangeway depth: 40 mm.

(g) Maximum height of check rail: 70 mm.

7.7.15.6. Platform height (4.2.9.2)

P cases

The nominal platform height dedicated for:

(a) commuter or regional traffic or

(b) commuter and long-distance traffic

(c) regional traffic and long-distance traffic
stopping in normal service, shall be allowed to be 680 mm for radii of 300 m and more above the running surface.

7.7.15.7. Platform offset (4.2.9.3)

P cases

(1) Instead of point 4.2.9.3(1), for the nominal track gauge of 1668 mm, the distance between the track centre and the platform edge, parallel to the running plane \( (b_q) \), as defined in chapter 13 of EN 15273-3:2013, shall be set on the basis of the installation limit gauge \( (b_{qlim}) \). The installation limit gauge shall be calculated on the basis of the gauges of upper parts GHE16 or GEC16 defined in Annex D, Section D.4.11 of EN 15273-3:2013.

(2) For a three-rail track, the installation limit gauge shall be the outside envelope resultant from the overlaying of the installation limit gauge centred on the track gauge 1668 mm, and the installation limit gauge set in 4.2.9.3(1) centred on the track gauge 1435 mm.

7.7.15.8. Assessment of structure gauge (6.2.4.1)

P cases

Instead of point 6.2.4.1(1), for the nominal track gauge of 1668 mm, assessment of structure gauge as a design review shall be done against characteristic cross sections using the results of calculations made by the Infrastructure Manager or the contracting entity on the basis of chapters 5, 7, 10 and Annex D, Section D.4.11 of EN 15273-3:2013 for the upper parts and Appendix P to this TSI for the lower parts.

7.7.15.9. Assessment of maximum pressure variations in tunnels (6.2.4.12)

P cases

Instead of point 6.2.4.12(3), for the nominal track gauge of 1668 mm, the reference cross section area to be considered is to be, independently to each motor or trailer vehicle:

(a) \( 12 \text{ m}^2 \) for vehicles designed for GEC16 reference kinematic profile,
(b) \( 11 \text{ m}^2 \) for vehicles designed for GEB16, and GHE16 reference kinematic profile.

The vehicle gauge to be considered shall be set on the basis of the gauge selected according to point 7.7.15.1.

7.7.16. This provision has been left intentionally blank Particular features on the Swedish network

7.7.16.1. General

P cases
On infrastructure with direct connection to the Finnish network and for infrastructure in harbours, the particular features of the Finnish network as specified in point 7.7.6 of this TSI may be applied on tracks, which are dedicated for 1524 mm nominal track gauge vehicles.

7.7.16.2. Platform offset (4.2.9.3)

P cases

As set out in point 4.2.9.3(1), the distance between the track centre and the platform edge parallel to the running plane (bq), as defined in chapter 13 of EN 15273-3:2013, shall be calculated with the following values for allowed additional overthrow (Skin):

(a) on the inside of the curve: Skin = 40,5/R,
(b) on the outside of the curve: Skin = 31,5/R.

7.7.17. Particular features on the UK network for Great Britain

7.7.17.1. TSINTSN categories of line (4.2.1)

P cases

(1) Where line speeds are stated in kilometres per hour [km/h] as a category or performance parameter in this TSINTSN, it shall be allowed to translate the speed to equivalent miles per hour [mph] as in Appendix G, for the United Kingdom national network in Great Britain.

(2) Instead of the column ‘Gauge’ in Table 2 and Table 3 of point 4.2.1(7), for the gauge of all lines except new, dedicated high speed lines of traffic code P1, it shall be allowed to use national technical rules as set out in Appendix Q.

7.7.17.2. Structure gauge (4.2.3.1)

P cases

Instead of point 4.2.3.1, for national gauges selected according to point 7.7.17.1(2), the structure gauge shall be set according to Appendix Q.

7.7.17.3. Distance between track centres (4.2.3.2)

P cases

(1) Instead of point 4.2.3.2, the nominal distance between track centres shall be 3400 mm on straight track and curved track with a radius of 400 m or greater.

(2) Where topographical constraints prevent a nominal distance of 3400 mm between track centres being achieved, it is permissible to reduce the distance between track centres provided special measures are put in place to ensure a safe passing clearance between trains.
Reduction in the distance between track centres shall be in accordance with the national technical rule set out in Appendix Q.

7.7.17.3.bis Equivalent conicity (4.2.4.5)

P cases

(1) Instead of point 4.2.4.5 (3) design values of track gauge, rail head profile and rail inclination for plain line shall be selected to ensure that the equivalent conicity limits set out in Table 32 are not exceeded.

<table>
<thead>
<tr>
<th>Speed range [km/h]</th>
<th>Wheel profile</th>
<th>S1002, GV1/40</th>
<th>EPS</th>
</tr>
</thead>
<tbody>
<tr>
<td>v ≤ 60</td>
<td>Assessment not required</td>
<td></td>
<td></td>
</tr>
<tr>
<td>60 &lt; v ≤ 200</td>
<td>0.25</td>
<td>0.30</td>
<td></td>
</tr>
<tr>
<td>200 &lt; v ≤ 280</td>
<td>0.20</td>
<td>0.20</td>
<td></td>
</tr>
<tr>
<td>v &gt; 280</td>
<td>0.10</td>
<td>0.15</td>
<td></td>
</tr>
</tbody>
</table>

(2) Instead of point 4.2.4.5. (4) the following wheelsets shall be modelled passing over the designed track conditions (simulated by calculation according to EN 15302:2008+A1:2010):


For SR1 and SR2 the following values apply:
(f) For the 1 435 mm track gauge system SR1 = 1 420 mm and SR2 = 1 426 mm.

7.7.17.4. Maximum unguided length of fixed obtuse crossings (4.2.5.3)

P cases

Instead of point 4.2.5.3, the design value of the maximum unguided length of fixed obtuse crossing shall be in accordance with the national technical rule set out in Appendix Q.

7.7.17.5. The immediate action limits for switches and crossings (4.2.8.6)

P cases
Instead of point 4.2.8.6(1)(b), for the ‘CEN56 Vertical’ design of switches and crossings, a minimum value of fixed nose protection for common crossings of 1 388 mm is allowed (measured 14 mm below the running surface, and on the theoretical reference line, at an appropriate distance back from the actual (RP) of the nose as indicated in Figure 2).

7.7.17.6. Platform height (4.2.9.2)

P cases
Instead of point 4.2.9.2, for platform height, national technical rules as set out in Appendix Q shall be allowed.

7.7.17.7. Platform offset (4.2.9.3)

P cases
Instead of point 4.2.9.3, for platform offset, national technical rules as set out in Appendix Q shall be allowed.

7.7.17.8. Equivalent conicity in service (4.2.11.2)

P cases
Instead of point 4.2.11.2.(2) the infrastructure manager shall measure the track gauge and the railhead profiles at the site in question at a distance of approximate 10 m. The mean equivalent conicity over 100 m shall be calculated by modelling with the wheelsets (a) — (e) mentioned in paragraph 7.7.17.3(2) of this TSINTSN in order to check for compliance, for the purpose of the joint investigation, with the limit equivalent conicity for the track specified in Table 14.

7.7.17.9. Assessment of structure gauge (6.2.4.1)

P cases
Instead of point 6.2.4.1, it shall be allowed to assess structure gauge in accordance with the national technical rules as set out in Appendix Q.

7.7.17.10. Assessment of distance between track centres (6.2.4.2)

P cases
Instead of point 6.2.4.2, it shall be allowed to assess distance between track centres in accordance with the national technical rules as set out in Appendix Q.

7.7.17.11. Assessment of platform offset (6.2.4.11)

P cases
Instead of point 6.2.4.11, it shall be allowed to assess platform offset in accordance with the national technical rules as set out in Appendix Q.
7.7.18.  Particular features on the UK network for Northern Ireland

7.7.18.1.  Structure gauge (4.2.3.1)

P cases
Instead of point 4.2.3.1(5), for the nominal track gauge of 1 600 mm, it shall be allowed to apply the uniform structure gauge IRL3 as set out in Appendix O to this TSI.

7.7.18.2.  Distance between track centres (4.2.3.2)

P cases
Instead of point 4.2.3.2(6), for the 1 600 mm track gauge, the distance between track centres shall be set on the basis of the gauges selected according to point 7.7.17.1. The nominal horizontal distance between track centres shall be specified for the design and shall consider margins for aerodynamic effects. The minimum allowed value for the uniform structure gauge IRL3 is an open point.

7.7.18.3.  Assessment of structure gauge (6.2.4.1)

P cases
Instead of point 6.2.4.1(5), for the 1 600 mm track gauge, assessment of structure gauge as a design review is to be made against characteristic cross sections using the structure gauge ‘IRL3’ as defined in Appendix O to this TSI.

7.7.19.  Particular features on the Slovak network

7.7.19.1.  TSI categories of line (4.2.1)

P cases
For the Traffic Code F1520 as defined in Table 3 of point 4.2.1(7), for the 1 520 mm track gauge system, it shall be allowed to use axle load 24.5 t and train length in the range from 650 m up to 1 050 m.

7.7.19.2.  Minimum radius of horizontal curve (4.2.3.4)

P cases
(1) Instead of point 4.2.3.4(2), reverse curves (other than reverse curves in marshalling yards where wagons are shunted individually) with radii in the range from 150 m up to 300 m for new lines shall be designed in accordance with Table 33 and Table 34 to prevent buffer locking.

(2) Instead of paragraph 4.2.3.4(3), for the 1 520 mm track gauge system, for main tracks, reverse curves with radii in the range from 150 m up to 250 m shall be designed with a section of straight track of at least 15 m between the curves.
Instead of point 4.2.3.4(3), for the 1 520 mm track gauge system, for tracks other than main tracks, reverse curves with radii in the range from 150 m up to 250 m shall be designed in accordance with Table 33 and Table 34.

**Table 33**

Limits for length of a straight intermediate element between two long circular curves in the opposite directions (m)

<table>
<thead>
<tr>
<th>$R_1/R_2$</th>
<th>150</th>
<th>160</th>
<th>170</th>
<th>180</th>
<th>190</th>
<th>200</th>
<th>220</th>
<th>230</th>
<th>250</th>
<th>280</th>
<th>300</th>
</tr>
</thead>
<tbody>
<tr>
<td>150</td>
<td>11,0</td>
<td>10,7</td>
<td>10,4</td>
<td>10,0</td>
<td>9,8</td>
<td>9,5</td>
<td>9,0</td>
<td>8,7</td>
<td>8,1</td>
<td>7,6</td>
<td>6,7</td>
</tr>
<tr>
<td>160</td>
<td>10,7</td>
<td>10,4</td>
<td>10,0</td>
<td>9,8</td>
<td>9,5</td>
<td>9,0</td>
<td>8,6</td>
<td>8,1</td>
<td>7,6</td>
<td>6,7</td>
<td>6,4</td>
</tr>
<tr>
<td>170</td>
<td>10,4</td>
<td>10,0</td>
<td>9,8</td>
<td>9,5</td>
<td>9,0</td>
<td>8,5</td>
<td>8,0</td>
<td>7,5</td>
<td>6,5</td>
<td>6,3</td>
<td>6,0</td>
</tr>
<tr>
<td>180</td>
<td>10,0</td>
<td>9,8</td>
<td>9,5</td>
<td>9,0</td>
<td>8,5</td>
<td>8,0</td>
<td>7,5</td>
<td>6,5</td>
<td>6,2</td>
<td>6,0</td>
<td>5,3</td>
</tr>
<tr>
<td>190</td>
<td>9,8</td>
<td>9,5</td>
<td>9,0</td>
<td>8,5</td>
<td>8,0</td>
<td>7,5</td>
<td>6,5</td>
<td>6,2</td>
<td>6,0</td>
<td>5,3</td>
<td>4,0</td>
</tr>
<tr>
<td>200</td>
<td>9,5</td>
<td>9,0</td>
<td>8,5</td>
<td>8,0</td>
<td>7,5</td>
<td>6,5</td>
<td>6,2</td>
<td>6,0</td>
<td>5,3</td>
<td>4,0</td>
<td>3,0</td>
</tr>
<tr>
<td>220</td>
<td>9,0</td>
<td>8,6</td>
<td>8,1</td>
<td>7,6</td>
<td>6,6</td>
<td>6,3</td>
<td>6,0</td>
<td>5,3</td>
<td>4,0</td>
<td>3,0</td>
<td>0,0</td>
</tr>
<tr>
<td>230</td>
<td>8,7</td>
<td>8,1</td>
<td>7,6</td>
<td>6,6</td>
<td>6,3</td>
<td>6,0</td>
<td>5,3</td>
<td>4,0</td>
<td>3,0</td>
<td>0,0</td>
<td></td>
</tr>
<tr>
<td>250</td>
<td>8,1</td>
<td>7,6</td>
<td>6,7</td>
<td>6,4</td>
<td>6,0</td>
<td>5,3</td>
<td>4,0</td>
<td>3,0</td>
<td>0,0</td>
<td></td>
<td></td>
</tr>
<tr>
<td>280</td>
<td>7,6</td>
<td>6,7</td>
<td>6,4</td>
<td>6,0</td>
<td>5,4</td>
<td>4,0</td>
<td>3,0</td>
<td>0,0</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>300</td>
<td>6,7</td>
<td>6,4</td>
<td>6,0</td>
<td>5,5</td>
<td>4,5</td>
<td>3,0</td>
<td>0,0</td>
<td></td>
<td></td>
<td></td>
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<tr>
<td>325</td>
<td>6,4</td>
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<td>5,7</td>
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<td>4,0</td>
<td>1,0</td>
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</tr>
<tr>
<td>350</td>
<td>6,3</td>
<td>5,9</td>
<td>5,2</td>
<td>4,0</td>
<td>3,0</td>
<td>1,0</td>
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<tr>
<td>400</td>
<td>6,0</td>
<td>5,2</td>
<td>4,0</td>
<td>3,0</td>
<td>0,0</td>
<td></td>
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<td></td>
</tr>
<tr>
<td>450</td>
<td>5,5</td>
<td>4,5</td>
<td>3,0</td>
<td>0,0</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>500</td>
<td>5,0</td>
<td>3,0</td>
<td>0,0</td>
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<td></td>
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<td></td>
<td></td>
</tr>
<tr>
<td>600</td>
<td>2,0</td>
<td>0,0</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
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<td></td>
</tr>
<tr>
<td>700</td>
<td>0,0</td>
<td></td>
<td></td>
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</tbody>
</table>

**Table 34**

Limits for length of a straight intermediate element between two long circular curves in the opposite directions (m); for passenger trains with speeds up to 40 km/h for other tracks than main tracks

<table>
<thead>
<tr>
<th>$R_1/R_2$</th>
<th>150</th>
<th>160</th>
<th>170</th>
<th>180</th>
<th>190</th>
<th>200</th>
<th>220</th>
<th>230</th>
<th>250</th>
</tr>
</thead>
<tbody>
<tr>
<td>150</td>
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<td></td>
<td></td>
<td></td>
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<td></td>
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<tr>
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<td></td>
<td></td>
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<tr>
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<tr>
<td>250</td>
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<td></td>
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</table>
### 7.7.19.3. Minimum radius of vertical curve (4.2.3.5)

**P-cases**

1. Instead of point 4.2.3.5(1), only for side track with maximum speed up to 10 km/h, the radius of vertical curves (except for humps in marshalling yards) shall be at least 500 m in both a crest and in a hollow.

2. Instead of point 4.2.3.5(3), for 1520 mm track gauge system, the radius of vertical curves (except the marshalling yards) shall be at least 2000 m both on a crest and in a hollow, in cramped conditions (e.g. insufficient space) at least 1000 m both on a crest and in hollow.

3. For side track with maximum speed up to 10 km/h, it shall be allowed to use the radius of vertical curves at least 500 m both on a crest and in a hollow.

4. Instead of point 4.2.3.5(4), for the 1520 mm track gauge system for humps in marshalling yards the radius of vertical curves shall be at least 300 m on a crest and 250 m in a hollow.

### 7.7.19.4. Cant deficiency (4.2.4.3)

**P-cases**

<table>
<thead>
<tr>
<th>Speed (km/h)</th>
<th>11.0</th>
<th>10.7</th>
<th>10.4</th>
<th>10.0</th>
<th>9.8</th>
<th>9.5</th>
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<th>8.1</th>
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<tr>
<td>160</td>
<td>10.7</td>
<td>10.4</td>
<td>10.0</td>
<td>9.8</td>
<td>9.5</td>
<td>9.0</td>
<td>8.7</td>
<td>8.1</td>
<td>7.6</td>
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<tr>
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<td>10.0</td>
<td>9.8</td>
<td>9.5</td>
<td>9.0</td>
<td>8.7</td>
<td>8.1</td>
<td>7.6</td>
<td>6.7</td>
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<td>9.5</td>
<td>9.0</td>
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<td>8.1</td>
<td>7.6</td>
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<td>6.2</td>
<td>6.0</td>
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<tr>
<td>280</td>
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<td>6.7</td>
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<td>5.4</td>
<td>4.0</td>
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<td>4.0</td>
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<td>4.0</td>
<td>4.0</td>
<td>4.0</td>
<td>4.0</td>
</tr>
</tbody>
</table>
Instead of point 4.2.4.3(3), for all types of rolling stock of the 1 520 mm track gauge system the cant deficiency shall not exceed 137 mm. For passenger traffic, this limit is valid for speeds up to 230 km/h. For mixed traffic, this limit is valid for speeds up to 160 km/h.

7.7.19.5. The immediate action limit for track twist (4.2.8.3)
P cases
Instead of point 4.2.8.3(4) and 4.2.8.3(5), for the 1 520 mm track gauge system, points from 4.2.8.3(1) to 4.2.8.3(3) shall be applied.

7.7.19.6. The immediate action limit of track gauge as an isolated defect (4.2.8.4)
P cases
Instead of point 4.2.8.4(2), for 1 520 mm track gauge system, the immediate action limits of track gauge as an isolated defects are set out in Table 35.

Table 35
Immediate action limits of track gauge for 1 520 mm track gauge system in Slovak republic

<table>
<thead>
<tr>
<th>Speed [km/h]</th>
<th>Minimum track gauge</th>
<th>Maximum track gauge</th>
</tr>
</thead>
<tbody>
<tr>
<td>v ≤ 80</td>
<td>1 511</td>
<td>1 555</td>
</tr>
<tr>
<td>80 &lt; v ≤ 120</td>
<td>1 512</td>
<td>1 550</td>
</tr>
<tr>
<td>120 &lt; v ≤ 160</td>
<td>1 513</td>
<td>1 545</td>
</tr>
<tr>
<td>160 &lt; v ≤ 230</td>
<td>1 514</td>
<td>1 540</td>
</tr>
</tbody>
</table>

7.7.19.7. The immediate action limit for cant (4.2.8.5)
P cases
Instead of point 4.2.8.5(3), for the 1 520 mm track gauge system, the maximum cant allowed in service is 170 mm.

7.7.19.8. The immediate action limits for switches and crossings (4.2.8.6)
P cases
Instead of point 4.2.8.6(3), for the 1 520 mm track gauge system, the technical characteristics of switches and crossings shall comply with the following in-service values:
(a) Minimum value of bypass at the narrowest location between open switch rail and stock rail is 60 mm.
(b) Minimum value of fixed nose protection for common crossings is 1,472 mm. This value is measured 14 mm below the running surface and on the theoretical reference line, at an appropriate distance back from the actual point (RP) of the nose as indicated in Figure 2. For crossings with point retraction, this value can be reduced. In this case the Infrastructure Manager shall demonstrate that the point retraction is sufficient to guarantee that the wheel will not hit the nose at the actual point (RP).

(c) Maximum value of free wheel passage at crossing nose is 1,436 mm

(d) Minimum flangeway width is 40 mm

(e) Minimum flangeway depth is 40 mm

(f) Maximum excess height of check rail is 54 mm

7.7.19.9. Platform height (4.2.9.2)

P cases

For renewed lines with maximum speed of no more than 120 km/h the nominal platform height shall be allowed from 200 mm to 300 mm above the running surface.

7.7.19.10. Equivalent conicity in service (4.2.11.2)

T cases

Until introduction of equipment for measurement of elements required for calculation of equivalent conicity in service, it is allowed in Slovak republic not to assess this parameter.

7.7.19.11. Track sleepers (5.3.3)

P cases

The requirement of point 5.3.3(2) shall be applied for speeds above 250 km/h.

7 (1) Axle load is based on design mass in working order for power heads (and for P2 locomotives) and operational mass under normal payload for vehicles capable of carrying a payload of passengers or luggage as defined in point 2.1 of EN 15663:2009+AC:2010. The corresponding ** axle load values for vehicles capable of carrying a payload for passengers or luggage are 31.5 t for P1 and 32.5 t for P2 as defined in Appendix K to this TSI.

8 (2) Axle load is based on design mass in working order for power heads and locomotives as defined in point 2.1 of EN 15663:2009+AC:2010 and design mass under exceptional payload for other vehicles as defined in Appendix K to this TSI.

9 (3) Axle load is based on design mass in working order for power heads and locomotives as defined in point 2.1 of EN 15663:2009+AC:2010 and design mass under exceptional payload for other vehicles as defined in Appendix K to this TSI.

12. (2) Commission Recommendation 2014/881/EU of 18 November 2014 on the procedure for demonstrating the level of compliance of existing railway lines with the basic parameters of the technical specifications for interoperability (See page 520 of this Official Journal).

Note: For reverse curves with different radii the radius of the smaller curve shall be used when designing straight element between the curves.
Appendix A

Assessment of interoperability constituents

The characteristics of the interoperability constituents to be assessed by the notified-approved body or the manufacturer in accordance with the selected module, in the different phases of design, development and production, are marked by ‘X’ in Table 36. Where no assessment is required, this is marked by ‘n.a.’ in the table.

There are no particular assessment procedures required for interoperability constituents of the infrastructure subsystem.

Table 36

Assessment of interoperability constituents for the ECUK declaration of conformity

<table>
<thead>
<tr>
<th>Characteristics to be assessed</th>
<th>Design review</th>
<th>Review of manufacturing process</th>
<th>Type test</th>
<th>Product quality (series)</th>
</tr>
</thead>
<tbody>
<tr>
<td>5.3.1 The rail</td>
<td>X</td>
<td>n.a.</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>5.3.1.1 Railhead profile</td>
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<td>n.a.</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>5.3.1.2 Rail steel</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>5.3.2 The rail fastening systems</td>
<td>n.a.</td>
<td>n.a.</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>5.3.3 Track sleepers</td>
<td>X</td>
<td>X</td>
<td>n.a.</td>
<td>X’</td>
</tr>
</tbody>
</table>
Appendix B

Assessment of the infrastructure subsystem

The characteristics of the subsystem to be assessed in the different phases of design, construction and operation are marked by ‘X’ in Table 37.

Where no assessment by an notified approved body is required, this is marked by ‘n.a.’ in the table. This does not prevent the need for other assessments to be performed in the framework of other phases.

Definition of assessment phases:

(1) ‘**Design review**’: it includes checking of correctness of values/parameters against applicable **TSIN** requirements related to the final design.

(2) ‘**Assembly before putting into service**’: checking on site that the actual product or subsystem complies with the relevant design parameters just before putting it into operation.

Column 3 gives references to point 6.2.4 ‘Particular assessment procedures for subsystem’ and to point 6.2.5 ‘Technical solutions giving presumption of conformity at design stage’.

### Table 37

Assessment of the infrastructure subsystem for the **ECUK** verification of conformity

<table>
<thead>
<tr>
<th>Characteristics to be assessed</th>
<th>New line or upgrading/renewal project</th>
<th>Particular assessment procedures</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Design review</td>
<td>Assembly before putting into service</td>
</tr>
<tr>
<td></td>
<td>1</td>
<td>2</td>
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<tr>
<td>Structure gauge (4.2.3.1)</td>
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<td>X</td>
</tr>
<tr>
<td>Distance between track centres (4.2.3.2)</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>Maximum gradients (4.2.3.3)</td>
<td>X</td>
<td>n.a.</td>
</tr>
<tr>
<td>Minimum radius of horizontal curve (4.2.3.4)</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>Minimum radius of vertical curve (4.2.3.5)</td>
<td>X</td>
<td>n.a.</td>
</tr>
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<td>Nominal track gauge (4.2.4.1)</td>
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<td>X</td>
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<td>Cant (4.2.4.2)</td>
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<td>Cant deficiency (4.2.4.3)</td>
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<td>Assessment of design values for equivalent conicity (4.2.4.5)</td>
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<td>6.2.4.6</td>
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<td>Railhead profile for plain line (4.2.4.6)</td>
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<td>Rail inclination (4.2.4.7)</td>
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<td>Design geometry of switches and crossings (4.2.5.1)</td>
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<td>Use of swing nose crossings (4.2.5.2)</td>
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<td>Maximum unguided length of fixed obtuse crossings (4.2.5.3)</td>
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<td>Track resistance to vertical loads (4.2.6.1)</td>
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<td>6.2.5</td>
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<tr>
<td>Longitudinal track resistance (4.2.6.2)</td>
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<td>6.2.5</td>
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<tr>
<td>Lateral track resistance (4.2.6.3)</td>
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<td>Resistance of new bridges to traffic loads (4.2.7.1)</td>
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<td>6.2.4.9</td>
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<tr>
<td>Equivalent vertical loading for new earthworks and earth pressure effects (4.2.7.2)</td>
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<td>6.2.4.9</td>
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<tr>
<td>Resistance of new structures over or adjacent to tracks (4.2.7.3)</td>
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<td>6.2.4.9</td>
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<td>Resistance of existing bridges and earthworks to traffic loads (4.2.7.4)</td>
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<tr>
<td>The immediate action limit for track twist (4.2.8.3)</td>
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<tr>
<td>The immediate action limit of track gauge as an isolated defect (4.2.8.4)</td>
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</tr>
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<td>The immediate action limit for cant (4.2.8.5)</td>
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<td>Platform offset (4.2.9.3)</td>
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<td>Track layout along platforms (4.2.9.4)</td>
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<td>Maximum pressure variation in tunnels (4.2.10.1)</td>
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<td>Effect of crosswinds (4.2.10.2)</td>
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<td>n.a.</td>
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<td>Train external cleaning facilities (4.2.12.3)</td>
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<td>Water restocking (4.2.12.4)</td>
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<td>Refuelling (4.2.12.5)</td>
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<td>Application of Interoperability Constituents</td>
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</tbody>
</table>
Appendix C

Technical characteristics of track design and switches and crossings design

Appendix C.1

Technical characteristics of track design

Track design shall be at least defined by the technical characteristics as follows:

(a) Rail
   — Profile(s) & grades
   — Continuous welded rail or length of rails (for jointed track sections)

(b) Fastening system
   — Type
   — Pad stiffness
   — Clamping force
   — Longitudinal restraint

(c) Sleeper
   — Type
   — Resistance to vertical loads:
     — Concrete: design bending moments
     — Wood: compliance to EN 13145:2001
     — Steel: moment of inertia of cross section
   — Resistance to longitudinal and lateral loads: geometry and weight
   — Nominal and design track gauge

(d) Rail inclination

(e) Ballast cross sections (ballast shoulder — ballast thickness)

(f) Ballast type (grading = granulometrie)

(g) Sleeper spacing

(h) Special devices: for example sleeper anchors, third/fourth rail, ...

Appendix C.2

Technical characteristics of switches and crossings design

Switches and crossings design shall be at least defined by the technical characteristics as follows:
(a) Rail
   — Profile(s) & grades (switch rail, stock rail)
   — Continuous welded rail or length of rails (for jointed track sections)
(b) Fastening system
   — Type
   — Pad stiffness
   — Clamping force
   — Longitudinal restraint
(c) Bearer
(d) Rail inclination
(e) Ballast cross sections (ballast shoulder — ballast thickness)
(f) Ballast type (grading = granulometrie)
(g) Type of crossing (fixed or movable point)
(h) Type of locking (switch pannel, movable point of crossing)
(i) Special devices: for example sleeper anchors, third/fourth rail, ...
(j) Generic switches and crossings drawing indicating
   — Geometrical diagram (triangle) describing the length of the turnout and the tangents at the end of the turnout
   — Main geometrical characteristics like the main radii in switch, closure and crossing panel, crossing angle
   — Sleeper spacing
Appendix D

Conditions of use of track design and switches and crossings design

Appendix D.1

Conditions of use of track design

Conditions of use of track design are defined to be as follows:

(a) Maximum axle load [t]
(b) Maximum line speed [km/h]
(c) Minimum horizontal curve radius [m]
(d) Maximum cant [mm]
(e) Maximum cant deficiency [mm]

Appendix D.2

Conditions of use of switches and crossings design

Conditions of use of switches and crossings design are defined to be as follows:

(a) Maximum axle load [t]
(b) Maximum line speed [km/h] on through route and diverging track of switches
(c) Rules for curved turnouts based on generic designs, giving minimum curvatures (for through route and diverging track of switches)
Appendix E

Capability requirements for structures according to traffic code

The minimum capability requirements for structures are defined in Table 38 and Table 39 according to the traffic codes given in Table 2 and Table 3. The capability requirements are defined in Table 38 and Table 39 by a combined quantity comprising of the EN line category and a corresponding maximum speed. The EN line category and associated speed shall be considered as a single combined quantity.

EN line category is a function of axle load and geometrical aspects relating to the spacing of axles. EN line categories are set out in Annex A of EN 15528:2015.

Table 38

<table>
<thead>
<tr>
<th>Traffic code</th>
<th>Passenger Carriages (including Coaches, Vans and Car Carriers) and Light Freight Wagons (±) (±)</th>
<th>Locomotives and Power Heads (±) (±)</th>
<th>Electric or Diesel Multiple Units, Power Units and Railcars (±) (±)</th>
</tr>
</thead>
<tbody>
<tr>
<td>P1</td>
<td>n.a. (±)</td>
<td>n.a. (±)</td>
<td>Open Point</td>
</tr>
<tr>
<td>P2</td>
<td>n.a. (±)</td>
<td>n.a. (±)</td>
<td>Open Point</td>
</tr>
</tbody>
</table>
| P3a (> 160 km/h) | A – 200  
B1 – 160                                         | D2 – 200 (±)                    | Open point                                        |
| P3b (≤ 160 km/h) | B1 – 160                                         | D2 – 160                        | C2 (±) – 160                                    |
|              |                                                 |                                 | D2 (±) – 120                                    |
| P4a (> 160 km/h) | A – 200  
B1 – 160                                         | D2 – 200 (±)                    | Open point                                        |
| P4b (≤ 160 km/h) | A – 160  
B1 – 140                                         | D2 – 160                        | B1 (±) – 160                                    |
|              |                                                 |                                 | C2 (±) – 140                                    |
|              |                                                 |                                 | D2 (±) – 120                                    |
| P5           | B1 – 120                                        | C2 – 120 (±)                    | B1 (±) – 120                                    |
| P6           | a12                                             |                                 |                                                   |
| P1520        | Open point                                      |                                 |                                                   |
| P1600        | Open point’                                     |                                 |                                                   |
Table 39

EN Line Category – Associated Speed \[1 \text{ (6)} \] [km/h] — Freight traffic

<table>
<thead>
<tr>
<th>Traffic code</th>
<th>Freight wagons and other vehicles</th>
<th>Locomotives (1)</th>
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</thead>
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<tr>
<td>F1</td>
<td>D4 – 120</td>
<td>D2 – 120</td>
</tr>
<tr>
<td>F2</td>
<td>D2 – 120</td>
<td>D2 – 120</td>
</tr>
<tr>
<td>F3</td>
<td>C2 – 100</td>
<td>C2 – 100</td>
</tr>
<tr>
<td>F4</td>
<td>B2 – 100</td>
<td>B2 – 100</td>
</tr>
<tr>
<td>F1520</td>
<td>Open point</td>
<td></td>
</tr>
<tr>
<td>F1600</td>
<td>Open point</td>
<td></td>
</tr>
</tbody>
</table>

(1) The indicated speed value in the table represents the maximum requirement for the line and may be lower in accordance with the requirements in point 4.2.1(12). When checking individual structures on the line, it is acceptable to take account of the type of vehicle and local allowed speed.

(2) Passenger Carriages (including Coaches, Vans, Car Carriers), Other Vehicles, Locomotives, Power Heads, Diesel and Electric Multiple Units, Power Units and Railcars are defined in the LOC & PAS NTNSNTSN. Light Freight Wagons are defined as vans except that they are allowed to be conveyed in formations which are not intended to convey passengers.

(3) The requirements for structures are compatible with Passenger Coaches, Vans, Car Carriers, Light Freight Wagons and vehicles in Diesel and Electric Multiple Units and Power Units with a length of; 18 m to 27.5 m for conventional and articulated vehicles and with a length of 9 m to 14 m for regular single axles.

(4) The requirements for structures are compatible with up to two adjacent coupled locomotives and/or power heads. The requirements for structures are compatible with a maximum speed of 120 km/h for three or more adjacent coupled locomotives and/or power heads (or a train of locomotives and/or power heads) subject to the locomotives and/or power heads satisfying the corresponding limits for freight wagons.

(5) For traffic code P5 the Member State Competent Authority may indicate whether the requirements for locomotives and power heads apply.

(6) When checking the compatibility of individual trains and structures, the basis of the compatibility check shall be in accordance with Appendix K to this TS4NTSN.

(7) The requirements for structures are compatible with an average mass per unit length over the length of each coach/vehicle of 2,75 t/m

(8) The requirements for structures are compatible with an average mass per unit length over the length of each coach/vehicle of 3,1 t/m

(9) Deleted.

(10) This footnote has been left intentionally blank
(11) Only 4 axle vehicles allowed. The spacing of the axles in a bogie shall be at least 2.6 m. The average mass per unit length over the length of the vehicle shall not exceed 5.0 t/m.

(12) Taking into account the state of art of operation there is no need to define harmonized requirements to deliver an adequate level of interoperability for this type of vehicles for P1 and P2 traffic codes.
Appendix F

Capability requirements for structures according to traffic code in the United Kingdom of Great Britain and Northern Ireland

The minimum capability requirements for structures are defined in Table 40 and Table 41 according to the traffic codes given in Table 2 and Table 3. The capability requirements are defined in Table 40 and Table 41 by a combined quantity comprising of the Route Availability number and a corresponding maximum speed. The Route Availability number and associated speed shall be considered as a single combined quantity.

The Route Availability number is a function of axle load and geometrical aspects relating to the spacing of axles. Route Availability numbers are defined in the national technical rules notified for this purpose.

Table 40

<table>
<thead>
<tr>
<th>Traffic code</th>
<th>Passenger Carriages (including Coaches, Vans and Car Carriers) and Light Freight Wagons ((\cdot) (\cdot))</th>
<th>Locomotives and Power Heads ((\cdot) (\cdot))</th>
<th>Electric or Diesel Multiple Units, Power Units and Railcars ((\cdot) (\cdot) (\cdot))</th>
</tr>
</thead>
<tbody>
<tr>
<td>P1</td>
<td>n.a. ((\cdot))</td>
<td>n.a. ((\cdot))</td>
<td>Open Point</td>
</tr>
<tr>
<td>P2</td>
<td>n.a. ((\cdot))</td>
<td>n.a. ((\cdot))</td>
<td>Open Point</td>
</tr>
<tr>
<td>P3a ((&gt; 160 \text{ km/h}))</td>
<td>RA1 – 125 RA2 – 90</td>
<td>RA7 – 125 RA8 – 110 RA8 – 100 RA5 – 125</td>
<td>Open point</td>
</tr>
<tr>
<td>P3b ((\leq 160 \text{ km/h}))</td>
<td>RA1 – 100 RA2 – 90</td>
<td>RA8 – 100 RA5 – 100</td>
<td>RA3 – 100</td>
</tr>
<tr>
<td>P4a ((&gt; 160 \text{ km/h}))</td>
<td>RA1 – 125 RA2 – 90</td>
<td>RA7 – 125 RA7 – 100 RA4 – 125</td>
<td>Open point</td>
</tr>
<tr>
<td>P4b ((\leq 160 \text{ km/h}))</td>
<td>RA1 – 100 RA2 – 90</td>
<td>RA7 – 100 RA4 – 100</td>
<td>RA3 – 100</td>
</tr>
<tr>
<td>P5</td>
<td>RA1 – 75</td>
<td>RA5 – 75 RA4 – 75</td>
<td>RA3 – 75</td>
</tr>
</tbody>
</table>
Table 41
Route Availability number — Associated Speed (1) (3) [miles per hour] — Freight traffic

<table>
<thead>
<tr>
<th>Traffic code</th>
<th>Freight wagons and other vehicles</th>
<th>Locomotives (2) (4) (5)</th>
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</thead>
<tbody>
<tr>
<td>F1</td>
<td>RA8 – 75</td>
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<td>F2</td>
<td>RA7 – 75</td>
<td>RA7 – 75</td>
</tr>
<tr>
<td>F3</td>
<td>RA5 – 60</td>
<td>RA7 – 60</td>
</tr>
<tr>
<td>F4</td>
<td>RA4 – 60</td>
<td>RA5 – 60</td>
</tr>
<tr>
<td>F1600</td>
<td>Open point</td>
<td></td>
</tr>
</tbody>
</table>

(1) The indicated speed value in the table represents the maximum requirement for the line and may be lower in accordance with the requirements in point 4.2.1(12). When checking individual structures on the line, it is acceptable to take account of the type of vehicle and local allowed speed.

(2) Passenger Carriages (including Coaches, Vans, Car Carriers), Other Vehicles, Locomotives, Power Heads, Diesel and Electric Multiple Units, Power Units and Railcars are defined in the LOC & PAS TSI. Light Freight Wagons are defined as vans except that they are allowed to be conveyed in formations which are not intended to convey passengers.

(3) The requirements for structures are compatible with Passenger Coaches, Vans, Car Carriers, Light Freight Wagons and vehicles in Diesel and Electric Multiple Units and Power Units with a length of; 18 m to 27.5 m for conventional and articulated vehicles and with a length of 9 m to 14 m for regular single axles.

(4) The requirements for structures are compatible with up to two adjacent coupled locomotives and/or power heads. The requirements for structures are compatible up to a maximum speed of 75 mph for up to five adjacent coupled locomotives and/or power heads (or a train of locomotives and/or power heads) subject to the locomotives and/or power heads satisfying the corresponding limits for freight wagons.

(5) When checking the compatibility of individual trains and structures, the basis of the compatibility check shall be in accordance with Appendix K except where modified by the national technical rules notified for this purpose.

(6) The requirements for structures are compatible with an average mass per unit length over the length of each coach/vehicle of 3,0 t/m.

(7) Only 4 axle vehicles allowed. The spacing of the axles in a bogie shall be at least 2,6 m. The average mass per unit length over the length of the vehicle shall not exceed 4,6 t/m.

(8) 4 or 6 axle vehicles allowed.

(9) Powerhead, only 4 axle vehicles allowed. Also includes locomotives where difference in length between locomotive and hauled vehicles is less than 15 % of length of hauled vehicles for speeds over 90 mph.

(10) For traffic code P5 the Member-State Competent Authority may indicate whether the requirements for locomotives and power heads apply.

(11) Taking into account the state of art of operation there is no need to define harmonized requirements to deliver an adequate level of interoperability for this type of vehicles for P1 and P2 traffic codes.
Appendix G

Speed conversion to miles per hour for Ireland and the United Kingdom of Great Britain and Northern Ireland

Table 42

<table>
<thead>
<tr>
<th>Speed [km/h]</th>
<th>Speed [mph]</th>
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</thead>
<tbody>
<tr>
<td>2</td>
<td>1</td>
</tr>
<tr>
<td>3</td>
<td>1.9364</td>
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<td>20</td>
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<td>18.6559</td>
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<td>40</td>
<td>25.9135</td>
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<tr>
<td>50</td>
<td>33.1711</td>
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<td>60</td>
<td>39.4287</td>
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<td>80</td>
<td>48.5813</td>
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<tr>
<td>100</td>
<td>60</td>
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<tr>
<td>120</td>
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<td>150</td>
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<td>160</td>
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<td>300</td>
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<tr>
<td>------</td>
<td>-----</td>
</tr>
<tr>
<td>350</td>
<td>220</td>
</tr>
</tbody>
</table>
Appendix H

This Appendix has been left intentionally blank

Structure gauge for the 1 520 mm track gauge system

Figure 3

Structure gauge S for the 1 520 mm track gauge system [dimensions in mm]

Clarifications for Figure 3:
- All horizontal dimensions shall be measured from the centre of the track, and all vertical dimensions shall be measured from the top of the rail head level.
- Left side of contour — applications for tracks in the railway station, stop/halt and for branch tracks/industry track (except contour Ia, Ib, IIa, IIIa),
- Right side of contour — applications for tracks on the plain line.

Application of specific parts of the contour:
- 1, I — 1, I — contour of structure gauge for non-electrified tracks,
1. I — II — III — II — 1. I — contour of structure gauge for electrified tracks — for tracks on the plain (open) line and for tracks in the railway station and for branch/industry tracks, where standing of vehicles is not expected,

Ia — Ib — IIa — IIIa — contour of structure gauge for electrified tracks — for other station tracks and other branch/industry tracks

Note: Values of 1 000 mm, 1 020 mm, 6 900 mm and 6 400 mm given in the numerators are for contact system with carrying cable.

Values of 1 100 mm, 1 120 mm, 6 750 mm and 6 250 mm given in the denominator are for contact system without carrying cable,

11 — 10 — 3 — contour of structure gauge for structures and equipment (except tunnel, bridge, platform, ramp) on the outside of ‘edge’ tracks;

9 — 4a — contour of structure gauge for tunnel, for railing on the bridge, elevated track (ballast profile), signals, embankment wall and for railing on the other structures of railway subgrade,

12-12 — contour from which (on track between stations or in stations within usable length of track) any device could not be above (higher), except level crossing covering, locomotive signaling inductors, switches mechanism and their near situated signaling and safety equipment

14-14 — contour of building (or foundation), underground cables, steel cables, pipes and other not railway structures (except signalling and safety equipment)

For nominal track gauge of 1 520 mm a1 = 670 mm and a2 = 760 mm.

For nominal track gauge of 1 524 mm a1 = 672 mm and a2 = 762 mm.

**Figure 4**

Reference profile of the lower parts on tracks fitted with double slip

![Reference profile of the lower parts on tracks fitted with double slip](image)

**Clarification for Figure 4:**
The distance of 760 mm is for track gauge 1 520 mm, and 762 mm for track gauge 1 524 mm.

**Figure 5**
Reference profile of the lower parts on marshalling yards fitted with rail brakes
Appendix I

Reverse curves with radii in the range from 150 m up to 300 m

The values in Table 43 are based on a reference vehicle (basic passenger coach with a distance between bogie pivots \( a = 19 \) m and distance between the buffer face and the bogie pivot \( n_t = 3.7 \) m, buffer width \( \Delta = 635 \) mm and transversal play of the vehicle \( w = +/– 60 \) mm) and an end throw difference of 395 mm for two adjacent basic passenger coaches.

The values in Table 44 are based on a reference vehicle (basic freight wagon with a distance between end axles or bogie pivots 12 m and distance between the buffer face and the end axle or bogie pivot 3 m) and an end throw difference of 225 mm for two adjacent basic freight wagons.

Due to local settings it can be necessary to require a longer length of the intermediate element or special operational conditions or a bigger width of the buffer to prevent buffer locking for existing vehicles that do not fulfil these assumptions.

Table 43

<table>
<thead>
<tr>
<th>R1</th>
<th>15</th>
<th>15</th>
<th>15</th>
<th>15</th>
<th>15</th>
<th>15</th>
<th>15</th>
<th>15</th>
<th>15</th>
<th>15</th>
<th>15</th>
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<tbody>
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<td>3</td>
<td>10</td>
<td>5</td>
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<td>2</td>
<td>9</td>
<td>10</td>
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<td>5</td>
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<td>10,2</td>
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<td>9,6</td>
<td>9,38</td>
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<td>8,94</td>
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<td>8,31</td>
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<td>7,78</td>
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</tr>
</tbody>
</table>

Table 44

Limits, for dedicated freight lines, for the length of a straight intermediate element between two long circular curves in the opposite directions [m]
| 150 | 6.79 | 6.61 | 6.43 | 6.25 | 6.09 | 5.92 | 5.76 | 5.60 | 5.44 | 5.28 | 5.13 |
| 160 | 6.43 | 6.20 | 6.01 | 5.82 | 5.63 | 5.45 | 5.26 | 5.07 | 4.89 | 4.70 | 4.51 |
| 170 | 6.09 | 5.85 | 5.63 | 5.42 | 5.20 | 4.98 | 4.76 | 4.54 | 4.31 | 4.08 | 3.84 |
| 180 | 5.76 | 5.51 | 5.26 | 5.01 | 4.76 | 4.51 | 4.25 | 3.98 | 3.70 | 3.40 | 3.09 |
| 190 | 5.44 | 5.16 | 4.89 | 4.60 | 4.31 | 4.01 | 3.70 | 3.36 | 3.01 | 2.61 | 2.15 |
| 200 | 5.13 | 4.82 | 4.51 | 4.18 | 3.84 | 3.48 | 3.09 | 2.65 | 2.15 | 1.51 | 0.0  |
| 210 | 4.82 | 4.47 | 4.11 | 3.73 | 3.32 | 2.88 | 2.37 | 1.73 | 0.68 | 0.0  | 0.0  |
| 220 | 4.50 | 4.11 | 3.69 | 3.25 | 2.75 | 2.15 | 1.35 | 0.0  | 0.0  | 0.0  | 0.0  |
| 230 | 4.17 | 3.73 | 3.24 | 2.70 | 2.04 | 1.07 | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  |
| 240 | 3.83 | 3.32 | 2.74 | 2.04 | 0.96 | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  |
| 250 | 3.47 | 2.87 | 2.15 | 1.07 | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  |
| 260 | 3.08 | 2.36 | 1.35 | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  |
| 270 | 2.65 | 1.73 | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  |
| 280 | 2.16 | 0.68 | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  |
| 290 | 1.51 | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  |
| 300 | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  | 0.0  |
Appendix J

Safety assurance over fixed obtuse crossings

(J.1) The fixed obtuse crossings should be designed in order not to have a too long unguided length. In obtuse crossing check rails cannot be constructed to assure guidance over the whole length. This unguided length can be accepted up to a certain limit, defined by a reference situation defining:

(a) Minimum crossing angle: tangent 1 in 9 (\(\tan \alpha = 0.11, \alpha = 6^\circ 20'\))
(b) Minimum radius through obtuse crossing: 450 m
(c) Minimum height of check rail: 45 mm
(d) Nose shape as defined in the figure below

Figure 6

Obtuse crossing

Figure 7

Point retraction X on check face
X = 3 mm (over a length of 150 mm).
Y = 8 mm (over a length of 200 to 500 mm approximately)

(J.2) If one or more of the above requirements is not respected, the design shall be checked, verifying either the equivalence of the unguided length or acceptance of the interference between wheel and nose when they get in contact.

(J.3) The design shall be checked for wheels with diameter between 630 mm and 840 mm. For wheel diameters between 330 mm and 630 mm specific demonstrations are required.

(J.4) The following graphs allow simple verification of unguided length for specific situation with different crossing angles, height of check rail and different crossing curvature.

The graphs consider the following maximum track tolerances:
(a) Track gauge between 1 433 mm and 1 439 mm inclusive
(b) Nose protection between 1 393 mm and 1 398 mm inclusive
(c) Free wheel passage ≤ 1 356 mm

Figure 8 allows to specify the minimum wheel diameter that can run on curved obtuse crossings with a radius of 450 m, Figure 9 allows it for straight obtuse crossings.

For other situations specific calculations can be performed.

(J.5) For track gauge systems other than 1 435 mm, specific calculations shall be performed.

*Figure 8*

**Minimum wheel diameter against crossing angle for 450 m radius of obtuse crossing**
1  Minimum wheel diameter [mm]  
2  N for crossing angle tangent 1 in N  
3  Height of check rail [mm] (Z3)  

**Figure 9**  
Minimum wheel diameter against crossing angle for straight obtuse crossing
1 Minimum wheel diameter [mm]
2 N for crossing angle tangent 1 in N
3 Height of check rail [mm] (Z3)
Appendix K

Basis of minimum requirements for structures for passenger coaches and multiple units

The following mass definitions for passenger carriages and multiple units form the basis of the minimum requirements for structures and checking the compatibility of structures with passenger coaches and multiple units.

The EN line categories in Appendix E are based upon the design mass under exceptional payload according to section 2.1 of EN 15663:2009+AC:2010 taking the values for passenger payload in standing areas given in Table 45 into account.

Where checks on the dynamic response of rail bridges are required to specify the load carrying capacity of the bridge, the load capacity of the bridge should be specified and expressed in terms of the design mass under normal payload according to section 2.1 of EN 15663:2009+AC:2010 taking the values for passenger payload in standing areas given in Table 45 into account.

Table 45

<table>
<thead>
<tr>
<th>Type of trains</th>
<th>Normal payload to specify Dynamic Compatibility</th>
<th>Exceptional payload to specify Line Category (Static Compatibility)</th>
</tr>
</thead>
<tbody>
<tr>
<td>High speed and long distance trains</td>
<td>160 (1)</td>
<td>320</td>
</tr>
<tr>
<td>High speed and long distance trains Reservation Obligatory</td>
<td>0</td>
<td>320</td>
</tr>
<tr>
<td>Others (regional, commuter, suburban trains)</td>
<td>280</td>
<td>500 (2)</td>
</tr>
</tbody>
</table>

(1) Normal payload of Table 3 of EN 15663:2009+AC:2010 plus an additional 160 kg/m² for standing areas
(2) For certain types of commuter services (e.g. RATP Paris) the passenger payload in standing areas is 700 kg/m².
Appendix L

Deleted

Appendix M

This Appendix has been left intentionally blank.

Specific case on the Estonian network

(1) Locomotive

(2) Distributed load: 140 kN/m

(3) Wagon
Appendix N

This Appendix has been left intentionally blank.

Specific cases of the Hellenic network

Deleted
Appendix O

**UK** Specific case on **the Ireland and United Kingdom of Northern Ireland networks**

Rules and drawings related to gauges IRL1, IRL2 and IRL3 are an open point.
Structure gauge for the lower parts for the 1,668 mm track gauge on the Spanish network

Structures gauges shall be obtained on the basis of the kinematic reference profiles and associated rules.

Calculations of structure gauge shall be done using the kinematic method in accordance with the requirements of chapters 5, 7 and 10 of EN 15273-3:2013 with the kinematic reference profiles and associated rules defined in this Appendix.

P.1. REFERENCE PROFILES

P.1.1. Kinematic reference profile GEI1

Figure 12 shows the reference profile for kinematic gauge GEI1 for vehicles which can pass over rail brakes in an active position.

Figure 12

Reference profile of lower parts of kinematic gauge GEI1 for vehicles which can pass over rail brakes in an active position (l = track gauge)

(Dimensions in millimeters)

(1) Running surface.

P.1.2. Kinematic reference profile GEI2

Figure 13 shows the reference profile for kinematic gauge GEI2 for vehicles which may pass over rail brakes in a non-active position.

Figure 13
Reference profile of lower parts of kinematic gauge GEI2 for vehicles which may pass over rail brakes in a non-active position (l = track gauge)

(Dimensions in millimeters)

1. Running surface.

P.2. ASSOCIATED RULES

Table 46 shows the additional overthrows for gauges GEI1 and GEI2.

<table>
<thead>
<tr>
<th>Additional overthrows for track gauge 'l' and height 'h' compared to the running surface</th>
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<tr>
<td>Radius</td>
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<tr>
<td>150 ≤ R &lt; 250</td>
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</table>

P.3. VERTICAL LOWERING

The heights of the lower part must be reduced by the value 50/Rv (m), the radius being in metres.

The vertical curve radius Rv is limited to 500 m. Heights not exceeding 80 mm shall be considered as zero within a radius Rv between 500 m and 625 m.
Appendix Q

National technical rules for UK-GB Specific Cases

The National Technical Rules for UK-GB specific cases referred to in point 7.7.17 of this TSINTSN are contained in the documents listed in Table 47. All documents are available on www.rgsonline.co.uk.

**Table 47**

Notified national technical rules for UK-GB Specific Cases

<table>
<thead>
<tr>
<th>Specific Case</th>
<th>NTSNTSI Point</th>
<th>Requirement</th>
<th>NTR Ref</th>
<th>NTR Title</th>
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<tr>
<td>7.7.17.1</td>
<td>4.2.1: Table 2 &amp; Table 3</td>
<td>Categories of line: Gauge</td>
<td>GI/RT7073</td>
<td>Requirements for the Position of Infrastructure and for Defining and Maintaining Clearances</td>
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<td>GE/RT8073</td>
<td>Requirements for the Application of Standard Vehicle Gauges</td>
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<td>GI/RT7020</td>
<td>GB Requirements for Platform Height, Platform Offset and Platform Width</td>
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<tr>
<td>7.7.17.2 &amp; 7.7.17.9</td>
<td>4.2.3.1 &amp; 6.2.4.1</td>
<td>Structure gauge</td>
<td>GI/RT7073</td>
<td>Requirements for the Position of Infrastructure and for Defining and Maintaining Clearances</td>
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<td>Requirements for the Application of Standard Vehicle Gauges</td>
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<td>GI/RT7020</td>
<td>GB Requirements for Platform Height, Platform Offset and Platform Width</td>
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<td>7.7.17.3 &amp; 7.7.17.10</td>
<td>4.2.3.2: Table 4 &amp; 6.2.4.2</td>
<td>Distance between track centres</td>
<td>GI/RT7073</td>
<td>Requirements for the Position of Infrastructure and for Defining and Maintaining Clearances</td>
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<td>7.7.17.4</td>
<td>4.2.5.3 &amp; Appendix J</td>
<td>Maximum unguided length of fixed obtuse crossings</td>
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<td>Track System Requirements</td>
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<td>GM/RT2466</td>
<td>Railway Wheelsets</td>
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<td>4.2.9.2</td>
<td>Platform height</td>
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<td>GB Requirements for Platform Height, Platform Offset and Platform Width</td>
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<td>4.2.9.3 &amp; 6.2.4.11</td>
<td>Platform offset</td>
<td>GI/RT7020</td>
<td>GB Requirements for Platform Height, Platform Offset and Platform Width</td>
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<td>GI/RT7073</td>
<td>Requirements for the Position of Infrastructure and for Defining and Maintaining Clearances</td>
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Appendix R

List of open points

(1) Immediate action limits for isolated defects in alignment for speeds of more than 300 km/h (4.2.8.1).

(2) Immediate action limits for isolated defects in longitudinal level for speeds of more than 300 km/h (4.2.8.2).

(3) The minimum allowed value of distance between track centres for the uniform structure gauge IRL3 is an open point (7.7.18.2).

(4) EN Line Category — Associated Speed [km/h] for Traffic codes P1 (multiple units), P2 (multiple units), P3a (multiple units), P4a (multiple units), P1520 (all vehicles), P1600 (all vehicles), F1520 (all vehicles) and F1600 (all vehicles) in Appendix E, Tables 38 and 39.

(5) Route Availability Number — Associated Speed [miles/h] for Traffic codes P1 (multiple units), P2 (multiple units), P3a (multiple units), P4a (multiple units), P1600 (all vehicles) and F1600 (all vehicles) in Appendix F, Tables 40 and 41.

(6) Rules and drawings related to gauges IRL1, IRL2 and IRL3 are an open point (Appendix O).

(7) The requirements for mitigating the risk for ballast pick up for speed greater than 250 km/h.
### Glossary

#### Table 48

<table>
<thead>
<tr>
<th>Defined term</th>
<th>NTSN/TSI point</th>
<th>Definition</th>
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<tbody>
<tr>
<td>Actual point (RP)</td>
<td>4.2.8.6</td>
<td>Physical end of a crossing vee. See Figure 2, which shows the relationship between the actual point (RP) and the intersection point (IP).</td>
</tr>
<tr>
<td>Alert limit</td>
<td>4.5.2</td>
<td>Refers to the value which, if exceeded, requires that the track geometry condition is analysed and considered in the regularly planned maintenance operations.</td>
</tr>
<tr>
<td>Axle load</td>
<td>4.2.1, 4.2.6.1</td>
<td>Sum of the static vertical wheel forces exerted on the track through a wheelset or a pair of independent wheels divided by acceleration of gravity.</td>
</tr>
<tr>
<td>Braking systems independent of wheel-rail adhesion conditions</td>
<td>4.2.6.2.2</td>
<td>&quot;Braking systems independent of wheel – rail adhesion conditions&quot; refers to all brake systems of the rolling stock capable to develop a brake force applied to the rails independently of the wheel – rail adhesion conditions (e.g. magnetic braking systems and eddy current braking systems.)</td>
</tr>
<tr>
<td>Cant</td>
<td>4.2.4.2</td>
<td>Difference in height, relative to the horizontal, of the two rails of one track at a particular location, measured at the centrelines of the heads of the rails.</td>
</tr>
<tr>
<td>Cant deficiency</td>
<td>4.2.4.3</td>
<td>Difference between the applied cant and a higher equilibrium cant.</td>
</tr>
<tr>
<td>Term</td>
<td>Code</td>
<td>Description</td>
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<tr>
<td>-------------------------------------------</td>
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<td>-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>Common crossing</td>
<td>4.2.8.6</td>
<td>Arrangement ensuring intersection of two opposite running edges of turnouts or diamond crossings and having one crossing vee and two wing rails.</td>
</tr>
<tr>
<td>Crosswind</td>
<td>4.2.10.2</td>
<td>Strong wind blowing laterally to a line which may adversely affect the safety of trains running.</td>
</tr>
<tr>
<td>Design value</td>
<td>4.2.3.4, 4.2.4.2, 4.2.4.5, 4.2.5.1, 4.2.5.3</td>
<td>Theoretical value without manufacturing, construction or maintenance tolerances.</td>
</tr>
<tr>
<td>Design track gauge</td>
<td>5.3.3</td>
<td>A single value which is obtained when all the components of the track conform precisely to their design dimensions or their median design dimension when there is a range.</td>
</tr>
<tr>
<td>Distance between track centres</td>
<td>4.2.3.2</td>
<td>The distance between points of the centre lines of the two tracks under consideration, measured parallel to the running surface of the reference track namely the less canted track.</td>
</tr>
<tr>
<td>Dynamic lateral force</td>
<td>4.2.6.3</td>
<td>The sum of dynamic forces exerted by a wheelset on the track in lateral direction.</td>
</tr>
<tr>
<td>Earthworks</td>
<td>4.2.7.2, 4.2.7.4</td>
<td>Soil structures and soil-retaining structures that are subject to railway traffic loading.</td>
</tr>
<tr>
<td>EN Line Category</td>
<td>4.2.7.4, Appendix E</td>
<td>The result of the classification process set out in EN 15528:2015 Annex A and referred to in that standard as “Line Category”. It represents the ability of the infrastructure to withstand the vertical loads imposed by vehicles</td>
</tr>
<tr>
<td>Metric Description</td>
<td>Reference</td>
<td>Description</td>
</tr>
<tr>
<td>-------------------</td>
<td>-----------</td>
<td>-------------</td>
</tr>
<tr>
<td>Equivalent conicity</td>
<td>4.2.4.5, 4.2.11.2</td>
<td>The tangent of the cone angle of a wheelset with coned wheels whose lateral movement has the same kinematic wavelength as the given wheelset on straight track and large-radius curves.</td>
</tr>
<tr>
<td>Fixed nose protection</td>
<td>4.2.5.3, Appendix J</td>
<td>Dimension between the crossing nose and check rail (see dimension No 2 on Figure 10 below).</td>
</tr>
<tr>
<td>Flangeway depth</td>
<td>4.2.8.6</td>
<td>Dimension between the running surface and the bottom of flangeway (see dimension No 6 on Figure 10 below).</td>
</tr>
<tr>
<td>Flangeway width</td>
<td>4.2.8.6</td>
<td>Dimension between a running rail and an adjacent check or wing rail (see dimension No 5 on Figure 10 below).</td>
</tr>
<tr>
<td>Free wheel passage at check rail/wing rail entry</td>
<td>4.2.8.6</td>
<td>Dimension between the working face of the crossing check rail or wing rail and the gauge face of the running rail opposite across the gauge measured at entry to check rail or wing rail respectively. (see dimensions No 4 on Figure 10 below). The entry to the check rail or wing rail is the point at which the wheel is allowed to contact the check rail or wing rail.</td>
</tr>
<tr>
<td>Free wheel passage at crossing nose</td>
<td>4.2.8.6</td>
<td>Dimension between the working face of the crossing wing rail and check rail opposite across the gauge (see dimension No 3 on Figure 10 below).</td>
</tr>
<tr>
<td>Free wheel passage in switches</td>
<td>4.2.8.6</td>
<td>Dimension from the gauge face of one switch rail to the back edge of</td>
</tr>
<tr>
<td>Term/</td>
<td>Definition/</td>
<td>Reference/</td>
</tr>
<tr>
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</tr>
<tr>
<td>vorrichtung/Côte de libre passage de l'aiguillage</td>
<td>the opposite switch rail (see dimension No 1 on Figure 10 below).</td>
<td>4.2.1, 4.2.3.1</td>
</tr>
<tr>
<td>Gauge/</td>
<td>Begrenzungslinie/</td>
<td>Set of rules including a reference contour and its associated calculation rules allowing definition of the outer dimensions of the vehicle and the space to be cleared by the infrastructure.</td>
</tr>
<tr>
<td>HBW/</td>
<td>HBW/</td>
<td>The non SI unit for steel hardness defined in EN ISO 6506-1:2005 Metallic materials – Brinell hardness test. Test method.</td>
</tr>
<tr>
<td>Height of check rail/</td>
<td>Radlenkerüberhöhung/</td>
<td>Height of the check rail above the running surface (see dimension 7 on Figure 14 below).</td>
</tr>
<tr>
<td>Immediate Action</td>
<td>Limit/</td>
<td>The value which, if exceeded, requires taking measures to reduce the risk of derailment to an acceptable level.</td>
</tr>
<tr>
<td>Infrastructure Manager/</td>
<td></td>
<td>As defined in Article 29 of Directive 2001/14/EC of 26 February 2001 on the allocation of railway infrastructure capacity and the levying of charges for the use of railway infrastructure and safety certification (OJ L 75, 14.3.2001, p. 29). Any body or undertaking that is responsible in particular for establishing and maintaining railway infrastructure. This may also include the management of infrastructure control and safety systems. The functions of the infrastructure manager on a network or part of a network may be allocated to different bodies or undertakings.</td>
</tr>
<tr>
<td>Term</td>
<td>Page References</td>
<td>Description</td>
</tr>
<tr>
<td>-------------------------------------------</td>
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<td>--------------------------------------------------------------------------------------------------------------------------------------------</td>
</tr>
<tr>
<td>In service value/</td>
<td>4.2.8.5, 4.2.11.2</td>
<td>Value measured at any time after the infrastructure has been placed into service.</td>
</tr>
<tr>
<td>Intersection point (IP)/</td>
<td>4.2.8.6</td>
<td>Theoretical intersection point of the running edges at the centre of the crossing (see figure 2).</td>
</tr>
<tr>
<td>Intervention Limit/</td>
<td>4.5.2</td>
<td>The value, which, if exceeded, requires corrective maintenance in order that the immediate action limit shall not be reached before the next inspection;</td>
</tr>
<tr>
<td>Isolated defect</td>
<td>4.2.8</td>
<td>A discrete track geometry fault.</td>
</tr>
<tr>
<td>Line speed</td>
<td>4.2.1</td>
<td>Maximum speed for which a line has been designed.</td>
</tr>
<tr>
<td>Maintenance file/</td>
<td>4.5.1</td>
<td>Elements of the technical file relating to conditions and limits of use and instructions for maintenance.</td>
</tr>
<tr>
<td>Maintenance plan/</td>
<td>4.5.2</td>
<td>A series of documents setting out the infrastructure maintenance procedures adopted by an Infrastructure Manager.</td>
</tr>
<tr>
<td>Multi-rail track</td>
<td>4.2.2.2</td>
<td>Track with more than two rails, where at least two pairs of respective rails are designed to be operated as separate single tracks, with or without different track gauges.</td>
</tr>
<tr>
<td>Nominal track gauge/</td>
<td>4.2.4.1</td>
<td>A single value which identifies the track gauge but may differ from the design track gauge.</td>
</tr>
<tr>
<td>Normal service</td>
<td>4.2.2.2</td>
<td>The railway operating to a planned timetable service.</td>
</tr>
<tr>
<td>Term</td>
<td>Page</td>
<td>Definition</td>
</tr>
<tr>
<td>-----------------------------</td>
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<td>-----------------------------------------------------------------------------</td>
</tr>
<tr>
<td>Passive provision</td>
<td>4.2.9</td>
<td>Provision for the future construction of a physical extension to a structure (for example: increased platform length).</td>
</tr>
<tr>
<td>Performance Parameter</td>
<td>4.2.1</td>
<td>Parameter describing the NTSNa TSI Category of Line used as the basis for the design of infrastructure subsystem elements and as the indication of the performance level of a line.</td>
</tr>
<tr>
<td>Plain line</td>
<td>4.2.45</td>
<td>Section of track without switches and crossings.</td>
</tr>
<tr>
<td>Point retraction</td>
<td>4.2.8.6</td>
<td>The reference line in a fixed common crossing can deviate from the theoretical reference line. From a certain distance to the crossing point, the reference line of the vee can, depending on the design, be retracted from this theoretical line away from the wheel flange in order to avoid contact between both elements. This situation is described in Figure 2.</td>
</tr>
<tr>
<td>Rail inclination</td>
<td>4.2.4.5</td>
<td>An angle defining the inclination of the head of a rail when installed in the track relative to the plane of the rails (running surface), equal to the angle between the axis of symmetry of the rail (or of an equivalent symmetrical rail having the same rail head profile) and the perpendicular to the plane of the rails.</td>
</tr>
<tr>
<td>Term</td>
<td>Section</td>
<td>Description</td>
</tr>
<tr>
<td>------</td>
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</tr>
<tr>
<td>Rail pad</td>
<td>3.2</td>
<td>A resilient layer fitted between a rail and the supporting sleeper or baseplate.</td>
</tr>
<tr>
<td>Reverse curve</td>
<td>4.2.5.4</td>
<td>Two abutting curves of opposite flexure or hand</td>
</tr>
<tr>
<td>Structure gauge</td>
<td>4.2.3.1</td>
<td>Defines the space in relation to the reference track that shall be cleared of all objects or structures and of the traffic on the adjacent tracks, in order to allow safe operation on the reference track. It is defined on the basis of the reference contour by application of the associated rules.</td>
</tr>
<tr>
<td>Swing nose</td>
<td>4.2.5.2</td>
<td>Within the domain of “common crossing with movable point”, the term “swing nose” identifies the part of the crossing which forms the vee and that it is moved to form a continuous running edge for either the main or the branch line.</td>
</tr>
<tr>
<td>Switch</td>
<td>4.2.8.6</td>
<td>A unit of track comprising two fixed rails (stock rails) and two movable rails (switch rails) used to direct vehicles from one track to another track.</td>
</tr>
<tr>
<td>Switches and crossings</td>
<td>4.2.4.5, 4.2.4.7, 4.2.5, 4.2.6, 4.2.8.6, 5.2, 6.2.4.4, 6.2.4.8, 6.2.5.2, 7.3.3, Appendix C and D</td>
<td>Track constructed from sets of switches and individual crossings and the rails connecting them.</td>
</tr>
<tr>
<td>Through route</td>
<td>Appendix D</td>
<td>In the context of switches and crossings a route which perpetuate the general alignment of the track.</td>
</tr>
<tr>
<td><strong>Track design</strong></td>
<td>4.2.6, 6.2.5, Appendix C and D</td>
<td>The track design consists of cross-section defining basic dimensions and track components (for example rail, rail fastenings, sleepers, ballast) used together with operating conditions with an impact on forces related to 4.2.6, such as axle load, speed and radius of horizontal curvature.</td>
</tr>
<tr>
<td><strong>Track gauge</strong>&lt;sup&gt;4.2.4.1, 4.2.4.5, 4.2.8.4, 5.3.3, 6.1.5.2, 6.2.4.3, Appendix H&lt;/sup&gt;</td>
<td>The smallest distance between lines perpendicular to the running surface intersecting each rail head profile in a range from 0 to 14 mm below the running surface.</td>
<td></td>
</tr>
<tr>
<td><strong>Track twist</strong>&lt;sup&gt;4.2.7.1.6 4.2.8.3, 6.2.4.9,&lt;/sup&gt;</td>
<td>Track twist is defined as the algebraic difference between two cross levels taken at a defined distance apart, usually expressed as a gradient between the two points at which the cross level is measured.</td>
<td></td>
</tr>
<tr>
<td><strong>Train length</strong>&lt;sup&gt;4.2.1&lt;/sup&gt;</td>
<td>The length of a train, which can run on a certain line in normal operation.</td>
<td></td>
</tr>
<tr>
<td><strong>Unguided length of an obtuse crossing</strong>&lt;sup&gt;4.2.5.3, Appendix J&lt;/sup&gt;</td>
<td>Portion of obtuse crossing where there is no guidance of the wheel described as &quot;unguided distance&quot; in EN 13232-3:2003.</td>
<td></td>
</tr>
<tr>
<td><strong>Usable length of a platform</strong>&lt;sup&gt;4.2.1, 4.2.9.1&lt;/sup&gt;</td>
<td>The maximum continuous length of that part of platform in front of which a train is intended to remain stationary in normal operating conditions for passengers to board and alight from the train, making appropriate allowance for stopping tolerances.</td>
<td></td>
</tr>
</tbody>
</table>
Normal operating conditions means that railway is operating in a non-degraded mode (e.g. rail adhesion is normal, signals are working, everything is working as planned).”

**Figure 14**

Geometry of switches and crossings

1. Free wheel passage in switches
2. Fixed nose protection
(3) Free wheel passage at crossing nose
(4) Free wheel passage at check rail/wing rail entry
(5) Flangeway width
(6) Flangeway depth
(7) Height of check rail
## Appendix T

### List of referenced standards

**Table 49**

### List of referenced standards

<table>
<thead>
<tr>
<th>Index No.</th>
<th>Reference</th>
<th>Document name</th>
<th>Version (year)</th>
<th>BP(s) concerned</th>
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<tr>
<td>1</td>
<td>EN 13674-1</td>
<td>Railway applications — Track — Rail Part 1: Vignole railway rails 46 kg/m and above</td>
<td>2011</td>
<td>Railhead profile for plain line (4.2.4.6), Assessment of rails (6.1.5.1)</td>
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<tr>
<td>2</td>
<td>EN 13674-4</td>
<td>Railway applications — Track — Rail — Part 4: Vignole railway rails from 27 kg/m to, but excluding 46 kg/m (with Amendment A1:2009)</td>
<td>2006</td>
<td>Railhead profile for plain line (4.2.4.6)</td>
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<tr>
<td>3</td>
<td>EN 13715</td>
<td>Railway applications — Wheelsets and boogies — Wheels — Wheels tread (with Amendment A1:2010)</td>
<td>2006 A1:2010</td>
<td>Equivalent conicity (4.2.4.5)</td>
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<tr>
<td>5</td>
<td>EN 13848-5</td>
<td>Railway applications — Track — Track geometry quality — Part 5: Geometric quality levels — Plain line (with Amendment A1:2010)</td>
<td>2008</td>
<td>The immediate action limit for alignment (4.2.8.1), The immediate action limit for longitudinal level (4.2.8.2), The immediate action limit for track twist (4.2.8.3)</td>
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<tr>
<td>6</td>
<td>EN 14067-5</td>
<td>Railway applications — Aerodynamics — Part 5: Requirements and test procedures for aerodynamics in tunnels (with Amendment A1:2010)</td>
<td>2006</td>
<td>Assessment of maximum pressure variations in tunnels (6.2.4.12)</td>
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<tr>
<td>7</td>
<td>EN 15273-3</td>
<td>Railway applications — Gauges — Part 3: Structure gauges</td>
<td>2013</td>
<td>Structure gauge (4.2.3.1), Distance between track centres (4.2.3.2), Platform offset (4.2.9.3), Assessment of</td>
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<tr>
<td>No.</td>
<td>Standard Code</td>
<td>Standard Title</td>
<td>Year</td>
<td>Descriptions</td>
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<td>8</td>
<td>EN 15302</td>
<td>Railway applications — Method for specifying the equivalent conicity (with Amendment A1:2010)</td>
<td>2008</td>
<td>Equivalent conicity (4.2.4.5), Assessment of design values for equivalent conicity (6.2.4.6)</td>
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<tr>
<td>9</td>
<td>EN 15528</td>
<td>Railway applications — Line categories for managing the interface between load limits of vehicles and infrastructure</td>
<td>2015</td>
<td>Capability requirements for structures according to traffic code (Appendix E)</td>
</tr>
<tr>
<td>10</td>
<td>EN 15663</td>
<td>Railway applications — Definition of vehicle reference masses (with Corrections AC:2010)</td>
<td>2009</td>
<td>TSI-NTSN categories of line (4.2.1), Basis of minimum requirements for structures for passenger coaches and multiple units (Appendix K)</td>
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<td>11</td>
<td>EN 1990</td>
<td>Eurocode — Basis of structural design (with Amendment A1:2005 and Correction AC:2010)</td>
<td>2002</td>
<td>Structures resistance to traffic loads (4.2.7), Resistance of new bridges to traffic loads (4.2.7.1)</td>
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<td>12</td>
<td>EN 1991-2</td>
<td>Eurocode 1 — Actions on structures — Part 2: Traffic load on bridges (with Correction AC:2010)</td>
<td>2003</td>
<td>Structures resistance to traffic loads (4.2.7), Resistance of new bridges to traffic loads (4.2.7.1), Equivalent vertical loading for new earthworks and earth pressure effects (4.2.7.2), Resistance of new structures over or adjacent to tracks (4.2.7.3)</td>
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<td>13</td>
<td>EN 14363:2005</td>
<td>Railway applications — Testing for the acceptance of running characteristics of railway vehicles — Testing of running behaviour and stationary tests</td>
<td>2005</td>
<td>Track resistance to vertical load (4.2.6.1), Lateral track resistance (4.2.6.3),</td>
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